

# INTERVAL TRANSLATION MAPS OF THREE INTERVALS

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# INTERVAL TRANSLATION MAPS

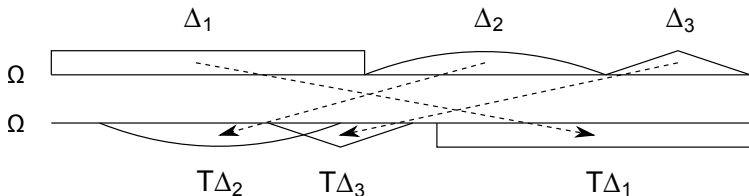


FIGURE: An Interval Translation Map of  $d = 3$  intervals.

$$0 = \beta_0 < \beta_1 < \cdots < \beta_d = 1, \quad \Delta_j := [\beta_{j-1}, \beta_j),$$

$$\Omega := [0, 1), \quad \Omega = \sqcup_{j=1}^d \Delta_j.$$

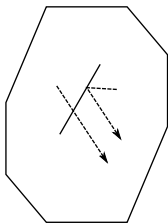
An *interval translation*  $T: \Omega \rightarrow \Omega$  is a map given by a translation on each of  $\Delta_j$ :

$$T|_{\Delta_j}: x \mapsto x + \gamma_j,$$

for some  $(\gamma_1, \dots, \gamma_d) \in \mathbb{R}^d$ .

# INTERVAL TRANSLATION MAPS

Introduced in 1995 by Boshernitzan, Kornfeld.



- Non-invertible generalization of Interval Exchange Transformations.
- Come from polygonal billiards with semi-permeable walls.
- Lebesgue measure is no longer invariant. New effects due to this.

## LIMIT SET

Let  $\Omega_0 = \Omega$ ,  $\Omega_n = T\Omega_{n-1}$  for  $n \geq 1$ .

The *limit set*  $X$  is the closure of  $\bigcap_{n=1}^{\infty} \Omega_n$ .

An interval translation map is called of *finite type* if  $\Omega_{n+1} = \Omega_n$  for some  $n$ , otherwise it is called of *infinite type*.

Denote the set of infinite type ITMs by  $\mathcal{S}$ .

### EXAMPLE

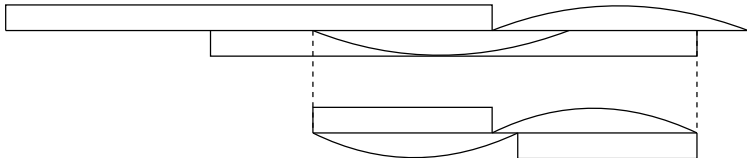


FIGURE: ITM of two intervals: rotation.

## FINITENESS RESULTS

### THEOREM (BOSHERNITZAN, KORNFELD, 1995)

- $\text{rk}(\beta_i, \gamma_i)_{\mathbb{Q}} \leq 2 \Rightarrow T$  is of finite type.
- There exists a translation map of three intervals of infinite type.

### THEOREM (SCHMELING, TROUBETZKOY, 1998)

- Finite type  $\Leftrightarrow X$  is a finite union of intervals,  $T|_X$  is IET.
- Infinite type,  $T|_X$  is transitive  $\Rightarrow X$  is a Cantor set.

## PARAMETER SPACE

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### FINITENESS PROBLEM

*How big is the set  $\mathcal{S}$  of ITMs of infinite type?*

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### FINITENESS PROBLEM

*How big is the set  $\mathcal{S}$  of ITMs of infinite type?*

### THEOREM (2012)

*In the 5-dim space  $\text{ITM}(3)$ , the set  $\mathcal{S}$  has zero Lebesgue measure. Moreover, from numerics (Bruin, Clack, 2011) follows*

$$4 \leq \dim_H(\mathcal{S} \cap \text{ITM}(3)) \leq 4.88.$$



## STRATEGY

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5.  $\mathcal{R}$  has an absolutely continuous ergodic measure  $m$ .
6.  $m(\mathcal{S}) = 0 \Rightarrow \text{Leb}(\mathcal{S}) = 0$ .

## INDUCING ON A SUBINTERVAL

$\Delta \subset \Omega$  is *regular* if  $\forall x \in \Omega$  some  $T^n x \in \Delta$ ,  $n$  uniformly bounded.

$T_\Delta$  is the induced map.

$\Delta \subset \Omega$  is a *trap* if it is regular and  $T\Delta \subset \Delta$ . Then  $T_\Delta = T|_\Delta$ .



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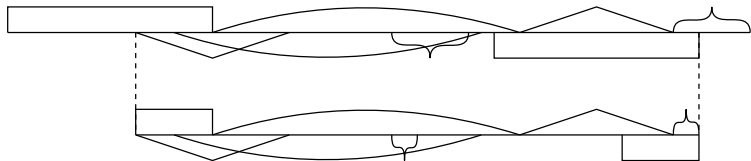
$\Delta \subset \Omega$  is a *trap* if it is regular and  $T\Delta \subset \Delta$ . Then  $T_\Delta = T|_\Delta$ .

### LEMMA

*Assume  $X$  is transitive.*

- *Let  $T$  have finite type. Then for any regular  $\Delta$  the map  $T_\Delta$  has finite type.*
- *Let  $T_\Delta$  have finite type for some regular  $\Delta$ . Then  $T$  has finite type.*

## DIMENSION REDUCTION



$T: \Omega \rightarrow \Omega$  is *tight* if  $[\inf T\Omega, \sup T\Omega) = \Omega$ .

$\text{TITM}(d)$  is the space of tight ITMs of  $d$  intervals.

$$\dim \text{TITM}(d) = \dim \text{ITM}(d) - 2 = 2d - 3.$$

### LEMMA

For any  $T \in \text{ITM}(d)$  there exists a trap  $\Delta$  such that the map  $T_\Delta$  is a tight interval translation map of  $r$  intervals,  $r \leq d$ .

## DOUBLE ROTATIONS

SUZUKI, ITO, AIHARA, 2005

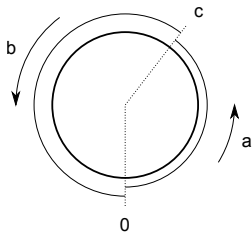
A *double rotation* is

$$f_{(a,b,c)}(x) = \begin{cases} \{x + a\}, & \text{if } x \in [0, c), \\ \{x + b\}, & \text{if } x \in [c, 1). \end{cases}$$

Independent rotations of two complementary arcs of  $S^1$ .

$$\dim \text{Rot}(2) = 3.$$

Any double rotation is an ITM of 2–4 intervals.



# DOUBLE ROTATIONS

## THEOREM (BRUIN, CLACK, 2011)

*The set  $\mathcal{S} \cap \text{Rot}(2)$  has zero Lebesgue measure.*

*Moreover, numerically*

$$2 \leq \dim_H(\mathcal{S} \cap \text{Rot}(2)) \leq 2.88.$$

Proof by Suzuki, Ito, Aihara's renormalization in the parameter space.

## REDUCTION TO DOUBLE ROTATIONS

### THEOREM (2012)

$\text{TITM}(3) = A \cup B \cup C \cup K$ :

- $A \cup B \cup C$  is open and dense.
- $K$  is a union of countably many hyperplanes.

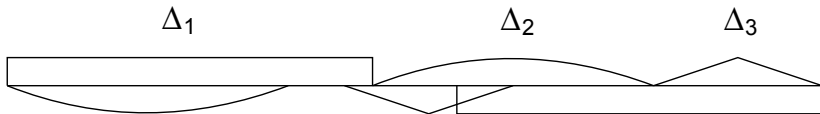
Moreover,

- any  $T \in A$  is a double rotation,
- any  $T \in B$  is reduced to a  $\text{Rot}(2)$  via Type 1 induction,
- any  $T \in C$  is reduced to a  $\text{Rot}(2)$  via Type 2 induction.

*The inductions are piecewise-invertible rational maps.*

Thus zero measure sets and the Hausdorff dimension are preserved.

## COMBINATORICS OF $T\Delta_i$



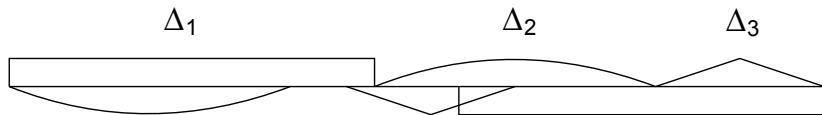
Assume  $\gamma_1 > 0$  and  $\gamma_3 < 0$ .

Because  $T$  is tight, some interval (not  $\Delta_1$ ) must go to the leftmost position, and some interval (not  $\Delta_3$ ) must go to the rightmost position. There are 3 cases:

	$A$	$A'$	$B\&C$
<i>Leftmost</i>	$\Delta_2$	$\Delta_3$	$\Delta_3$
<i>Rightmost</i>	$\Delta_1$	$\Delta_2$	$\Delta_1$

The cases  $A$  and  $A'$  are mirror images of each other, so we consider only case  $A$  of these two.

## DOUBLE ROTATION IN DISGUISE



$\Delta_2$  goes to the leftmost position and  $\Delta_1$  goes to the rightmost position.

$T$  is a double rotation with  $c = \beta_2$  (i.e. the first arc is  $\Delta_1 \cup \Delta_2$  and the second one is  $\Delta_3$ ) and  $a = -|\Delta_1|$ ,  $b = \gamma_3$ .

## INDUCTIONS

	<i>A</i>	<i>A'</i>	<i>B&amp;C</i>
<i>Leftmost</i>	$\Delta_2$	$\Delta_3$	$\Delta_3$
<i>Rightmost</i>	$\Delta_1$	$\Delta_2$	$\Delta_1$

Now  $\Delta_1$  goes rightmost,  $\Delta_3$  goes leftmost. Because of the symmetry, we can assume  $|\Delta_1| \geq |\Delta_3|$ .

Consider the two sub-cases:  $\gamma_2 < 0$  and  $\gamma_2 > 0$ .



## TYPE 1 INDUCTION

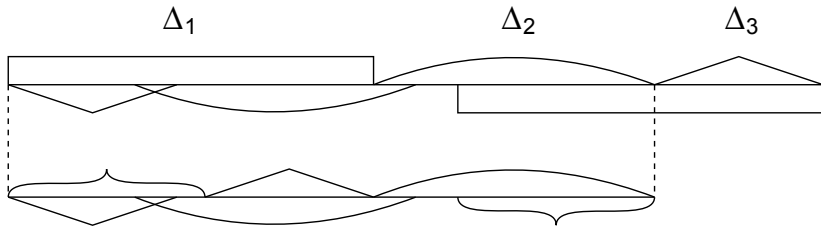


FIGURE: Induction to  $\Delta_1 \cup \Delta_2$ .

Case  $\gamma_2 < 0$ .

### PROPOSITION

*In this case,  $\Delta = \Delta_1 \cup \Delta_2$  is regular with the return time  $\leq 2$ .  $T_\Delta$  is a tight ITM of three intervals which is a double rotation.*

## TYPE 2 INDUCTION

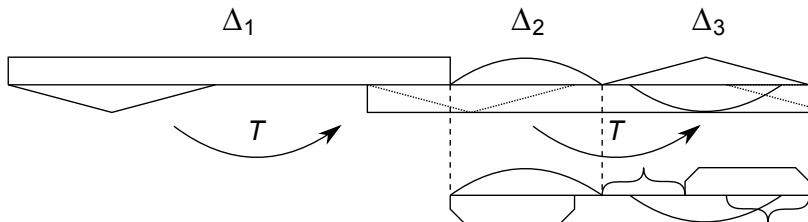


FIGURE: Induction to  $\Delta_2 \cup \Delta_3$ .

Case  $\gamma_2 > 0$ .

### PROPOSITION

*In this case,  $\Delta = \Delta_2 \cup \Delta_3$  is regular, and  $T_\Delta$  is a tight ITM of three intervals which is a double rotation.*

That's it. **THANK YOU!**