

# Renormalization for Lorenz maps

Denis Gaidashev, Matematiska Institutionen, Uppsala Universitet

Tieste, June 5, 2012

## Lorenz dynamics

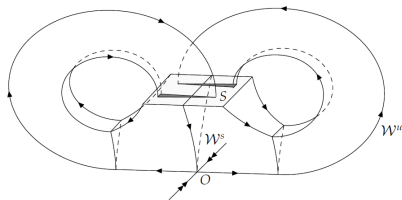
**The geometric Lorenz flow** ( R. F. Williams, 79): a model capturing the qualitative behaviour of the Lorenz flow with extra conditions. Specifically, the return map

- map preserves a one-dimensional foliation in a section transversal to the flow;
- contracts distances between points in the leafs of this foliation at a geometric rate.

## Lorenz dynamics

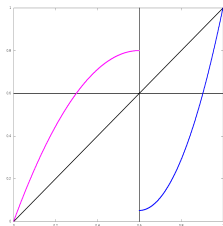
**The geometric Lorenz flow** ( R. F. Williams, 79): a model capturing the qualitative behaviour of the Lorenz flow with extra conditions. Specifically, the return map

- map preserves a one-dimensional foliation in a section transversal to the flow;
- contracts distances between points in the leaves of this foliation at a geometric rate.

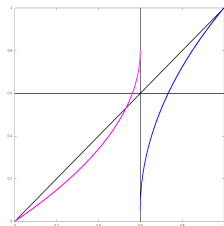


- Lorenz dynamics is asymptotically one-dimensional, and can be understood in terms of a map acting on the space of leaves (an interval): **the Lorenz map**.

- Lorenz dynamics is asymptotically one-dimensional, and can be understood in terms of a map acting on the space of leaves (an interval): **the Lorenz map**.

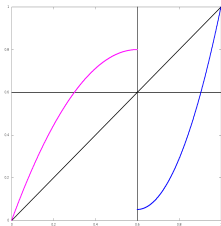


$$|f(x) - c| \approx A|x - c|^2$$

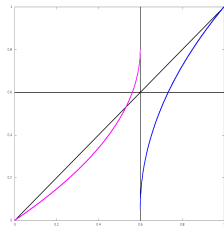


$$|f(x) - c| \approx B|x - c|^{\frac{1}{2}}$$

- Lorenz dynamics is asymptotically one-dimensional, and can be understood in terms of a map acting on the space of leaves (an interval): **the Lorenz map**.



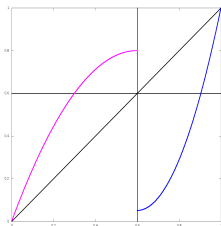
$$|f(x) - c| \approx A|x - c|^2$$



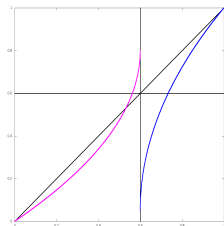
$$|f(x) - c| \approx B|x - c|^{\frac{1}{2}}$$

- There is an open set of vector fields in  $\mathbb{R}^3$ , that generate a geometric Lorenz flow with a “smooth” Lorenz map of  $\rho < 1$  (J. Guckenheimer and R. F. Williams, '79). “Similarly”, for  $\rho \geq 1$ .

- Lorenz dynamics is asymptotically one-dimensional, and can be understood in terms of a map acting on the space of leaves (an interval): **the Lorenz map**.



$$|f(x) - c| \approx A|x - c|^2$$



$$|f(x) - c| \approx B|x - c|^{\frac{1}{2}}$$

- There is an open set of vector fields in  $\mathbb{R}^3$ , that generate a geometric Lorenz flow with a “smooth” Lorenz map of  $\rho < 1$  (J. Guckenheimer and R. F. Williams, '79). “Similarly”, for  $\rho \geq 1$ .
- **As with the unimodal maps, Lorenz maps with  $\rho > 1$  have a richer dynamics that combines contraction with expansion.**

Let  $u \in [0, 1]$ ,  $v \in [0, 1]$ ,  $c \in (0, 1)$  and  $\rho > 0$ . *The standard Lorenz family*  $(u, v, c) \mapsto Q(x)$  is the family of maps  $Q : [0, 1] \setminus \{c\} \mapsto [0, 1]$  with a single critical point at which the map is discontinuous:

$$Q(x) = \begin{cases} u \left(1 - \left(\frac{c-x}{c}\right)^\rho\right), & x \in [0, c), \\ 1 + v \left(-1 + \left(\frac{x-c}{1-c}\right)^\rho\right), & x \in (c, 1], \end{cases}$$



Let  $u \in [0, 1]$ ,  $v \in [0, 1]$ ,  $c \in (0, 1)$  and  $\rho > 0$ . *The standard Lorenz family*  $(u, v, c) \mapsto Q(x)$  is the family of maps  $Q : [0, 1] \setminus \{c\} \mapsto [0, 1]$  with a single critical point at which the map is discontinuous:

$$Q(x) = \begin{cases} u \left(1 - \left(\frac{c-x}{c}\right)^\rho\right), & x \in [0, c), \\ 1 + v \left(-1 + \left(\frac{x-c}{1-c}\right)^\rho\right), & x \in (c, 1], \end{cases}$$

Above,  $u = |Q([0, c))|$ ,  $v = |Q((c, 1])|$ , while  $u$  and  $1 - v$  are the critical values.

Let  $u \in [0, 1]$ ,  $v \in [0, 1]$ ,  $c \in (0, 1)$  and  $\rho > 0$ . *The standard Lorenz family*  $(u, v, c) \mapsto Q(x)$  is the family of maps  $Q : [0, 1] \setminus \{c\} \mapsto [0, 1]$  with a single critical point at which the map is discontinuous:

$$Q(x) = \begin{cases} u \left(1 - \left(\frac{c-x}{c}\right)^\rho\right), & x \in [0, c), \\ 1 + v \left(-1 + \left(\frac{x-c}{1-c}\right)^\rho\right), & x \in (c, 1], \end{cases}$$

Above,  $u = |Q([0, c))|$ ,  $v = |Q((c, 1])|$ , while  $u$  and  $1 - v$  are the critical values.

More generally,

A  *$C^k$ -Lorenz map*  $f : [0, 1] \setminus \{c\} \mapsto [0, 1]$  is defined as

$$f(x) = \begin{cases} f_0(x) \equiv \phi(Q(x)), & x \in [0, c), \\ f_1(x) \equiv \psi(Q(x)), & x \in (c, 1], \end{cases}$$

where  $\phi$  and  $\psi$  are  $C^k$  orientation preserving diffeomorphisms of  $[0, 1]$  (this space will be denoted by  $\mathcal{D}^k$ ).

The set of  $C^k$ -Lorenz maps will be denoted  $\mathcal{L}^k$

## Kneading sequences

- For any  $x \in [0, 1] \setminus \{c\}$  such that  $f^n(x) \neq c$  for all  $n \in \mathbb{N}$ , define the itinerary  $\omega(x) \in \{0, 1\}^{\mathbb{N}}$  of  $x$  as the sequence  $\{\omega^0(x), \omega^1(x), \dots\}$ , such that

$$\omega^i = \begin{cases} 0, & f^i(x) < c, \\ 1, & f^i(x) > c. \end{cases}$$

## Kneading sequences

- For any  $x \in [0, 1] \setminus \{c\}$  such that  $f^n(x) \neq c$  for all  $n \in \mathbb{N}$ , define the itinerary  $\omega(x) \in \{0, 1\}^{\mathbb{N}}$  of  $x$  as the sequence  $\{\omega^0(x), \omega^1(x), \dots\}$ , such that

$$\omega^i = \begin{cases} 0, & f^i(x) < c, \\ 1, & f^i(x) > c. \end{cases}$$

- $\omega(x^+) \equiv \lim_{y \downarrow x} \omega(y)$ ,  $\omega(x^-) \equiv \lim_{y \uparrow x} \omega(y)$  exists for all  $x \in [0, 1]$ .

## Kneading sequences

- For any  $x \in [0, 1] \setminus \{c\}$  such that  $f^n(x) \neq c$  for all  $n \in \mathbb{N}$ , define the itinerary  $\omega(x) \in \{0, 1\}^{\mathbb{N}}$  of  $x$  as the sequence  $\{\omega^0(x), \omega^1(x), \dots\}$ , such that

$$\omega^i = \begin{cases} 0, & f^i(x) < c, \\ 1, & f^i(x) > c. \end{cases}$$

- $\omega(x^+) \equiv \lim_{y \downarrow x} \omega(y)$ ,  $\omega(x^-) \equiv \lim_{y \uparrow x} \omega(y)$  exists for all  $x \in [0, 1]$ .
- The kneading invariant  $K(f)$  of  $f$  is the pair  $(K^-(f), K^+(f)) = (\omega(c^-), \omega(c^+))$ .

- Are there situations when the **limiting dynamics** of a Lorenz map is more understandable?

- Are there situations when the **limiting dynamics** of a Lorenz map is more understandable?
  
  
  
  
  
  
  
  
  
  
- Can it happen that the limiting dynamics concentrates on a subset of the domain, i.e. is there an **attractor for dynamics**?

## Renormalization

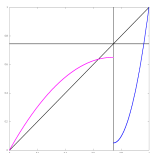
A Lorenz map  $f$  is *renormalizable* if there exist  $p$  and  $q$ ,  $0 < p < c < q < 1$ , s. t. the first return map  $(f^n, f^m)$ ,  $n > 1, m > 1$ , of  $C = [p, q]$  is affinely conjugate to a nontrivial Lorenz map. Choose  $C$  such that it is maximal. The rescaled first return map of such  $C \setminus \{c\}$  is called the *renormalization of  $f$*  and denoted  $\mathcal{R}[f]$ .



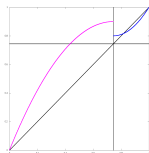
## Renormalization

A Lorenz map  $f$  is **renormalizable** if there exist  $p$  and  $q$ ,  $0 < p < c < q < 1$ , s. t. the first return map  $(f^n, f^m)$ ,  $n > 1, m > 1$ , of  $C = [p, q]$  is affinely conjugate to a nontrivial Lorenz map. Choose  $C$  such that it is maximal. The rescaled first return map of such  $C \setminus \{c\}$  is called the **renormalization of  $f$**  and denoted  $\mathcal{R}[f]$ .

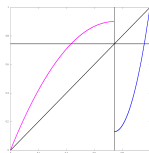
- A Lorenz map  $f$  with  $c_1^+ < c < c_1^-$  is called **nontrivial**, otherwise  $f$  has a globally attracting fixed point.



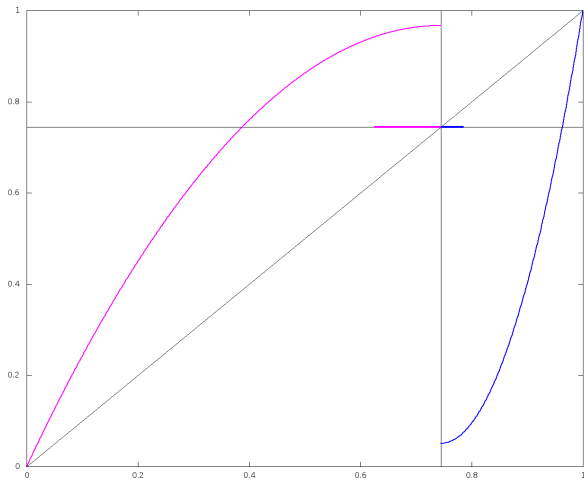
Trivial



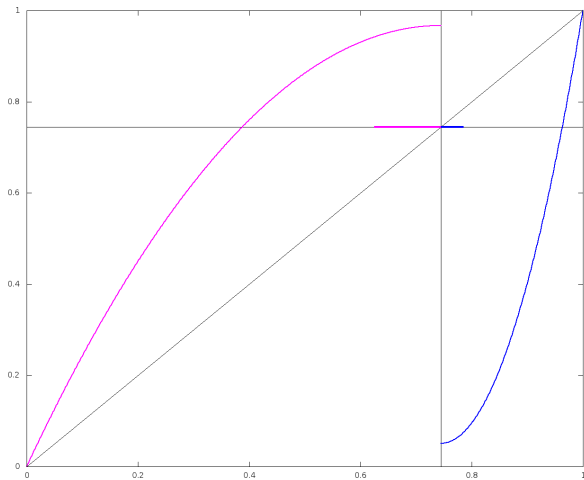
Trivial



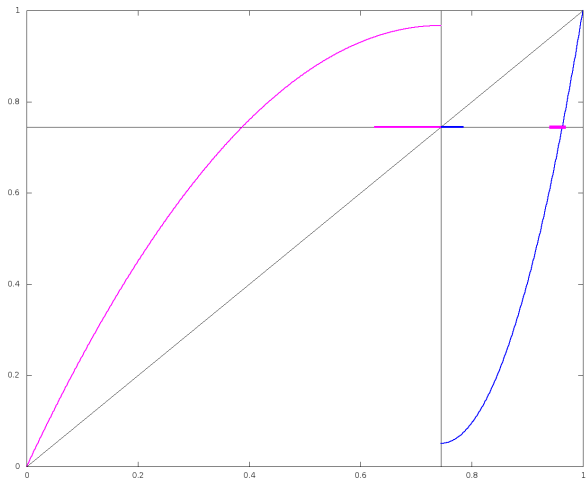
Nontrivial



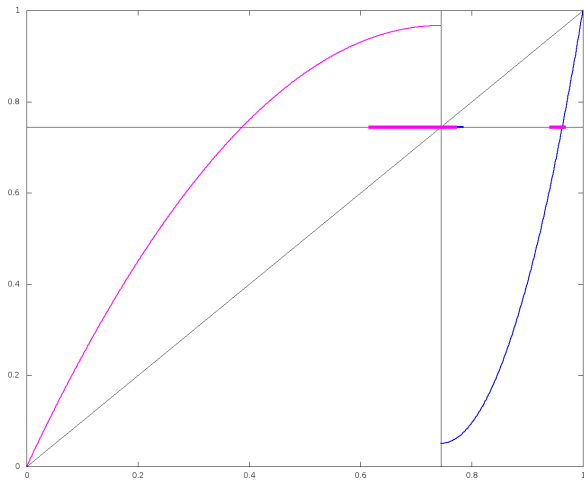
A Lorenz map of renormalization type  $(01, 1000)$ .



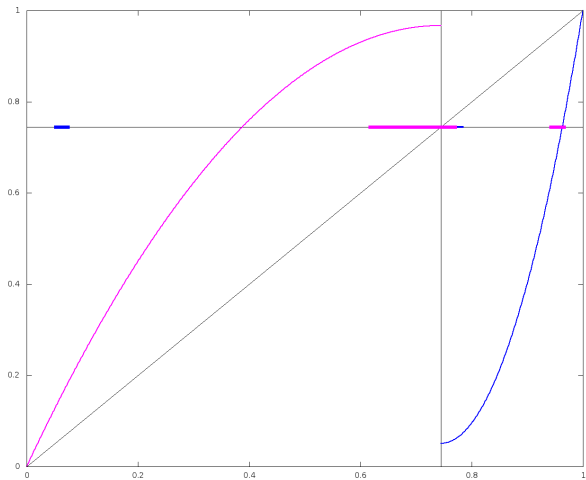
A Lorenz map of renormalization type  $(01, 1000)$ .



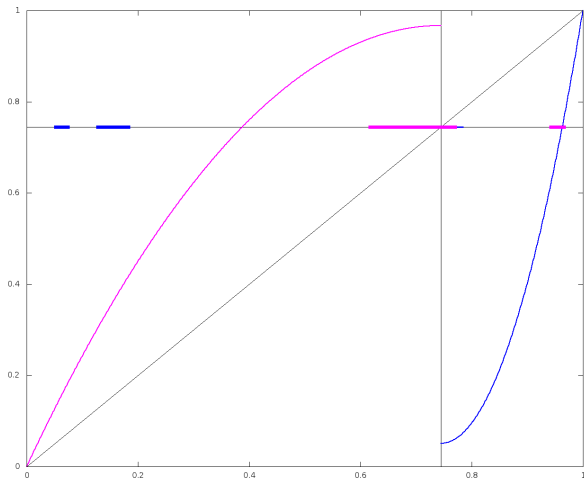
A Lorenz map of renormalization type  $(01, 1000)$ .



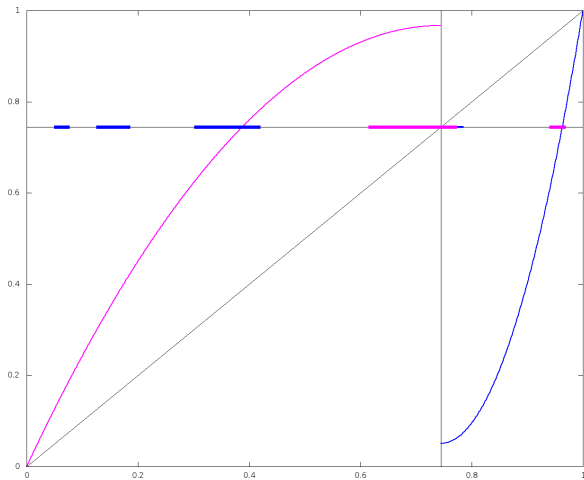
A Lorenz map of renormalization type (01, 1000).



A Lorenz map of renormalization type  $(01, 1000)$ .

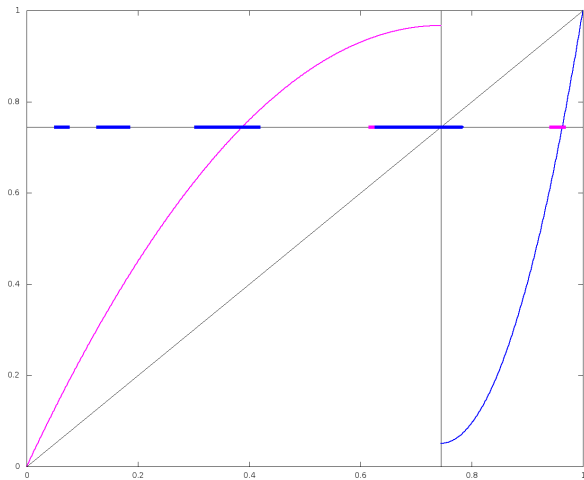


A Lorenz map of renormalization type (01, 1000).



A Lorenz map of renormalization type  $(01, 1000)$ .





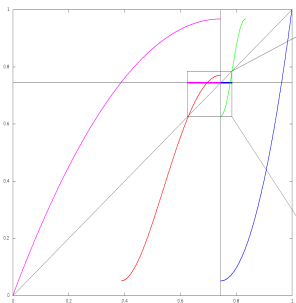
A Lorenz map of renormalization type  $(01, 1000)$ .

- Denote  $L = [p, c)$ ,  $R = (c, q]$ , the first return map will be denoted  $\mathcal{P}[f]$  - the **prerenormalization**. If  $f$  is renormalizable, then  $\exists$  minimal  $n > 1, m > 1$  such that

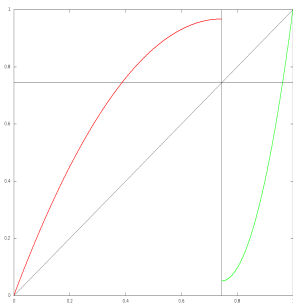
$$\mathcal{P}[f](x) = \begin{cases} f^{n+1}(x), & x \in L, \\ f^{m+1}(x), & x \in R, \end{cases}$$

- Denote  $L = [p, c)$ ,  $R = (c, q]$ , the first return map will be denoted  $\mathcal{P}[f]$  - the **prerenormalization**. If  $f$  is renormalizable, then  $\exists$  minimal  $n > 1, m > 1$  such that

$$\mathcal{P}[f](x) = \begin{cases} f^{n+1}(x), & x \in L, \\ f^{m+1}(x), & x \in R, \end{cases}$$



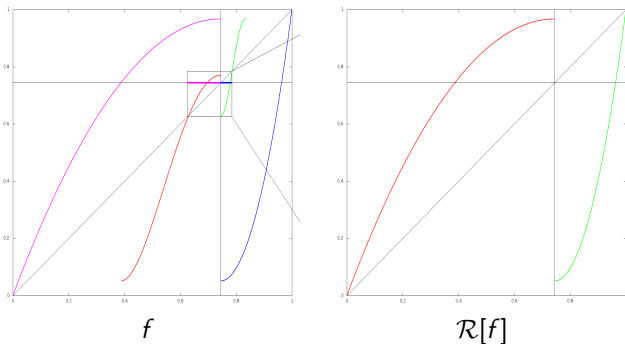
$f$



$\mathcal{R}[f]$

- Denote  $L = [p, c)$ ,  $R = (c, q]$ , the first return map will be denoted  $\mathcal{P}[f]$  - the **prerenormalization**. If  $f$  is renormalizable, then  $\exists$  minimal  $n > 1, m > 1$  such that

$$\mathcal{P}[f](x) = \begin{cases} f^{n+1}(x), & x \in L, \\ f^{m+1}(x), & x \in R, \end{cases}$$



- $\mathcal{R}[f] = A^{-1} \circ \mathcal{P}[f] \circ A,$

where  $A$  is the affine orientation preserving rescaling of  $[0, 1]$  onto  $C$ .

- The intervals  $f^i(L)$ ,  $1 \leq i \leq n$ , and  $f^i(R)$ ,  $1 \leq i \leq m$ , are pairwise disjoint, and disjoint from  $C$ . Associate a finite sequence of 0 and 1 to each of these two sequences of intervals:

$$\omega^- = \{K_0^-, \dots, K_n^-\}, \quad \omega^+ = \{K_0^+, \dots, K_m^+\},$$

$$\omega = (\omega^-, \omega^+) \in \{0, 1\}^{n+1} \times \{0, 1\}^{m+1},$$

- the type of renormalization.

- The intervals  $f^i(L)$ ,  $1 \leq i \leq n$ , and  $f^i(R)$ ,  $1 \leq i \leq m$ , are pairwise disjoint, and disjoint from  $C$ . Associate a finite sequence of 0 and 1 to each of these two sequences of intervals:

$$\omega^- = \{K_0^-, \dots, K_n^-\}, \quad \omega^+ = \{K_0^+, \dots, K_m^+\},$$

$$\omega = (\omega^-, \omega^+) \in \{0, 1\}^{n+1} \times \{0, 1\}^{m+1},$$

- the type of renormalization.

- The combinatorics

$$\omega = (\overbrace{01\dots 1}^n, \overbrace{10\dots 0}^m) \quad (1)$$

will be called **monotone**. Given a fixed  $\omega$ , the set of  $\omega$ -renormalizable maps will be denoted  $\mathcal{L}_\omega$ .

- The intervals  $f^i(L)$ ,  $1 \leq i \leq n$ , and  $f^i(R)$ ,  $1 \leq i \leq m$ , are pairwise disjoint, and disjoint from  $C$ . Associate a finite sequence of 0 and 1 to each of these two sequences of intervals:

$$\omega^- = \{K_0^-, \dots, K_n^-\}, \quad \omega^+ = \{K_0^+, \dots, K_m^+\},$$

$$\omega = (\omega^-, \omega^+) \in \{0, 1\}^{n+1} \times \{0, 1\}^{m+1},$$

- the type of renormalization.

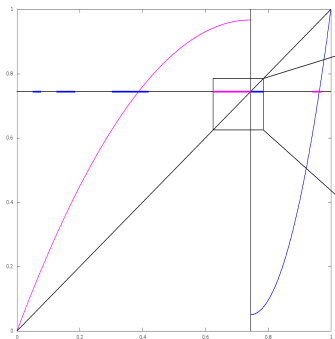
- The combinatorics

$$\omega = (\overbrace{01\dots 1}^n, \overbrace{10\dots 0}^m) \quad (1)$$

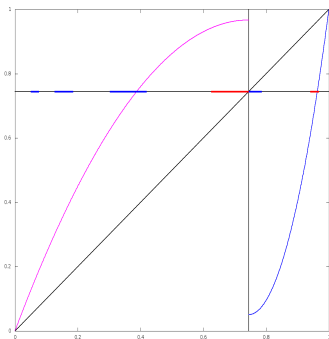
will be called **monotone**. Given a fixed  $\omega$ , the set of  $\omega$ -renormalizable maps will be denoted  $\mathcal{L}_\omega$ .

- If  $\mathcal{R}^i[f] \in \mathcal{L}_{\omega_i}$  and  $\bar{\omega} = (\omega_0, \omega_1, \dots, \omega_n)$ , with  $n$  finite or infinite, then  $f \in \mathcal{L}_{\bar{\omega}}$ .

- Suppose we can construct a compact  $\mathcal{K} \subset \mathcal{L}^k$  which is renormalization invariant:  $R[\mathcal{K}] \subset \mathcal{K}$ . Then consider a  $f \in \mathcal{K} \cap \mathcal{L}_{\bar{\omega}}^S$ ,  $\bar{\omega} = \{\omega_0, \omega_1, \omega_2, \dots\} \in \mathcal{M}^{\mathbb{N}}$ .



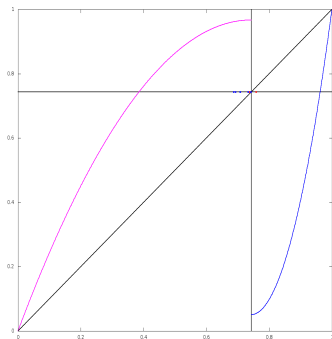
$f$



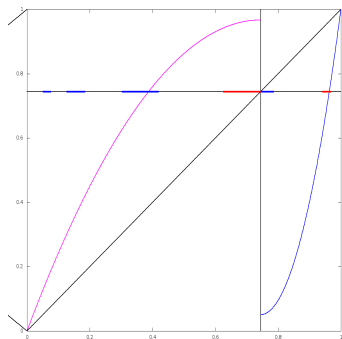
$R[f]$



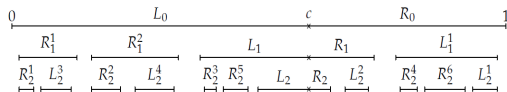
- Suppose we can construct a compact  $\mathcal{K} \subset \mathcal{L}^k$  which is **renormalization invariant**:  $R[\mathcal{K}] \subset \mathcal{K}$ . Then consider a  $f \in \mathcal{K} \cap \mathcal{L}_{\bar{\omega}}^S$ ,  $\bar{\omega} = \{\omega_0, \omega_1, \omega_2, \dots\} \in \mathcal{M}^{\mathbb{N}}$ .



$f$



$R[f]$



Generations of a Cantor set for an infinitely renormalizable map of type (01, 100).

- $\exists C_n = L_n \cup R_n \cup \{c\}$ , which are returned by  $f$ , with return times  $i_n$  and  $j_n$ .

- $\exists C_n = L_n \cup R_n \cup \{c\}$ , which are returned by  $f$ , with return times  $i_n$  and  $j_n$ .
- Let  $\Lambda_0 = [0, 1]$ , define

$$\Lambda_n = \bigcup_{i=0}^{i_n-1} \overline{f^i(L_n)} \cup \bigcup_{j=0}^{j_n-1} \overline{f^j(R_n)}, n = 1, 2, \dots$$

Intervals in  $\Lambda_n$  are intervals of generation  $n$ . Components of  $\Lambda_{n-1} \setminus \Lambda_n$  are gaps of generation  $n$ .

- $\exists C_n = L_n \cup R_n \cup \{c\}$ , which are returned by  $f$ , with return times  $i_n$  and  $j_n$ .
- Let  $\Lambda_0 = [0, 1]$ , define

$$\Lambda_n = \bigcup_{i=0}^{i_n-1} \overline{f^i(L_n)} \cup \bigcup_{j=0}^{j_n-1} \overline{f^j(R_n)}, n = 1, 2, \dots$$

Intervals in  $\Lambda_n$  are intervals of generation  $n$ . Components of  $\Lambda_{n-1} \setminus \Lambda_n$  are gaps of generation  $n$ .

## Cantor attractor

Suppose that  $\mathcal{K}$  is a compact non-empty subset of  $\mathcal{L}^k$ ,  $k \geq 3$ , such that  $R[\mathcal{K} \cap \mathcal{L}_{\mathcal{M}}^S] \subset \mathcal{K}$ .

Let  $f \in \mathcal{L}_{\mathcal{M}}^S \cap \mathcal{K}$  be infinitely renormalizable, and let  $\Lambda$  be the closure of the orbits of the critical values. Then,

- 1)  $\Lambda$  is a Cantor set of Lebesgue measure 0 and a Hausdorff dimension strictly inside  $(0, 1)$ ;
- 2)  $\Lambda$  is uniquely ergodic (if bounded combinatorics);
- 3) the complement of the basin of attraction of  $\Lambda$  in  $[0, 1]$  has zero Lebesgue measure.

## Compactness

- A Lorenz map can be identified with a quintuple  $(u, v, c, \phi, \psi)$ :

$$\mathcal{L}^k \approx [0, 1]^2 \times (0, 1) \times \mathcal{D}^k \times \mathcal{D}^k.$$

## Compactness

- A Lorenz map can be identified with a quintuple  $(u, v, c, \phi, \psi)$ :

$$\mathcal{L}^k \approx [0, 1]^2 \times (0, 1) \times \mathcal{D}^k \times \mathcal{D}^k.$$

Given  $\pi > 0$ ,  $\epsilon > 0$ , set

$$\mathcal{K}_\epsilon^\pi \equiv \{f \in \mathcal{L}^1 : \text{dist}[\psi] \leq \pi, \text{dist}[\phi] \leq \pi; c(f) \in [\epsilon, 1 - \epsilon]\}.$$

## Compactness

- A Lorenz map can be identified with a quintuple  $(u, v, c, \phi, \psi)$ :

$$\mathcal{L}^k \approx [0, 1]^2 \times (0, 1) \times \mathcal{D}^k \times \mathcal{D}^k.$$

Given  $\pi > 0$ ,  $\epsilon > 0$ , set

$$\mathcal{K}_\epsilon^\pi \equiv \{f \in \mathcal{L}^1 : \text{dist}[\psi] \leq \pi, \text{dist}[\phi] \leq \pi; c(f) \in [\epsilon, 1 - \epsilon]\}.$$

## Compactness

Given  $\pi > 0$  and  $\epsilon > 0$ , the set  $\mathcal{K}_\epsilon^\pi$  is relatively compact in  $\mathcal{L}^0$ .

## A-priori bounds



## A-priori bounds

1) Denote the affine transformation that takes  $[0, 1]$  onto  $I$  as  $\xi_I$ .  
The quintuple for the renormalized map is

$$\tilde{u} = \frac{|Q(L)|}{|U|}, \quad \tilde{v} = \frac{|Q(R)|}{|V|}, \quad \tilde{c} = \frac{|L|}{|C|},$$

$$\tilde{\phi} = \xi_{\tilde{\phi}(U)}^{-1} \circ \bar{\phi} \circ \xi_U, \quad \tilde{\psi} = \xi_{\tilde{\psi}(V)}^{-1} \circ \bar{\psi} \circ \xi_V, \quad \bar{\phi} = f_1^n \circ \phi, \quad \bar{\psi} = f_0^m \circ \psi,$$

where  $U = \phi^{-1} \circ f_1^{-n}(C)$ ,  $V = \psi^{-1} \circ f_0^{-m}(C)$ .

## A-priori bounds

1) Denote the affine transformation that takes  $[0, 1]$  onto  $I$  as  $\xi_I$ . The quintuple for the renormalized map is

$$\tilde{u} = \frac{|Q(L)|}{|U|}, \quad \tilde{v} = \frac{|Q(R)|}{|V|}, \quad \tilde{c} = \frac{|L|}{|C|},$$

$$\tilde{\phi} = \xi_{\tilde{\phi}(U)}^{-1} \circ \bar{\phi} \circ \xi_U, \quad \tilde{\psi} = \xi_{\tilde{\psi}(V)}^{-1} \circ \bar{\psi} \circ \xi_V, \quad \bar{\phi} = f_1^n \circ \phi, \quad \bar{\psi} = f_0^m \circ \psi,$$

where  $U = \phi^{-1} \circ f_1^{-n}(C)$ ,  $V = \psi^{-1} \circ f_0^{-m}(C)$ .

2) Demonstrate that for any  $x, y \in [0, 1]$ ,

$$\frac{D\tilde{\phi}(x)}{D\tilde{\phi}(y)} = \frac{D(f_1^n \circ \phi)(z)}{D(f_1^n \circ \phi)(w)} \leq e^\pi, \quad \text{where } z, w \in U.$$

Use the **Koebe principle**!

## A-priori bounds

1) Denote the affine transformation that takes  $[0, 1]$  onto  $I$  as  $\xi_I$ . The quintuple for the renormalized map is

$$\tilde{u} = \frac{|Q(L)|}{|U|}, \quad \tilde{v} = \frac{|Q(R)|}{|V|}, \quad \tilde{c} = \frac{|L|}{|C|},$$

$$\tilde{\phi} = \xi_{\tilde{\phi}(U)}^{-1} \circ \bar{\phi} \circ \xi_U, \quad \tilde{\psi} = \xi_{\tilde{\psi}(V)}^{-1} \circ \bar{\psi} \circ \xi_V, \quad \bar{\phi} = f_1^n \circ \phi, \quad \bar{\psi} = f_0^m \circ \psi,$$

where  $U = \phi^{-1} \circ f_1^{-n}(C)$ ,  $V = \psi^{-1} \circ f_0^{-m}(C)$ .

2) Demonstrate that for any  $x, y \in [0, 1]$ ,

$$\frac{D\tilde{\phi}(x)}{D\tilde{\phi}(y)} = \frac{D(f_1^n \circ \phi)(z)}{D(f_1^n \circ \phi)(w)} \leq e^\pi, \quad \text{where } z, w \in U.$$

Use the **Koebe principle**!

3) Estimate  $\tilde{c} = \frac{|L|}{|C|}$ , and show that there exists  $\epsilon > 0$  such that  $\tilde{c} \in [\epsilon, 1 - \epsilon]$  whenever  $c$  is.

## Summary of results

## Summary of results

- 1) Structure of the parameters space for renormalizable Lorenz maps: M. Martens and W. de Melo (Ergod. Th. and Dynam. Sys. 2001).

## Summary of results

1) Structure of the parameters space for renormalizable Lorenz maps: M. Martens and W. de Melo (Ergod. Th. and Dynam. Sys. 2001).

2) Renormalization

M. Martens, B. Winckler, 2011	Monotone combinatorics, short return times for one branch, long for the other $[\rho] \leq  \omega^-  - 1 \leq [2\rho - 1],$ $n_- \leq  \omega^+  - 1 \leq n_+$	A-priori bounds, renormalization horseshoe, unstable manifolds
-------------------------------------	--	--

## Summary of results

1) Structure of the parameters space for renormalizable Lorenz maps: M. Martens and W. de Melo (Ergod. Th. and Dynam. Sys. 2001).

### 2) Renormalization

M. Martens, B. Winckler, 2011	Monotone combinatorics, short return times for one branch, long for the other $[\rho] \leq  \omega^-  - 1 \leq [2\rho - 1],$ $n_- \leq  \omega^+  - 1 \leq n_+$	A-priori bounds, renormalization horseshoe, unstable manifolds
D.G., 2012	Monotone combinatorics, long returns times for both branches	A-priori bounds, renormalization horseshoe, no hyperbolicity

## Summary of results

1) Structure of the parameters space for renormalizable Lorenz maps: M. Martens and W. de Melo (Ergod. Th. and Dynam. Sys. 2001).

### 2) Renormalization

M. Martens, B. Winckler, 2011	Monotone combinatorics, short return times for one branch, long for the other $[\rho] \leq  \omega^-  - 1 \leq [2\rho - 1],$ $n_- \leq  \omega^+  - 1 \leq n_+$	A-priori bounds, renormalization horseshoe, unstable manifolds
D.G., 2012	Monotone combinatorics, long returns times for both branches	A-priori bounds, renormalization horseshoe, no hyperbolicity
B. Winckler, D.G., 2011	Fixed combinatorics: ( $\{0, 1\}, \{1, 0, 0\}$ )	Existence of a renormalization fixed point