

Rigidity of certain solvable actions on the sphere

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For $k \geq 2$, the solvable Baumslag-Solitar group $BS(1, k)$ is defined by

$$BS(1, k) = \langle a, b \mid aba^{-1} = b^k \rangle.$$

This group admits a real-analytic and effective action ρ_{std} on $S^1 = \mathbb{R}P^1 = \mathbb{R} \setminus \{0\}$ given by $\rho_{std}^a(x) = kx$, $\rho_{std}^b(x) = x + 1$ for $x \in \mathbb{R} = S^1 \setminus \{\infty\}$ and $\rho_{std}^a(\infty) = \rho_{std}^b(\infty) = \infty$. In [2], Burslem and Wilkinson proved the following rigidity result on $BS(1, k)$ -actions on S^1 .

Theorem 1 (Burslem-Wilkinson [2]). *For $k \geq 2$, any real-analytic and effective $BS(1, k)$ -action on the circle S^1 is locally rigid.*

As a special case, ρ_{std} is locally rigid.

In this talk, we discuss rigidity of higher dimensional analog of ρ_{std} . For $n \geq 1$ and $k \geq 2$, we define a solvable group $\Gamma_{n,k}$ by

$$\Gamma_{n,k} = \langle a, b_1, \dots, b_n \mid ab_i a^{-1} = b_i^k, b_i b_j = b_j b_i \text{ for any } i, j = 1, \dots, n \rangle.$$

Remark that $\Gamma_{1,k} \simeq \langle a, b_i \rangle \simeq BS(1, k)$. For a basis $(v_1, \dots, v_n) \in \text{GL}(n, \mathbb{R})$, we define a real-analytic $\Gamma_{n,k}$ -action ρ_B on the n -sphere $S^n = \mathbb{R}^n \cup \{\infty\}$ by $\rho_B^a(x) = kx$, $\rho_B^{b_i}(x) = x + v_i$ for $x \in \mathbb{R}^n = S^n \setminus \{\infty\}$ and $\rho_B^a(\infty) = \rho_B^{b_i}(\infty) = \infty$. It is not so hard to see that ρ_B is not locally rigid if $n \geq 2$.

Proposition 2 ([1]). *For $B, B' \in \text{GL}(n, \mathbb{R})$, the actions ρ_B and $\rho_{B'}$ are smoothly conjugate if and only if $B' = (cT)B$ for some $c > 0$ and $T \in \text{O}(n)$.*

However, ρ_B exhibits a form of rigidity, *i.e.*, it has a finite-dimensional deformation space in the following sense:

Main Theorem ([1]). *For any given $n, k \geq 2$ and $B \in \text{GL}(n, \mathbb{R})$, any C^∞ $\Gamma_{n,k}$ -action ρ sufficiently close to ρ_B is smoothly conjugate to $\rho_{B'}$ for some $B' = B'(\rho)$. Moreover, B' depends continuously on the action ρ .*

The proof is divided into three steps:

1. Show the persistence of the global fixed point ∞ . It reduces the theorem to the rigidity problem of the local $\Gamma_{n,k}$ -action associated with ρ_B .

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2. Construct the (modified) non-linear deformation complex of the local $\Gamma_{n,k}$ -action and show its finite-dimensionality.
3. Show the exactness of the (modified) linear deformation complex, and apply Weil's Implicit Function Theorem ([4])

It is natural to ask whether sub-actions of ρ_B restricted to $\langle a, b_1 \rangle \simeq BS(1, k)$. For $n \geq 1$ and $v \in \mathbb{R}^n$, let ρ_v be a $BS(1, k)$ -action on S^n given by $\rho_v^a(x) = kx$ and $\rho_v^b(x) = x + v$ for $x \in \mathbb{R}^n = S^n \setminus \{\infty\}$ and $\rho_v^a(\infty) = \rho_v^b(\infty) = \infty$. Remark that ρ_v and ρ_w are smoothly conjugate for any non-zero $v, w \in \mathbb{R}^n$.

Question 3. For $n \geq 2$, is ρ_v locally rigid?

In the case $n = 2$, it can be shown that the local action at the global fixed point ∞ is *not* locally rigid and its deformation space as a local action is two-dimensional. However, is it unknown whether each non-trivial deformation can extend to a global action on S^n or not. For $n \geq 3$, nothing is known.

References

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