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Coronal Loop Seismology - Basics

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Coronal Loop Seismology – Basics

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Outline





Simple model of coronal loop
The concept of coronal seismology
MHD waves
Observations of coronal loops oscillations as an input for coronal seismology:
Magnetic field from kink oscillations
Magnetic field from slow waves

2D curved loop model

 $V_{A}^{2} = -$



Variables: ρ, p, V, B EOS: T(p) -> ρ, c_s(T), V, V_A

Numerical model
 Boundary conditions
 Initial conditions

$$\begin{array}{c}
0.4 \\
0.3 \\
\hline
0.2 \\
\hline
0.2 \\
\hline
0.2 \\
\hline
0.1 \\
0.0 \\
\hline
0.$$

$$(\nabla \times \mathbf{B}) \times \mathbf{B} = 0$$

$$\nabla \times \mathbf{B} = 0$$

$$A = B\Lambda_B \cos(x/\Lambda_B) \exp(-z/\Lambda_B)$$

$$\mathbf{B} = [B\cos(x/\Lambda_B), -B\sin(x/\Lambda_B),]\exp(-z/\Lambda_B)$$

$$\Lambda_B = \frac{2L}{\pi}$$

$$\rho(z) = \rho_0$$



2D curved loop model



Variables: ρ, **p**, **V**, **B** EOS: T(**p**) -> ρ, c_s(T), V, V_A

Equilibrium: **√V**=0 ✓T - peak temperature TRACE: 171 Fe IX/X 1MK 195 Fe XII 1.5MK 284 Fe XV 2MK SUMER(SOHO) Fe XIX 6.3 MK Fe XX 8MK *p* - observed brightness + theory of Thomson scattering + scale height - spectroscopy $\checkmark \mathbf{B} - \mathbf{?} \rightarrow \beta \text{ regime } \rho \left(\frac{\partial \mathbf{V}}{\partial t} + \mathbf{V} \cdot \nabla \mathbf{V} \right) = \nabla p + \frac{1}{\mu} (\nabla \times \mathbf{B}) \times \mathbf{B} ; \beta = \frac{p}{B^2 / 2\mu} = \frac{2}{\gamma} \frac{c_s^2}{V_A^2}$

Magnetic field measurements

Magnetogram - refers to a pictorial representation of the spatial variations in strength of the solar magnetic field. Magnetograms are often produced by exploiting the Zeeman effect (1896).





Magnetic field measurements

Photospheric
magnetogram
Potential extrapolation
NLFF model
Potential field source
surface (PFSS)









Zeeman effect









(Coronal) Seismology



Seismology is the scientific study of earthquakes and the propagation of elastic waves through the Earth or through other planet-like bodies. The field also includes studies of earthquake effects, such as tsunamis as well as diverse seismic sources such as volcanic, tectonic, oceanic, atmospheric, and artificial processes (such as explosions).

> The study of waves with the aim to get the information about the local medium of propagation (remote diagnosis).

Coronal seismology is a technique of studying the plasma of the Sun's corona with the use of magnetohydrodynamic (MHD) waves and oscillations.

The study of coronal waves, in order to measure physical quantities in the solar corona.
Source: Wikipedia

Why Coronal Seismology?



- To understand wave processes in plasma environments.
- To measure physical properties in the solar corona, that are difficult to measure otherwise. Often localized in space, so natural fine spatial resolution.
- To test physical models for coronal structures.

Works well for the description of a number of plasma structures:

- that can be described by a straight cylinder (structures non-uniform in the transverse direction and extending along the magnetic field, that can act as a waveguide) and
- that are observed in solar corona (e.g. coronal loops).

Coronal Seismology





History of Coronal Seismology?



- Uchida (1970) "on the basis of the density distribution in the corona, this seismological diagnosis reveals the distribution of magnetic field"
- Roberts et al. (1984) "magnetoacoustic oscillations provide a potentially useful diagnostic tool for determining physical conditions in the inhomogeneous corona"







Coronal loops form the basic structure of the lower corona and transition region of the Sun. These highly structured and elegant loops are a direct consequence of the twisted solar magnetic flux within the solar body.

Theory of MHD waves



Edwin & Roberts (1983); Roberts et al. (1984)







Horizontal mode



Van Doorsselaere et al. (2004) -> curvature does not select a preferential oscillation direction

Vertical mode



Wang & Solanki (2004)

Theory of MHD waves



Roberts, Edwin, & Benz (1984)

TABLE III Pulse periods of MHD waves

Standing MHD waves

Slow modes	$T_0 = 2 \times 10^6 \mathrm{K}$	τ _s ≈ 850 s
$t = \frac{2L}{2L} = \frac{1.2 \times 10^{-4} L (1 + (c_0)^2)^{1/2}}{12}$	$L = 10^{10} \mathrm{cm}$	10304
$c_s = \frac{1}{kc_T} = \frac{1}{jT_0^{1/2}} \left(1 + \left(\frac{1}{v_A} \right) \right)$	$j=1, c_0 \leqslant v_{A}$	
Fast kink mode	$N_0 = 10^9 \text{ cm}^{-3}$	$\tau_s \approx 50 \text{ s}$
$T = \frac{2L}{2} = \frac{4\pi^{1/2}L}{2} \left(\rho_0 + \rho_e \right)^{1/2}$	$L = 10^{10} \mathrm{cm}$	
$\frac{c_j}{kc_k} = \frac{1}{j} \left(\frac{B_0^2 + B_e^2}{B_0^2 + B_e^2} \right)$	$B_0 = 40 \; \mathrm{G}, \rho_0 \gg \rho_e$	
Fast sausage mode	$N_0 = 10^9$ cm ⁻³	$\tau_s\approx 1.5~s$
$r = \frac{2\pi a}{2\pi a} = 4\pi^{3/2} a \left(\rho_0 + \rho_e \right)^{1/2}$	$a/L = 10^{-2}$	
$\frac{c_{p}}{c_{k}} = \frac{4\pi}{c_{k}} - \frac{4\pi}{a} \left(\frac{B_{0}^{2} + B_{e}^{2}}{B_{0}^{2} + B_{e}^{2}} \right)$	$B_0=40~{\rm G},\rho_0 \gg \rho_e$	I
Propagating MHD waves		
$T = \frac{2\pi a}{(1 - \rho_e)^{1/2}} \approx 2.6 \left(\frac{a}{a}\right)$	$a = 2 \times 10^8 \text{ cm}, s = 1$	$\tau_c\approx 2~s$
$v_e = \frac{1}{j_{0,e}v_A} \left(1 - \frac{1}{\rho_0}\right) \approx 2.0 \left(\frac{1}{v_A}\right)$	$N_0 = 10^9 \text{ cm}^{-3}$	
	$B_0=40~{\rm G},\beta \ll 1$	

Theory of MHD waves



Breakthrough (SOHO & TRACE)



- Kink oscillations of coronal loops (Aschwanden et al. 1999, 2002; Nakariakov et al. 1999; Verwichte et al. 2004)
- Propagating longitudinal waves in polar plumes and near loop footpoints (Ofman et al. 1997-1999; DeForest & Gurman, 1998; Berghmans & Clette, 1999; Nakariakov et al. 2000; De Moortel et al. 2000-2004)
- 3. Standing longitudinal waves in coronal loops (Kliem at al. 2002; Wang & Ofman 2002)
- 4. Global sausage mode (Nakariakov et al. 2003)
- Propagating fast wave trains. (Williams et al. 2001, 2002; Cooper et al. 2003; Katsiyannis et al. 2003; Nakariakov et al. 2004, Verwichte et al. 2005)

Already identified coronal MHD modes:







Kink oscillations

- Periods: 1s 1h
- ✓ Generation: granules or flares
- Quasiperiodicty
- Fast generation of standing waves and strong damping





Scheme of the method



Nakariakov, Ofman (2001)

Details:

- 1. Distance between footpoints -> semi-circular loop length $L=\pi R$
- 2. Observed period and length -> phase speed V_{ph}=2L/P
- 3. Phase speed=kink speed -> V_{ph}=c_k
- 4. Kink speed -> Alfvén speed $c_k = V_A \sqrt{\frac{2}{1 + \rho_a / \rho_i}}$
- 5. Alfvén speed and density -> magnetic field $B = V_A \sqrt{4\pi\rho_i} = \frac{\sqrt{2\pi^{3/2}L}}{P} \sqrt{\rho_i (1 + \rho_e / \rho_i)}$ For $\rho = 1 \times 10^9 \text{ cm}^{-3}$ to $\rho = 6 \times 10^9 \text{ cm}^{-3}$ ->B=4-30G
- 6. From detailed emission measure studies $\rho = 10^{9.2\pm0.3} \text{ cm}^{-3}$ to $\rho = 6 \times 10^{9.3\pm0.3} \text{ cm}^{-3}$ -
- -> B=13±9G





 $V_{A}^{2} = -$



Error analysis:

- 1. Errors in determination of loop length (due to projection and different than circular shape, e.g. elliptic -> 15%).
- 2. The error in the determination of the oscillation period (sensitive to the condition of the specific observation, here 3% as many periods were observed).
- 3. The accuracy of determination of the densities depends upon the specific method applied and is about 50% (e.g. Mason et al. 1999 and references therein). The determination of the density ratio possibly has even larger error, but as the ratio is assumed to be small, one can neglect its value.
- 4. The relative error of the method can be estimated as

 $\delta B = \sqrt{(\delta L)^2 + (\delta P)^2 + (\delta \rho_i / 2)^2}$

For δL=10%, δP=3%, δq=50% -> δB=30%

Nakariakov, Ofman (2001)







Case on 2000 September 29

Wang et al. (2003)

Selwa, Murawski, Solanki (2005)

Method:

- 1. Distance between footpoints -> elliptical loop length L
- 2. Observed period and length -> tube speed $c_t=2L/P$, $c_t=V_A\sqrt{\frac{1}{c_s^2+V_s^2}}$
- 3. Slow speed (measured T) and Alfvén speed -> plasma β

$$c_s^2 = \frac{\gamma p}{\rho} = \sqrt{\gamma k_B T / \mu m_p} \quad ; \quad V_A^2 = \frac{B^2}{4\pi\rho_i} \quad \to \quad \beta = \frac{2}{\gamma} \frac{c}{V}$$

4. Thus magnetic field can be estimated as

$$B = \left(\frac{n_9}{C_1}\right)^{1/2} \left(\frac{P^2}{4L^2} - \frac{1}{C_2 T_6}\right)^{-1/2}$$

For $C_1 = 4.8 \times 10^3$, $C_2 = 2.3 \times 10^4$, B[G], n₉[10⁹cm⁻³], P[s], L[km], T[10⁶K]

excluding 1 loop 0.15-0.33 (mean 0.24±0.08),

B: 21-61 G (mean 34±14G)

Wang et al. (2007)

Error analysis:

- 1. Errors in determination of electron density (less significant as f_n is the constant number)
- 2. Errors in determination of temperature
- 3. Errors in determination of the loop length
- 4. Errors in determination of the oscillation period
- 5. The relative error of the method can be estimated as $\partial B = \sqrt{f_n^2 (\partial n)^2 + f_T^2 (\partial T)^2 + f_L^2 (\partial L)^2 + f_P^2 (\partial P)^2}$ For $\delta n = \delta L = \delta T = 5\%$ $\rightarrow \delta B = 40\% \text{ with } f_T \sim 2.4 \text{ and } f_L = f_P \sim 5.9$ $f_n = \frac{\partial B}{\partial n} / \frac{B}{n} = \frac{1}{2},$ $f_T = \frac{\partial B}{\partial T} / \frac{B}{T} = \left(\frac{C_2 P^2 T_6}{2L^2} - 2\right)^{-1} = \frac{1}{\gamma\beta},$ $f_L = \frac{\partial B}{\partial L} / \frac{B}{L} = \left(1 - \frac{4L^2}{C_2 T_6 P^2}\right)^{-1} = 1 + \frac{2}{\gamma\beta},$ $f_P = \frac{\partial B}{\partial P} / \frac{B}{P} = f_L = 1 + 2f_T.$





Average and ranges of physical parameters of 26 oscillating loops^a.

Parameter	Average	Range
Loop half length L	110 ± 53 Mm	37-291 Mm
Loop width w	8.7 ± 2.8 Mm	5.5-16.8 Mm
Oscillation period P	321 ± 140 s	137-694 s ^b
	$5.4 \pm 2.3 \text{ min}$	2.3-10.8 min ^b
Decay time t_d	$580 \pm 385 \text{ s}$	191-1246 s ^c
	9.7 ± 6.4 min	3.2-20.8 min ^c
Oscillation duration d	$1392 \pm 1080 \text{ s}$	400-5388 s
	$23 \pm 18 \min$	6.7-90 min
Oscillation amplitude A	$2200 \pm 2800 \text{ km}$	100-8800 km
Number of periods	4.0 ± 1.8	1.3-8.7
Electron density of loop nloop	$(6.0 \pm 3.3)10^8 \text{ cm}^{-3}$	$(1.3-17.1) \times 10^8 \text{ cm}^{-3}$
Maximum transverse speed vmax	$42 \pm 53 \text{ km s}^{-1}$	3.6-229 km s ⁻¹
Loop Alfvén speed vA	$2900 \pm 800 \text{ km s}^{-1}$	1600-5600 km s ⁻¹
Mach factor vmax/vsound	0.28 ± 0.35	0.02-1.53
Alfvén transit time tA	150 ± 64 s	60-311 s
Duration/Alfvénic transit d/tA	9.8 ± 5.7	1.5-26.0
Decay/Alfvénic transit td/tA	4.1 ± 2.3	1.7-9.6 ^c
Period/Alfvénic transit P/tA	2.4 ± 1.2	0.9-5.4 ^b

^a All Alfvénic speeds and times are calculated for a magnetic field of B = 30 G, so scaling to other magnetic field values are $v_A(B) = v_A(B/30 \text{ G})$ and $t_A(B) = t_A(B/30 \text{ G})^{-1}$.

^b The most extreme period of P = 2004 s (case 9a) is excluded in the statistics.

^c Only the 10 most reliable decay times t_d (with no parentheses in Table II) are included in the statistics.

Conclusions





Coronal seismology;
Observe and model coronal waves
Measure physical parameters

 Magnetic field measure in photoshpere (Zeeman effect)

 Magnetic field determined from kink and slow loop oscillations