RANDOM GRAPHS

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Graph Theory Preliminaries A graph G, formally speaking, is a pair (V(G), E(G))where the elements $v \in V(G)$ are called vertices and the elements of E(G), called edges, are two element subsets $\{v, w\}$ of V(G). When $\{v, w\} \in E(G)$ we say v, w are adjacent. (In standard graph theory terminology our graphs are undirected and have no loops and no multiple edges.) Pictorially, we often display the $v \in V(G)$ as points and draw an arc between v and w when they are adjacent. We call V(G) the vertex set of G and E(G)the edge set of G. (When G is understood we shall write simply V and E respectively. We also often write $v \in G$ or $\{v, w\} \in G$ instead of the formally correct $v \in V(G)$ and $\{v, w\} \in E(G)$ respectively.) A set $S \subseteq V$ is called a *clique* if all pairs $x, y \in S$ are adjacent. The clique number, denoted by $\omega(G)$, is the largest size of a clique in G. The complete graph on k vertices, denoted by K_k , consists of a vertex set of size k with all pairs x, yadjacent.

1 Lecture 1: Random Graphs

1.1 What is a Random Graph

Let n be a positive integer, $0 \le p \le 1$. The random graph G(n, p) is a probability space over the set of graphs on the vertex set $\{1, \ldots, n\}$ determined by

$$\Pr[\{i, j\} \in G] = p \tag{1}$$

with these events mutually independent.

Random Graphs is an active area of research which combines probability theory and graph theory. The subject began in 1960 with the monumental paper *On the Evolution of Random Graphs* by Paul Erdős and Alfred Rényi. The book *Random Graphs* by Béla Bollobás is the standard source for the field. The book *The Probabilistic Method* by Noga Alon and this author contains much of the material in these notes, and more.

There is a compelling dynamic model for random graphs. For all pairs i, j let $x_{i,j}$ be selected uniformly from [0, 1], the choices mutually independent. Imagine p going from 0 to 1. Originally, all potential edges are "off". The edge from i to j (which we may imagine as a neon light) is turned on when p reaches $x_{i,j}$ and then stays on. At p = 1 all edges

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are "on". At time p the graph of all "on" edges has distribution G(n,p). As p increases G(n,p) evolves from empty to full.

In their original paper Erdős and Rényi let G(n, e) be the random graph with n vertices and precisely e edges. Again there is a dynamic model: Begin with no edges and add edges randomly one by one until the graph becomes full. Generally G(n, e) will have very similar properties as G(n, p) with $p \sim \frac{e}{\binom{n}{2}}$. We will work on the probability model exclusively.

1.2 Threshold Functions

The term "the random graph" is, strictly speaking, a misnomer. G(n, p) is a probability space over graphs. Given any graph theoretic property A there will be a probability that G(n, p) satisfies A, which we write $\Pr[G(n, p) \models A]$. When A is monotone $\Pr[G(n, p) \models A]$ is a monotone function of p. As an instructive example, let A be the event "G is triangle free". Let X be the number of triangles contained in G(n, p). Linearity of expectation gives

$$E[X] = \binom{n}{3} p^3 \tag{2}$$

This suggests the parametrization p = c/n. Then

$$\lim_{n \to \infty} E[X] = \lim_{n \to \infty} \binom{n}{3} p^3 = c^3/6 \tag{3}$$

We shall see that the distribution of X is asymptotically Poisson. In particular

$$\lim_{n \to \infty} \Pr[G(n, p) \models A] = \lim_{n \to \infty} \Pr[X = 0] = e^{-c^3/6}$$
(4)

Note that

$$\lim_{c \to 0} e^{-c^3/6} = 1 \tag{5}$$

$$\lim_{c \to \infty} e^{-c^3/6} = 0 \tag{6}$$

When $p = 10^{-6}/n$, G(n, p) is very unlikely to have triangles and when $p = 10^{6}/n$, G(n, p) is very likely to have triangles. In the dynamic view the first triangles almost always appear at $p = \Theta(1/n)$. If we take a function such as $p(n) = n^{-.9}$ with $p(n) \gg n^{-1}$ then G(n, p) will almost always have triangles. Occasionally we will abuse notation and say, for example, that $G(n, n^{-.9})$ contains a triangle - this meaning that the probability that it contains a triangle approaches 1 as n approaches infinity. Similarly, when $p(n) \ll n^{-1}$, for example, $p(n) = 1/(n \ln n)$, then G(n, p) will almost always not contain a triangle and we abuse notation and say that $G(n, 1/(n \ln n))$ is trianglefree. It was a central observation of Erdős and Rényi that many natural graph theoretic properties become true in a very narrow range of p. They made the following key definition.

Definition 1. r(n) is called a threshold function for a graph theoretic property A if

- 1. When $p(n) \ll r(n), \lim_{n \to \infty} \Pr[G(n, p) \models A] = 0$
- 2. When $p(n) \gg r(n), \lim_{n \to \infty} \Pr[G(n, p) \models A] = 1$

or visa versa.

In our example, 1/n is a threshold function for A. Note that the threshold function, when one exists, is not unique. We could equally have said that 10/n is a threshold function for A.

Lets approach the problem of G(n, c/n) being trianglefree once more. For every set S of three vertices let B_S be the event that S is a triangle. Then $\Pr[B_S] = p^3$. Then "trianglefreeness" is precisely the conjunction $\wedge \overline{B}_S$ over all S. If the B_S were mutually independent then we *would* have

$$\Pr[\wedge \overline{B}_S] = \prod[\overline{B}_S] = (1 - p^3)^{\binom{n}{3}} \sim e^{-\binom{n}{3}p^3} \to e^{-c^3/6}$$
(7)

The reality is that the B_S are not mutually independent though when $|S \cap T| \leq 1$, B_S and B_T are mutually independent. This is quite a typical situation in the study of random graphs in which we must deal with events that are "almost", but not precisely, mutual independent.

1.3 Variance

Here we introduce the Variance in a form that is particularly suited to the study of random graphs. The expressions Δ and Δ^* defined in this section will appear often in these notes.

Let X be a nonnegative integral valued random variable and suppose we want to bound $\Pr[X=0]$ given the value $\mu = E[X]$. If $\mu < 1$ we may use the inequality

$$\Pr[X > 0] \le E[X] \tag{8}$$

so that if $E[X] \to 0$ then X = 0 almost always. (Here we are imagining an infinite sequence of X dependent on some parameter n going to infinity. This is the standard situation with the random graph G(n, p(n)).) But now suppose $E[X] \to \infty$. It does not necessarily follow that X > 0 almost always. For example, let X be the number of deaths due to nuclear war in the twelve months after reading this paragraph. Calculation of E[X] can make for lively debate but few would deny that it is quite large. Yet we may believe - or hope that $Pr[X \neq 0]$ is very close to zero. We can sometimes deduce X > 0 almost always if we have further information about Var[X].

Theorem 1.1.

$$\Pr[X=0] \le \frac{Var[X]}{E[X]^2} \tag{9}$$

Proof. Set $\lambda = \mu/\sigma$ in Chebyschev's Inequality. Then

$$\Pr[X=0] \le \Pr[|X-\mu| \ge \lambda\sigma] \le \frac{1}{\lambda^2} = \frac{\sigma^2}{\mu^2}$$
(10)

We generally apply this result in asymptotic terms.

Corollary 1.2. If $Var[X] = o(E[X]^2)$ then X > 0 a.a.

The proof of Theorem 1.3 actually gives that for any $\epsilon>0$

$$\Pr[|X - E[X]| \ge \epsilon E[X]] \le \frac{Var[X]}{\epsilon^2 E[X]^2}$$
(11)

and thus in asymptotic terms we actually have the following stronger assertion:

Corollary 1.3. If $Var[X] = o(E[X]^2)$ then $X \sim E[X]$ a.a.

Suppose again $X = X_1 + \ldots + X_m$ where X_i is the indicator random variable for event A_i . For indices i, j write $i \sim j$ if $i \neq j$ and the events A_i, A_j are not independent. We set (the sum over ordered pairs)

$$\Delta = \sum_{i \sim j} \Pr[A_i \wedge A_j] \tag{12}$$

Note that when $i \sim j$

$$Cov[X_i, X_j] = E[X_i X_j] - E[X_i]E[X_j] \le E[X_i X_j] = \Pr[A_i \land A_j]$$

$$\tag{13}$$

and that when $i \neq j$ and not $i \sim j$ then $Cov[X_i, X_j] = 0$. Thus

$$Var[X] \le E[X] + \Delta \tag{14}$$

Corollary 1.4. If $E[X] \to \infty$ and $\Delta = o(E[X]^2)$ then X > 0 almost always. Furthermore $X \sim E[X]$ almost always.

Let us say X_1, \ldots, X_m are symmetric if for every $i \neq j$ there is an automorphism of the underlying probability space that sends event A_i to event A_j . Examples will appear in the next section. In this instance we write

$$\Delta = \sum_{i \sim j} \Pr[A_i \wedge A_j] = \sum_i \Pr[A_i] \sum_{j \sim i} \Pr[A_j | A_i]$$
(15)

and note that the inner summation is independent of i. We set

$$\Delta^* = \sum_{j \sim i} \Pr[A_j | A_i] \tag{16}$$

where i is any fixed index. Then

$$\Delta = \sum_{i} \Pr[A_i] \Delta^* = \Delta^* \sum_{i} \Pr[A_i] = \Delta^* E[X]$$
(17)

Corollary 1.5. If $E[X] \to \infty$ and $\Delta^* = o(E[X])$ then X > 0 almost always. Furthermore $X \sim E[X]$ almost always.

The condition of Corollary 1.4 has the intuitive sense that conditioning on any specific A_i holding does not substantially increase the expected number E[X] of events holding.

1.4 Appearance of Small Subgraphs

What is the threshold function for the appearance of a given graph H. This problem was solved in the original papers of Erdős and Rényi. We begin with an instructive special case.

Theorem 1.6. The property $\omega(G) \ge 4$ has threshold function $n^{-2/3}$.

Proof. For every 4-set S of vertices in G(n, p) let A_S be the event "S is a clique" and X_S its indicator random variable. Then

$$E[X_S] = \Pr[A_S] = p^6 \tag{18}$$

as six different edges must all lie in G(n, p). Set

$$X = \sum_{|S|=4} X_S \tag{19}$$

so that X is the number of 4-cliques in G and $\omega(G) \ge 4$ if and only if X > 0. Linearity of Expectation gives

$$E[X] = \sum_{|S|=4} E[X_S] = \binom{n}{4} p^6 \sim \frac{n^4 p^6}{24}$$
(20)

When $p(n) \ll n^{-2/3}$, E[X] = o(1) and so X = 0 almost surely.

Now suppose $p(n) \gg n^{-2/3}$ so that $E[X] \to \infty$ and consider the Δ^* of Corollary 1.5. (All 4-sets "look the same" so that the X_S are symmetric.) Here $S \sim T$ if and only if $S \neq T$ and S, T have common edges - i.e., if and only if $|S \cap T| = 2$ or 3. Fix S. There are $O(n^2)$ sets T with $|S \cap T| = 2$ and for each of these $\Pr[A_T|A_S] = p^5$. There are O(n) sets T with $|S \cap T| = 3$ and for each of these $\Pr[A_T|A_S] = p^3$. Thus

$$\Delta^* = O(n^2 p^5) + O(np^3) = o(n^4 p^6) = o(E[X])$$

since $p \gg n^{-2/3}$. Corollary 1.5 therefore applies and X > 0, i.e., there *does* exist a clique of size 4, almost always.

The proof of Theorem 1.6 appears to require a fortuitous calculation of Δ^* . The following definitions will allow for a description of when these calculations work out.

Definition 2. Let H be a graph with v vertices and e edges. We call $\rho(H) = e/v$ the density of H. We call H balanced if every subgraph H' has $\rho(H') \leq \rho(H)$. We call H strictly balanced if every proper subgraph H' has $\rho(H') < \rho(H)$.

Examples. K_4 and, in general, K_k are strictly balanced. The graph



is not balanced as it has density 7/5 while the subgraph K_4 has density 3/2. The graph



is balanced but not strictly balanced as it and its subgraph K_4 have density 3/2.

Theorem 1.7. Let H be a balanced graph with v vertices and e edges. Let A(G) be the event that H is a subgraph (not necessarily induced) of G. Then $p = n^{-v/e}$ is the threshold function for A.

Proof. We follow the argument of Theorem 1.6. For each v-set S let A_S be the event that $G|_S$ contains H as a subgraph. Then

$$p^e \le \Pr[A_S] \le v! p^e \tag{21}$$

(Any particular placement of H has probability p^e of occuring and there are at most v! possible placements. The precise calculation of $\Pr[A_S]$ is, in general, complicated due to the overlapping of potential copies of H.) Let X_S be the indicator random variable for A_S and

$$X = \sum_{|S|=v} X_S \tag{22}$$

so that A holds if and only if X > 0. Linearity of Expectation gives

$$E[X] = \sum_{|S|=v} E[X_S] = \binom{n}{v} \Pr[A_S] = \Theta(n^v p^e)$$
(23)

If $p \ll n^{-v/e}$ then E[X] = o(1) so X = 0 almost always.

Now assume $p \gg n^{-v/e}$ so that $E[X] \to \infty$ and consider the Δ^* of Corollary 1.5. (All v-sets look the same so the X_S are symmetric.) Here $S \sim T$ if and only if $S \neq T$ and S, T have common edges - i.e., if and only if $|S \cap T| = i$ with $2 \leq i \leq v - 1$. Let S be fixed. We split

$$\Delta^* = \sum_{T \sim S} \Pr[A_T | A_S] = \sum_{i=2}^{v-1} \sum_{|T \cap S|=i} \Pr[A_T | A_S]$$
(24)

For each *i* there are $O(n^{v-i})$ choices of *T*. Fix *S*, *T* and consider $\Pr[A_T|A_S]$. There are O(1) possible copies of *H* on *T*. Each has - since, critically, *H* is balanced - at most $\frac{ie}{v}$ edges with both vertices in *S* and thus at least $e - \frac{ie}{v}$ other edges. Hence

$$\Pr[A_T|A_S] = O(p^{e - \frac{ie}{v}}) \tag{25}$$

and

$$\Delta^* = \sum_{i=2}^{v-1} O(n^{v-i} p^{e-\frac{ie}{v}}) = \sum_{i=2}^{v-1} O((n^v p^e)^{1-\frac{i}{v}})$$
(26)

so that

$$\Delta^* = \sum_{i=2}^{v-1} o(n^v p^e) = o(E[X])$$
(27)

as $n^v p^e \to \infty$. Hence Corollary 1.5 applies.

Theorem 1.8. In the notation of Theorem 1.7 if H is not balanced then $p = n^{-v/e}$ is not the threshold function for A.

Proof. Let H_1 be a subgraph of H with v_1 vertices, e_1 edges and $e_1/v_1 > e/v$. Let α satisfy $v/e < \alpha < v_1/e_1$ and set $p = n^{-\alpha}$. The expected number of copies of H_1 is then o(1) so almost always G(n,p) contains no copy of H_1 . But if it contains no copy of H_1 then it surely can contain no copy of H.

The threshold function for the property of containing a copy of H, for general H, was examined in the original papers of Erdős and Rényi. Let H_1 be that subgraph with maximal density $\rho(H_1) = e_1/v_1$. (When H is balanced we may take $H_1 = H$.) They showed that $p = n^{-v_1/e_1}$ is the threshold function. This will follow fairly quickly from the methods of theorem 1.7.

We finish this section with two strengthenings of Theorem 1.7.

Theorem 1.9. Let H be strictly balanced with v vertices, e edges and a automorphisms. Let X be the number of copies of H in G(n,p). Assume $p \gg n^{-v/e}$. Then almost always

$$X \sim \frac{n^v p^e}{a} \tag{28}$$

Proof. Label the vertices of H by $1, \ldots, v$. For each ordered x_1, \ldots, x_v let A_{x_1, \ldots, x_v} be the event that x_1, \ldots, x_v provides a copy of H in that order. Specifically we define

$$A_{x_1,\dots,x_v}: \{i,j\} \in E(H) \Rightarrow \{x_i,x_j\} \in E(G)$$

$$\tag{29}$$

We let I_{x_1,\ldots,x_v} be the corresponding indicator random variable. We define an equivalence class on v-tuples by setting $(x_1,\ldots,x_v) \equiv (y_1,\ldots,y_v)$ if there is an automorphism σ of V(H) so that $y_{\sigma(i)} = x_i$ for $1 \leq i \leq v$. Then

$$X = \sum I_{x_1,\dots,x_v} \tag{30}$$

gives the number of copies of H in G where the sum is taken over one entry from each equivalence class. As there are $(n)_v/a$ terms

$$E[X] = \frac{(n)_v}{a} E[I_{x_1,\dots,x_v}] = \frac{(n)_v p^e}{a} \sim \frac{n^v p^e}{a}$$
(31)

Our assumption $p \gg n^{-v/e}$ implies $E[X] \to \infty$. It suffices therefore to show $\Delta^* = o(E[X])$. Fixing x_1, \ldots, x_v ,

$$\Delta^* = \sum_{(y_1, \dots, y_v) \sim (x_1, \dots, x_v)} \Pr[A_{(y_1, \dots, y_v)} | A_{(x_1, \dots, x_v)}]$$
(32)

There are v!/a = O(1) terms with $\{y_1, \ldots, y_v\} = \{x_1, \ldots, x_v\}$ and for each the conditional probability is at most one (actually, at most p), thus contributing O(1) = o(E[X]) to Δ^* . When $\{y_1, \ldots, y_v\} \cap \{x_1, \ldots, x_v\}$ has i elements, $2 \le i \le v - 1$ the argument of Theorem 1.7 gives that the contribution to Δ^* is o(E[X]). Altogether $\Delta^* = o(E[X])$ and we apply Corollary 1.5 **Theorem 1.10.** Let H be any fixed graph. For every subgraph H' of H (including H itself) let $X_{H'}$ denote the number of copies of H' in G(n,p). Assume p is such that $E[X_{H'}] \to \infty$ for every H'. Then

$$X_H \sim E[X_H] \tag{33}$$

almost always.

Proof. Let H have v vertices and e edges. As in Theorem 4.4 it suffices to show $\Delta^* = o(E[X])$. We split Δ^* into a finite number of terms. For each H' with w vertice and f edges we have those (y_1, \ldots, y_v) that overlap with the fixed (x_1, \ldots, x_v) in a copy of H'. These terms contribute, up to constants,

$$n^{v-w}p^{e-f} = \Theta\left(\frac{E[X_H]}{E[X_{H'}]}\right) = o(E[X_H])$$

to Δ^* . Hence Corollary 1.5 does apply.

1.5 Connectivity

In this section we give a relatively simple example of what we call the Poisson Paradigm: the rough notion that if there are many rare and nearly independent events then the number of events that hold has approximately a Poisson distribution. This will yield one of the most beautiful of the Erdős- Rényi results, a quite precise description of the threshold behavior for connectivity. A vertex $v \in G$ is *isolated* if it is adjacent to no $w \in V$. In G(n, p) let X be the number of isolated vertices.

Theorem 1.11. Let p = p(n) satisfy $n(1-p)^{n-1} = \mu$. Then

$$\lim_{n \to \infty} \Pr[X = 0] = e^{-\mu} \tag{34}$$

Proof. We let X_i be the indicator random variable for vertex *i* being isolated so that $X = X_1 + \ldots + X_n$. Then $E[X_i] = (1-p)^{n-1}$ so by linearity of expectation $E[X] = \mu$. Now consider the *r*-th factorial moment $E[(X)_r]$ $((X)_r := \prod i = 0^{r-1}(X-i))$ for any fixed *r*. By the symmetry $E[(X)_r] = (n)_r E[X_1 \cdots X_r]$. For vertices $1, \ldots, r$ to all be isolated the $r(n-1) - \binom{r}{2}$ pairs $\{i, x\}$ overlapping $1, \ldots, r$ must all not be edges. Thus

$$E[(X)_r] = (n)_r (1-p)^{r(n-1) - \binom{r}{2}} \sim n^r (1-p)^{r(n-1)} \sim \mu^r$$
(35)

(That is, the dependence among the X_i was asymptotically negligible.) All the moments of X approach those of $P(\mu)$. This implies (a nonobvious result in probability theory) that X approaches $P(\mu)$ in distribution.

Now we give the Erdős-Rényi famous "double exponential" result.

Theorem 1.12. Let

$$p = p(n) = \frac{\log n}{n} + \frac{c}{n} + o(\frac{1}{n})$$
(36)

Then

$$\lim_{n \to \infty} \Pr[G(n, p) \text{ is connected}] = e^{-e^{-c}}$$
(37)

Proof. For such p, $n(1-p)^{n-1} \sim \mu = e^{-c}$ and by the above argument the probability that X has no isolated vertices approaches $e^{-\mu}$. If G has no isolated vertices but is not connected there is a component of k vertices for some $2 \leq k \leq \frac{n}{2}$. Letting B be this event

$$\Pr[B] \le \sum_{k=2}^{n/2} \binom{n}{k} k^{k-2} p^{k-1} (1-p)^{k(n-1) - \binom{k}{2}}$$
(38)

The first factor is the choice of a component set $S \subset V(G)$. The second factor is a choice of tree on S. The third factor is the probability that those tree pairs are in E(G). The final factor is that there be no edge from S to V(G) - S. Some calculation (which we omit but note that k = 2 provides the main term) gives that $\Pr[B] = o(1)$ so that $X \neq 0$ and connectivity have the same limiting probability.

1.6 The Janson Inequalities

In many instances we would like to bound the probability that none of a set of bad events $B_i, i \in I$ occur. If the events are mutually independent then

$$\Pr[\wedge_{i\in I}\overline{B_i}] = \prod_{i\in I}\Pr[\overline{B_i}]$$
(39)

When the B_i are "mostly" independent the Janson Inequalities allow us, sometimes, to say that these two quantities are "nearly" equal.

Let Ω be a finite universal set and let R be a random subset of Ω given by

$$\Pr[r \in R] = p_r,\tag{40}$$

these events mutually independent over $r \in \Omega$. (In application to G(n, p), Ω is the set of pairs $\{i, j\}$, $i, j \in V(G)$ and all $p_r = p$ so that R is the edge set of G(n, p).) Let $A_i, i \in I$, be subsets of Ω , I a finite index set. Let B_i be the event $A_i \subseteq R$. (That is, each point $r \in \Omega$ "flips a coin" to determine if it is in R. B_i is the event that the coins for all $r \in A_i$ came up "heads".) Let X_i be the indicator random variable for B_i and $X = \sum_{i \in I} X_i$ the number of $A_i \subseteq R$. The event $\wedge_{i \in I} \overline{B_i}$ and X = 0 are then identical. For $i, j \in I$ we write $i \sim j$ if $i \neq j$ and $A_i \cap A_j \neq \emptyset$. Note that when $i \neq j$ and not $i \sim j$ then B_i, B_j are independent events since they involve separate coin flips. Furthermore, and this plays a crucial role in the proofs, if $i \notin J \subset I$ and not $i \sim j$ for all $j \in J$ then B_i is mutually independent of $\{B_j | j \in J\}$, i.e., independent of any Boolean function of those B_j . This is because the coin flips on A_i and on $\cup_{j \in J} A_j$ are independent. We define

$$\Delta = \sum_{i \sim j} \Pr[B_i \wedge B_j] \tag{41}$$

Here the sum is over ordered pairs so that $\Delta/2$ gives the same sum over unordered pairs. (This will be the same Δ as defined earlier.) We set

$$M = \prod_{i \in I} \Pr[\overline{B_i}],\tag{42}$$

the value of $\Pr[\wedge_{i \in I} \overline{B_i}]$ if the B_i were independent.

Theorem 1.13 (The Janson Inequality). Let $B_i, i \in I, \Delta, M$ be as above and assume all $\Pr[B_i] \leq \epsilon$. Then

$$M \le \Pr[\wedge_{i \in I} \overline{B_i}] \le M e^{\frac{1}{1-\epsilon} \frac{\Delta}{2}}$$
(43)

Now set

$$\mu = E[X] = \sum_{i \in I} \Pr[B_i] \tag{44}$$

For each $i \in I$

$$\Pr[\overline{B_i}] = 1 - \Pr[B_i] \le e^{-\Pr[B_i]} \tag{45}$$

so, multiplying over $i \in I$,

$$M \le e^{-\mu} \tag{46}$$

It is often more convenient to replace the upper bound of Theorem 1.13 with

$$\Pr[\wedge_{i\in I}\overline{B_i}] \le e^{-\mu + \frac{1}{1-\epsilon}\frac{\Delta}{2}} \tag{47}$$

As an example, set $p = cn^{-2/3}$ and consider the probability that G(n,p) contains no K_4 . The B_i then range over the $\binom{n}{4}$ potential K_4 - each being a 6-element subset of Ω . Here, as is often the case, $\epsilon = o(1)$, $\Delta = o(1)$ (as calculated previously) and μ approaches a constant, here $k = c^6/24$. In these instances $\Pr[\wedge_{i \in I} \overline{B_i}] \to e^{-k}$. Thus we have the fine structure of the threshold function of $\omega(G) = 4$.

As Δ becomes large the Janson Inequality becomes less precise. Indeed, when $\Delta \geq 2\mu(1-\epsilon)$ it gives an upper bound for the probability which is larger than one. At that point (and even somewhat before) the following result kicks in.

Theorem 1.14. (Generalized Janson Inequality) Under the assumptions of Theorem 1.13 and the further assumption that $\Delta \ge \mu(1 - \epsilon)$

$$\Pr[\wedge_{i\in I}\overline{B_i}] \le e^{-\frac{\mu^2(1-\epsilon)}{2\Delta}} \tag{48}$$

The Generalized Janson Inequality (when it applies) often gives a much stronger result than Chebyschev's Inequality as used earlier. We can bound $Var[X] \leq \mu + \Delta$ so that

$$\Pr[\wedge_{i\in I}\overline{B_i}] = \Pr[X=0] \le \frac{Var[X]}{E[X]^2} \le \frac{\mu + \Delta}{\mu^2}$$
(49)

Suppose $\epsilon = o(1), \ \mu \to \infty, \ \mu \ll \Delta$, and $\gamma = \frac{\mu^2}{\Delta} \to \infty$. Chebyschev's upper bound on $\Pr[X = 0]$ is then roughly γ^{-1} while Janson's upper bound is roughly $e^{-\gamma}$.

1.7 The Proofs

The original proofs of Janson are based on estimates of the Laplace transform of an appropriate random variable. The proof presented here follows that of Boppana and Spencer [1989]. We shall use the inequalities

$$\Pr[B_i|\wedge_{j\in J}\overline{B_j}] \le \Pr[B_i] \tag{50}$$

valid for all index sets $J \subset I, i \notin J$ and

$$\Pr[B_i|B_k \wedge \bigwedge_{j \in J} \overline{B_j}] \le \Pr[B_i|B_k]$$
(51)

valid for all index sets $J \subset I, i, k \notin J$. The first follows from general Correlation Inequalities. The second is equivalent to the first since conditioning on B_k is the same as assuming $p_r = \Pr[r \in R] = 1$ for all $r \in A_k$. We note that Janson's Inequality actually applies to any set of events B_i and relation ~ for which (50,51) apply.

Proof. (Thm. 1.13) The lower bound follows immediately. Order the index set $I = \{1, \ldots, m\}$ for convenience. For $1 \le i \le m$

$$Pr[B_i| \wedge_{1 \le j < i} \overline{B_j}] \le \Pr[B_i] \tag{52}$$

 \mathbf{SO}

$$Pr[\overline{B_i}| \wedge_{1 \le j < i} \overline{B_j}] \ge Pr[\overline{B_i}]$$
(53)

and

$$\Pr[\wedge_{i \in I} \overline{B_i}] = \prod_{i=1}^m \Pr[\overline{B_i}| \wedge_{1 \le j < i} \overline{B_j}] \ge \prod_{i=1}^m \Pr[\overline{B_i}]$$
(54)

Now the upper bound. For a given *i* renumber, for convenience, so that $i \sim j$ for $1 \leq j \leq d$ and not for $d+1 \leq j < i$. We use the inequality $\Pr[A|B \wedge C] \geq \Pr[A \wedge B|C]$, valid for any A, B, C. With $A = B_i, B = \overline{B_1} \wedge \ldots \wedge \overline{B_d}, C = \overline{B_{d+1}} \wedge \ldots \wedge \overline{B_{i-1}}$

$$Pr[B_i| \wedge_{1 \le j < i} \overline{B_j}] = \Pr[A|B \wedge C] \ge Pr[A \wedge B|C] = Pr[A|C]Pr[B|A \wedge C]$$
(55)

From the mutual independence Pr[A|C] = Pr[A]. We bound

$$\Pr[B|A \wedge C] \ge 1 - \sum_{j=1}^{d} \Pr[B_j|B_i \wedge C] \ge 1 - \sum_{j=1}^{d} \Pr[B_j|B_i]$$
(56)

from the Correlation Inequality. Thus

$$Pr[B_i| \wedge_{1 \le j < i} \overline{B_j}] \ge \Pr[B_i] - \sum_{j=1}^d Pr[B_j \wedge B_i]$$
(57)

Reversing

$$Pr[\overline{B_i}| \wedge_{1 \le j < i} \overline{B_j}] \le \Pr[\overline{B_i}] + \sum_{j=1}^d \Pr[B_j \wedge B_i]$$
(58)

$$\leq \Pr[\overline{B_i}] \left(1 + \frac{1}{1 - \epsilon} \sum_{j=1}^d \Pr[B_j \wedge B_i] \right)$$
(59)

since $\Pr[\overline{B_i}] \ge 1 - \epsilon$. Employing the inequality $1 + x \le e^x$,

$$Pr[\overline{B_i}| \wedge_{1 \le j < i} \overline{B_j}] \le \Pr[\overline{B_i}] e^{\frac{1}{1-\epsilon} \sum_{j=1}^d \Pr[B_j \wedge B_i]}$$
(60)

For each $1 \leq i \leq m$ we plug this inequality into

$$\Pr[\wedge_{i \in I} \overline{B_i}] = \prod_{i=1}^m \Pr[\overline{B_i}| \wedge_{1 \le j < i} \overline{B_j}]$$
(61)

The terms $\Pr[\overline{B_i}]$ multiply to M. The exponents add: for each $i, j \in I$ with j < i and $j \sim i$ the term $\Pr[B_j \land B_i]$ appears once so they add to $\Delta/2$.

Proof. (Theorem 1.14) As discussed earlier, the proof of Theorem 1.13 gives

$$\Pr[\wedge_{i \in I} \overline{B_i}] \le e^{-\mu + \frac{1}{1 - \epsilon} \frac{\Delta}{2}}$$
(62)

which we rewrite as

$$-\ln[\Pr[\wedge_{i\in I}\overline{B_i}]] \ge \sum_{i\in I}\Pr[B_i] - \frac{1}{2(1-\epsilon)}\sum_{i\sim j}\Pr[B_i \wedge B_j]$$
(63)

For any set of indices $S \subset I$ the same inequality applied only to the $B_i, i \in S$ gives

$$-\ln[\Pr[\wedge_{i\in S}\overline{B_i}]] \ge \sum_{i\in S} \Pr[B_i] - \frac{1}{2(1-\epsilon)} \sum_{i,j\in S, i\sim j} \Pr[B_i \wedge B_j]$$
(64)

Let now S be a random subset of I given by

$$\Pr[i \in S] = p \tag{65}$$

with p a constant to be determined, the events mutually independent. (Here we are using probabilistic methods to prove a probability theorem!)

$$E\left[-\ln[\Pr[\wedge_{i\in S}\overline{B_i}]\right] \ge E\left[\sum_{i\in S}\Pr[B_i]\right] - \frac{1}{2(1-\epsilon)}E\left[\sum_{i,j\in S, i\sim j}\Pr[B_i \wedge B_j]\right]$$
(66)

Each term $\Pr[B_i]$ then appears with probability p and each term $\Pr[B_i \wedge B_j]$ with probability p^2 so that

$$E\left[-\ln[\Pr[\wedge_{i\in S}\overline{B_i}]\right] \ge p\mu - \frac{1}{1-\epsilon}p^2\frac{\Delta}{2}$$
(67)

We set

$$p = \frac{\mu(1-\epsilon)}{\Delta} \tag{68}$$

so as to maximize this quantity. The added assumption of Theorem 1.14 assures us that the probability p is at most one. Then

$$E\left[-\ln[\Pr[\wedge_{i\in S}\overline{B_i}]\right] \ge \frac{\mu^2(1-\epsilon)}{2\Delta}$$
(69)

Therefore there is a specific $S \subset I$ for which

$$-\ln[\Pr[\wedge_{i\in S}\overline{B_i}] \ge \frac{\mu^2(1-\epsilon)}{2\Delta}$$
(70)

That is,

$$\Pr[\wedge_{i\in S}\overline{B_i}] \le e^{-\frac{\mu^2(1-\epsilon)}{2\Delta}} \tag{71}$$

But

$$\Pr[\wedge_{i \in I} \overline{B_i}] \le \Pr[\wedge_{i \in S} \overline{B_i}] \tag{72}$$

completing the proof.

1.8 Appearance of Small Subgraphs Revisited

Generalizing the fine threshold behavior for the appearance of K_4 we find the fine threshold behavior for the appearance of any strictly balanced graph H.

Theorem 1.15. Let H be a strictly balanced graph with v vertices, e edges and a automorphisms. Let c > 0 be arbitrary. Let A be the property that G contains no copy of H. Then with $p = cn^{-v/e}$,

$$\lim_{n \to \infty} \Pr[G(n, p) \models A] = exp[-c^e/a]$$
(73)

Proof. Let $A_{\alpha}, 1 \leq \alpha \leq {n \choose v} v!/a$, range over the edge sets of possible copies of H and let B_{α} be the event $G(n, p) \supseteq A_{\alpha}$. We apply Janson's Inequality. As

$$\lim_{n \to \infty} \mu = \lim_{n \to \infty} \binom{n}{v} v! p^e / a = c^e / a \tag{74}$$

we find

$$\lim_{n \to \infty} M = \exp[-c^e/a] \tag{75}$$

Now we examine (similar to Theorem 1.7)

$$\Delta = \sum_{\alpha \sim \beta} \Pr[B_{\alpha} \wedge B_{\beta}] \tag{76}$$

We split the sum according to the number of *vertices* in the intersection of copies α and β . Suppose they intersect in j vertices. If j = 0 or j = 1 then $A_{\alpha} \cap A_{\beta} = \emptyset$ so that $\alpha \sim \beta$ cannot occur. For $2 \leq j \leq v$ let f_j be the maximal $|A_{\alpha} \cap A_{\beta}|$ where $\alpha \sim \beta$ and α, β intersect in j vertices. As $\alpha \neq \beta$, $f_v < e$. When $2 \leq j \leq v - 1$ the critical observation is that $A_{\alpha} \cap A_{\beta}$ is a subgraph of H and hence, as H is strictly balanced,

$$\frac{f_j}{j} < \frac{e}{v} \tag{77}$$

There are $O(n^{2v-j})$ choices of α, β intersecting in j points since α, β are determined, except for order, by 2v - j points. For each such α, β

$$\Pr[B_{\alpha} \wedge B_{\beta}] = p^{|A_{\alpha} \cup A_{\beta}|} = p^{2e - |A_{\alpha} \cap A_{\beta}|} \le p^{2e - f_{j}}$$
(78)

Thus

$$\Delta = \sum_{j=2}^{v} O(n^{2v-j}) O(n^{-\frac{v}{e}(2e-f_j)})$$
(79)

But

$$2v - j - \frac{v}{e}(2e - f_j) = \frac{vf_j}{e} - j < 0$$
(80)

so each term is o(1) and hence $\Delta = o(1)$. By Janson's Inequality

$$\lim_{n \to \infty} \Pr[\wedge \overline{B}_{\alpha}] = \lim_{n \to \infty} M = exp[-c^e/a]$$
(81)

completing the proof.

The fine threshold behavior for the appearance of an arbitrary graph H has been worked out but it can get quite complicated.

1.9 Some Very Low Probabilities

Let A be the property that G does not contain K_4 and consider $\Pr[G(n,p) \models A]$ as p varies. (Results with K_4 replaced by an arbitrary H are discussed at the end of this section.) We know that $p = n^{-2/3}$ is a threshold function so that for $p \gg n^{-2/3}$ this probability is o(1). Here we want to estimate that probability. Our estimates here will be quite rough, only up to a o(1) additive factor in the hyperexponent, though with more care the bounds differ by "only" a constant factor in the exponent. If we were to consider all potential K_4 as giving mutually independent events then we would be led to the estimate $(1-p^6)^{\binom{n}{4}} = e^{-n^{4+o(1)}p^6}$. For p appropriately small this turns out to be correct. But for, say, $p = \frac{1}{2}$ it would give the estimate $e^{-n^{4+o(1)}}$. This must, however, be way off the mark since with probability $2^{-\binom{n}{2}} = e^{-n^{2+o(1)}}$ the graph G could be empty and hence trivially satisfy A.

Rather than giving the full generality we assume $p = n^{-\alpha}$ with $\frac{2}{3} > \alpha > 0$. The result is:

$$\Pr[G(n,p) \models A] = e^{-n^{4-6\alpha+o(1)}}$$
(82)

for $\frac{2}{3} > \alpha \ge \frac{2}{5}$ and

$$\Pr[G(n,p) \models A] = e^{-n^{2-\alpha+o(1)}}$$
(83)

for $\frac{2}{5} \ge \alpha > 0$.

The upper bound follows from the inequality

$$\Pr[G(n,p) \models A] \ge \max\left[(1-p^6)^{\binom{n}{4}}, (1-p)^{\binom{n}{2}} \right]$$
(84)

This is actually two inequalities. The first comes from the probability of G not containing a K_4 being at most the probability as if all the potential K_4 were independent. The second is the same bound on the probability that G doesn't contain a K_2 - i.e., that G has no edges. Calculation shows that the "turnover" point for the two inequalities occurs when $p = n^{-2/5+o(1)}$.

The upper bound follows from the Janson inequalities. For each four set α of vertices B_{α} is that that 4-set gives a K_4 and we want $\Pr[\wedge \overline{B_{\alpha}}]$. We have $\mu = \Theta(n^4 p^6)$ and $-\ln M \sim \mu$ and (as shown earlier) $\Delta = \Theta(\mu \Delta^*)$ with $\Delta^* = \Theta(n^2 p^5 + np^3)$. With $p = n^{-\alpha}$ and $\frac{2}{3} > \alpha > \frac{2}{5}$ we have $\Delta^* = o(1)$ so that

$$\Pr[\wedge \overline{B_{\alpha}}] < e^{-\mu(1+o(1))} = e^{-n^{4-6\alpha+o(1)}}$$

When $\frac{2}{5} > \alpha > 0$ then $\Delta^* = \Theta(n^2 p^5)$ (somewhat surprisingly the np^3 never is significant in these calculations) and the extended Janson inequality gives

$$\Pr[\wedge \overline{B_{\alpha}}] \le e^{-\Theta(\mu^2/\Delta)} = e^{-\Theta(\mu/\Delta^*)} = e^{-n^{2-\alpha}}$$

The general result has been found by T. Luczak, A. Rucinski and S. Janson (1990). Let H be any fixed graph and let A be the property of not containing a copy of H. For any subgraph H' of H the correlation inequality gives

$$\Pr[G(n,p) \models A] \le e^{-E[X_{H'}]} \tag{85}$$

where $X_{H'}$ is the number of copies of H' in G. Now let $p = n^{-\alpha}$ where we restrict to those α for which p is past the threshold function for the appearance of H. Then

$$\Pr[G(n,p) \models A] = e^{n^{o(1)}} \min_{H'} e^{-E[X_{H'}]}$$
(86)

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