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**Hall-MHD and applications (part II)**

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# Hall – MHD

## *and applications (part II)*

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# Hall-MHD equations

- The dimensionless version, for a length scale  $L_0$ , density  $n_0$  and Alfvén speed  $V_A = B_0 / \sqrt{4\pi m_i n_0}$

$$\frac{d\vec{U}}{dt} = \frac{1}{\varepsilon} (\vec{E} + \vec{U} \times \vec{B}) - \frac{\beta}{n} \vec{\nabla} p_i - \frac{\eta}{\varepsilon n} \vec{J} + \nu \nabla^2 \vec{U} \quad \nu = \frac{\mu}{m_i n V_A L_0}$$

$$0 = -\frac{1}{\varepsilon} (\vec{E} + \vec{U}_e \times \vec{B}) - \frac{\beta}{n} \vec{\nabla} p_e + \frac{\eta}{\varepsilon n} \vec{J} \quad \text{where} \quad \vec{J} = \vec{\nabla} \times \vec{B} = \frac{n}{\varepsilon} (\vec{U} - \vec{U}_e)$$

- We define the Hall parameter  $\varepsilon = \frac{c}{\omega_{pi} L_0}$

as well as the plasma beta  $\beta = \frac{\rho_0}{m_i n_0 V_A^2}$  and the electric resistivity  $\eta = \frac{c^2 \nu_{ie}}{\omega_{pi}^2 L_0 V_A}$

- Adding these two equations yields:

$$n \frac{d\vec{U}}{dt} = (\vec{\nabla} \times \vec{B}) \times \vec{B} - \beta \vec{\nabla} (p_i + p_e) + \nu \nabla^2 \vec{U}$$

- On the other hand, using

$$\left. \begin{aligned} \vec{E} &= -\frac{1}{c} \frac{\partial \vec{A}}{\partial t} - \vec{\nabla} \phi \\ \vec{B} &= \vec{\nabla} \times \vec{A} \end{aligned} \right\} \rightarrow \frac{\partial \vec{A}}{\partial t} = (\vec{U} - \frac{\varepsilon}{n} \vec{\nabla} \times \vec{B}) \times \vec{B} - \vec{\nabla} \phi + \frac{\varepsilon \beta}{n} \vec{\nabla} p_e - \frac{\eta}{n} \vec{\nabla} \times \vec{B}$$

Hall-MHD  
equations



# Hall MHD in a strong field

- The RHMHD equations are (Gomez, Dmitruk & Mahajan 2008):

$$\begin{aligned}
 \partial_t a &= \partial_z(\varphi - \varepsilon b) + [\varphi - \varepsilon b, a] & + \eta \nabla_\perp^2 a \\
 \partial_t \omega &= \partial_z j & + [\varphi, \omega] - [a, j] & + \nu \nabla_\perp^2 \omega \\
 \partial_t b &= \partial_z(u - \varepsilon j) + [\varphi, b] + [u - \varepsilon j, a] & + \eta \nabla_\perp^2 b \\
 \partial_t u &= \partial_z b & + [\varphi, u] - [a, b] & + \nu \nabla_\perp^2 u
 \end{aligned}$$

where

$$\begin{aligned}
 \vec{B} &= \hat{z} + \vec{\nabla} \times (a \hat{z} + g \hat{x}) = [a_y, -a_x, 1 + b] & , & & b = -g_y \\
 \vec{U} &= \vec{\nabla} \psi + \vec{\nabla} \times (\varphi \hat{z} + f \hat{x}) = [\varphi_y + \psi_x, -\varphi_x + \psi_y, u + \psi_z] & , & & u = -f_y
 \end{aligned}$$

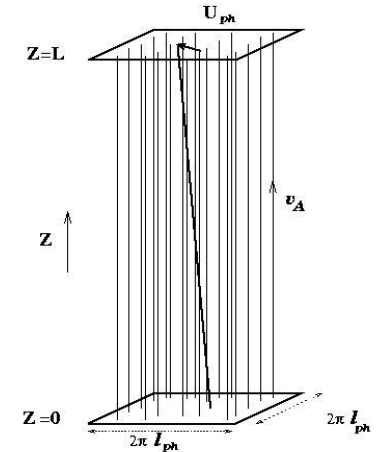
- These are the RHMHD equations. Their ideal invariants (just as for 3D HMHD) are:

$$\begin{aligned}
 E &= \frac{1}{2} \int d^3 r (|\vec{U}|^2 + |\vec{B}|^2) = \frac{1}{2} \int d^3 r (|\vec{\nabla}_\perp \varphi|^2 + |\vec{\nabla}_\perp a|^2 + u^2 + b^2) \\
 H_m &= \frac{1}{2} \int d^3 r (\vec{A} \cdot \vec{B}) = \int d^3 r a b \\
 H_h &= \frac{1}{2} \int d^3 r (\vec{A} + \varepsilon \vec{U}) \cdot (\vec{B} + \varepsilon \vec{\Omega}) = \int d^3 r (ab + \varepsilon(a\omega + ub) + \varepsilon^2 u\omega)
 \end{aligned}$$

energy

magnetic helicity

hybrid helicity





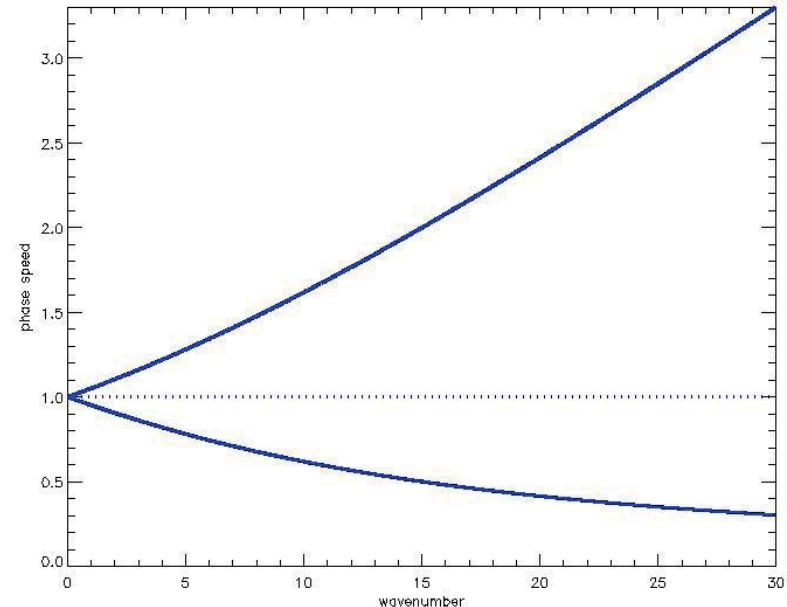
# Linear modes of the RHMHD equations

- Retaining the linear terms in the RHMHD eqs we obtain the following dispersion relationship

$$\omega^4 - 2k_z^2 \left(1 + \frac{(\varepsilon k_\perp)^2}{2}\right) \omega^2 + k_z^4 = 0$$

which displays the following (dispersive) modes

$$\omega_\pm = \sqrt{k_z^2 + \left(\frac{\varepsilon k_\perp k_z}{2}\right)^2} \pm \frac{\varepsilon k_\perp k_z}{2}$$



- The positive branch corresponds to (right hand, circularly polarized) *whistlers*, while the negative branch are (left hand polarized) *ion-cyclotron* waves.
- The phase speed for *whistlers* grows like  $\mathcal{C}_+ \approx \varepsilon k_\perp$  thus forcing to a very small dt for numerical convergence.
- Ion-cyclotron* waves, instead, display a decreasing phase speed like  $\mathcal{C}_- \approx 1 / \varepsilon k_\perp$ , which makes them good candidates for *resonant particle acceleration*.



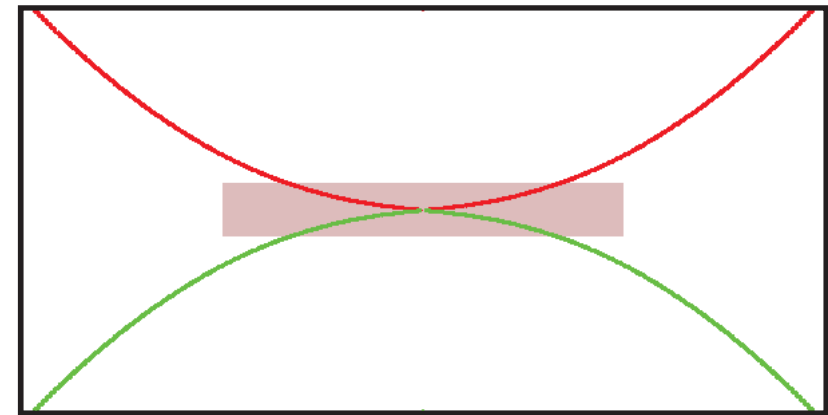
# Hall-MHD reconnection in 2.5D

- Hall reconnection has extensively been studied for the Earth's magnetopause and also the magnetotail. The Hall effect is expected to increase the reconnection rate.
- The simplest geometrical setup is 2.5D, for which the velocity and magnetic field can be written in terms of four scalar fields (Gómez 2006, Space Sci. Rev. 122, 231; Gómez et al. 2006, Adv. Sp. Res. 37, 1287)

$$\vec{B}(x, y, t) = \vec{\nabla} \times [\hat{z} a(x, y, t)] + \hat{z} b(x, y, t)$$

$$\vec{U}(x, y, t) = \vec{\nabla} \times [\hat{z} \phi(x, y, t)] + \hat{z} u(x, y, t)$$

$$\vec{U}_\perp = \vec{U} - \varepsilon \vec{J} = \vec{\nabla} \times [\hat{z}(\phi - \varepsilon b)] + \hat{z}(u - \varepsilon j)$$



- The 2.5D Hall-MHD equations are

$$\partial_t a = [\phi - \varepsilon b, a] + \eta \nabla^2 a$$

$$\partial_t \omega = [\phi, \omega] + [j, a] + \nu \nabla^2 \omega$$

$$\partial_t b = [\phi, b] + [u - \varepsilon j, a] + \eta \nabla^2 b$$

$$\partial_t u = [b, a] + [\phi, u] + \nu \nabla^2 u$$

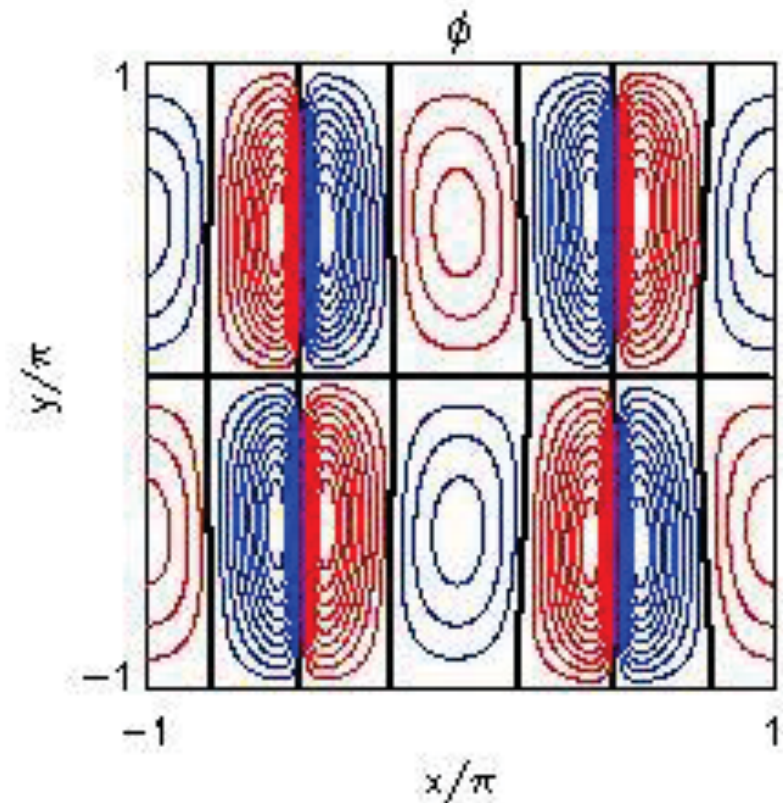
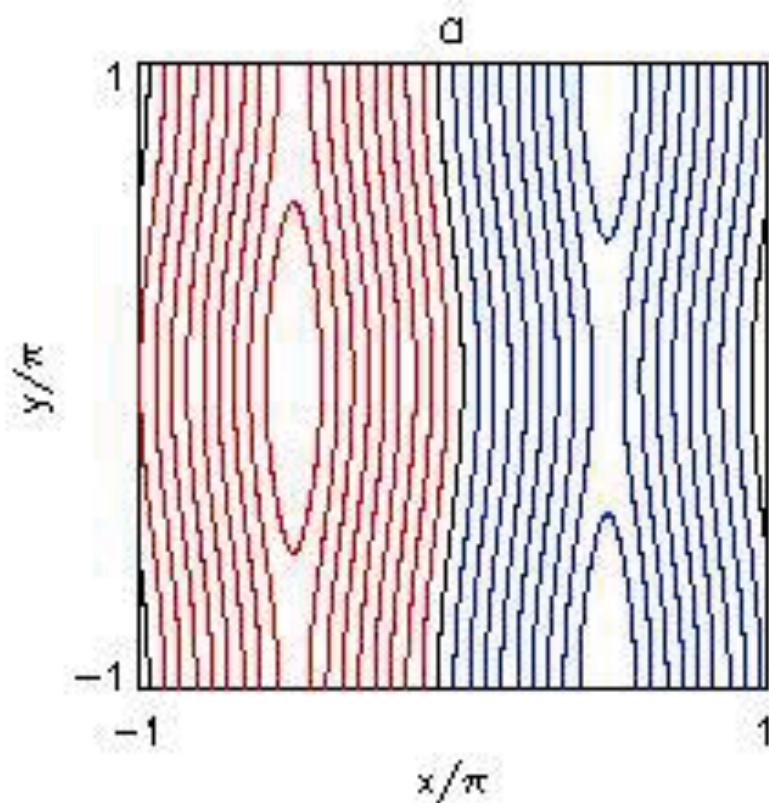
where  $\omega = -\nabla^2 \phi$  ,  $j = -\nabla^2 a$

- In the absence of Hall, the parallel components (u,b) have no influence on the perp. dynamics.
- When Hall is present, the parallel components will be turned on and couple to the perp. components.





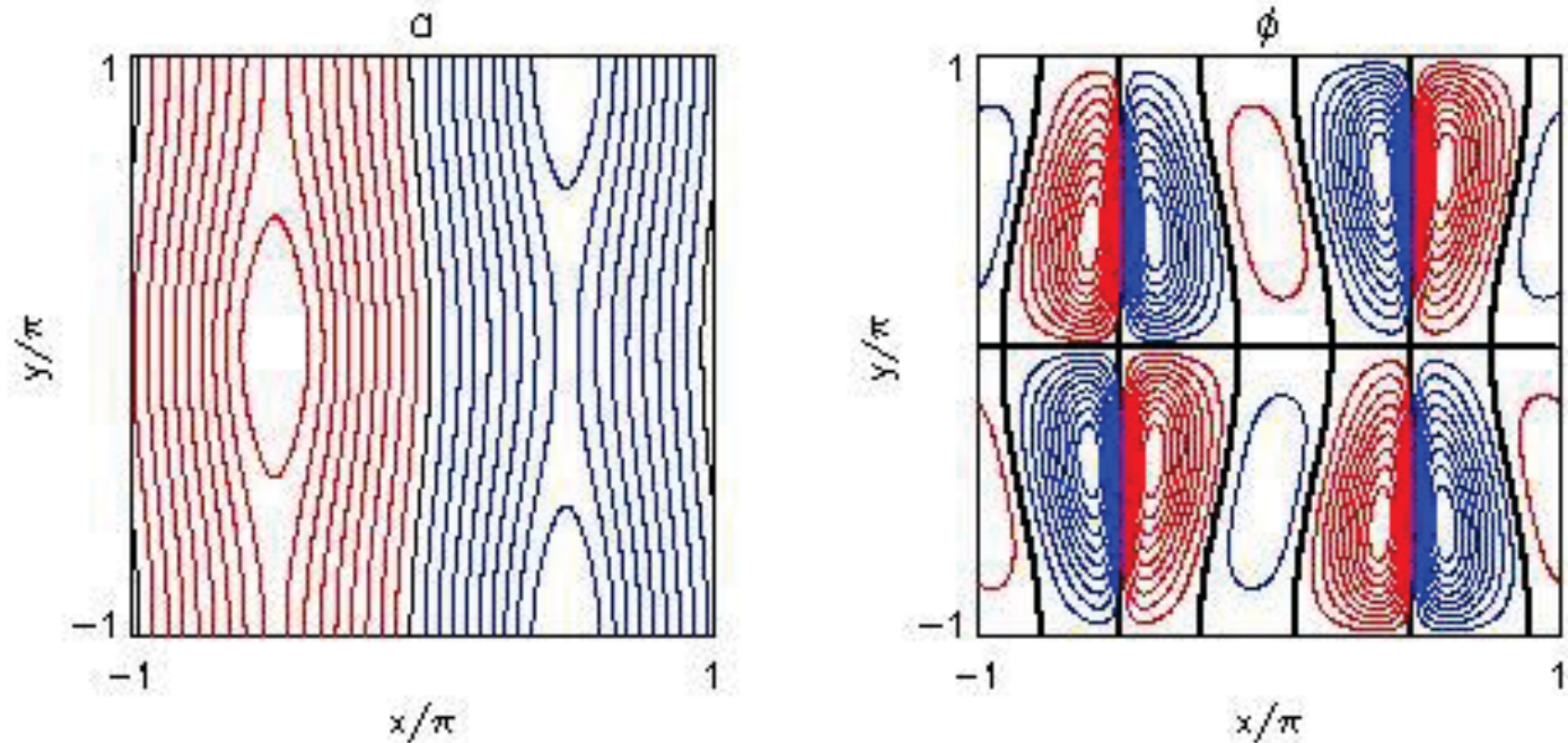
# Hall-MHD reconnection in 2D



- When the Hall effect is neglected (pure MHD) **2D** reconnection is possible.
- Magnetic **fieldlines** (left) and flow **streamlines** (right) are shown at three successive Alfvén times. **Blue** contours are **positive** and the **red** ones are **negative**.



# Hall-MHD reconnection in 2D

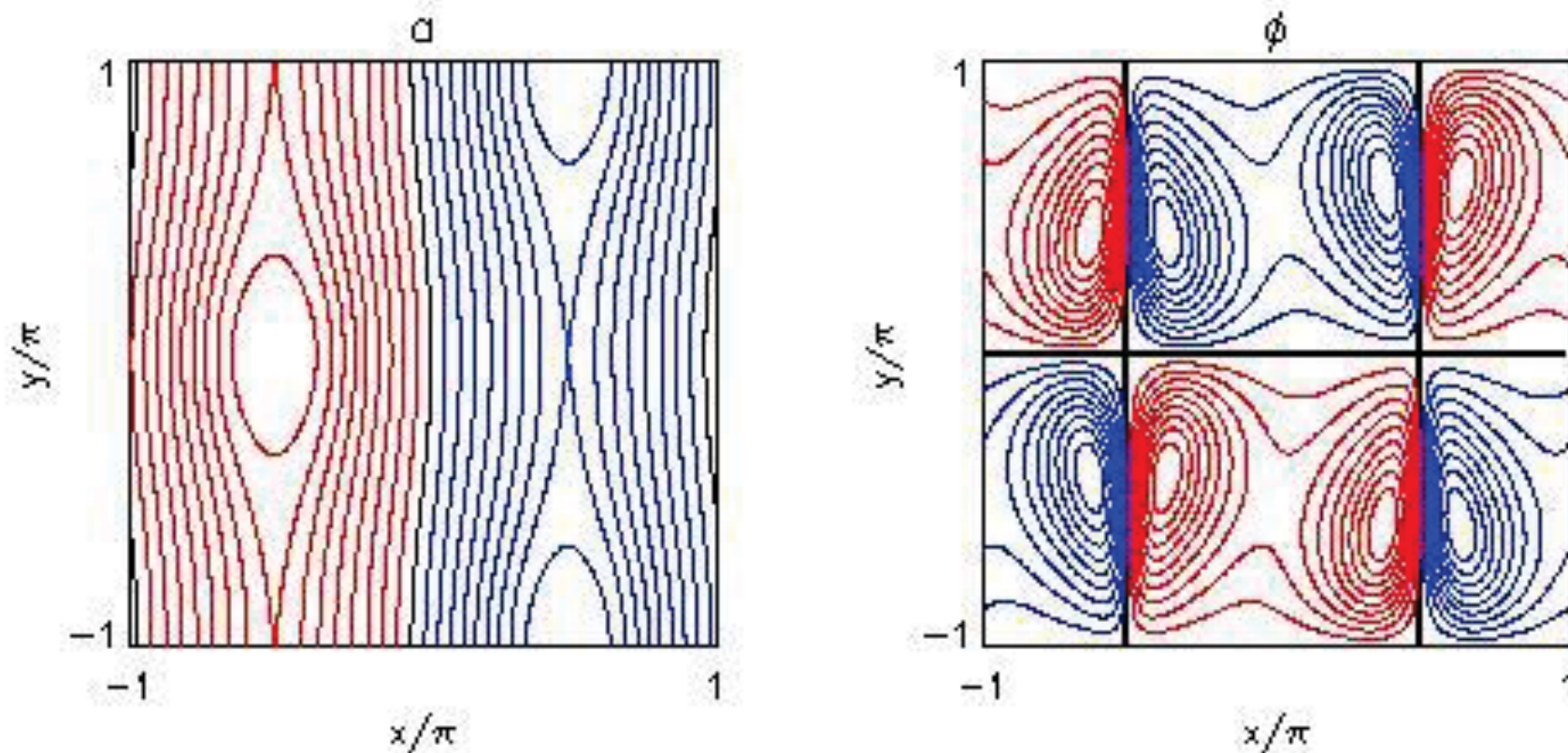


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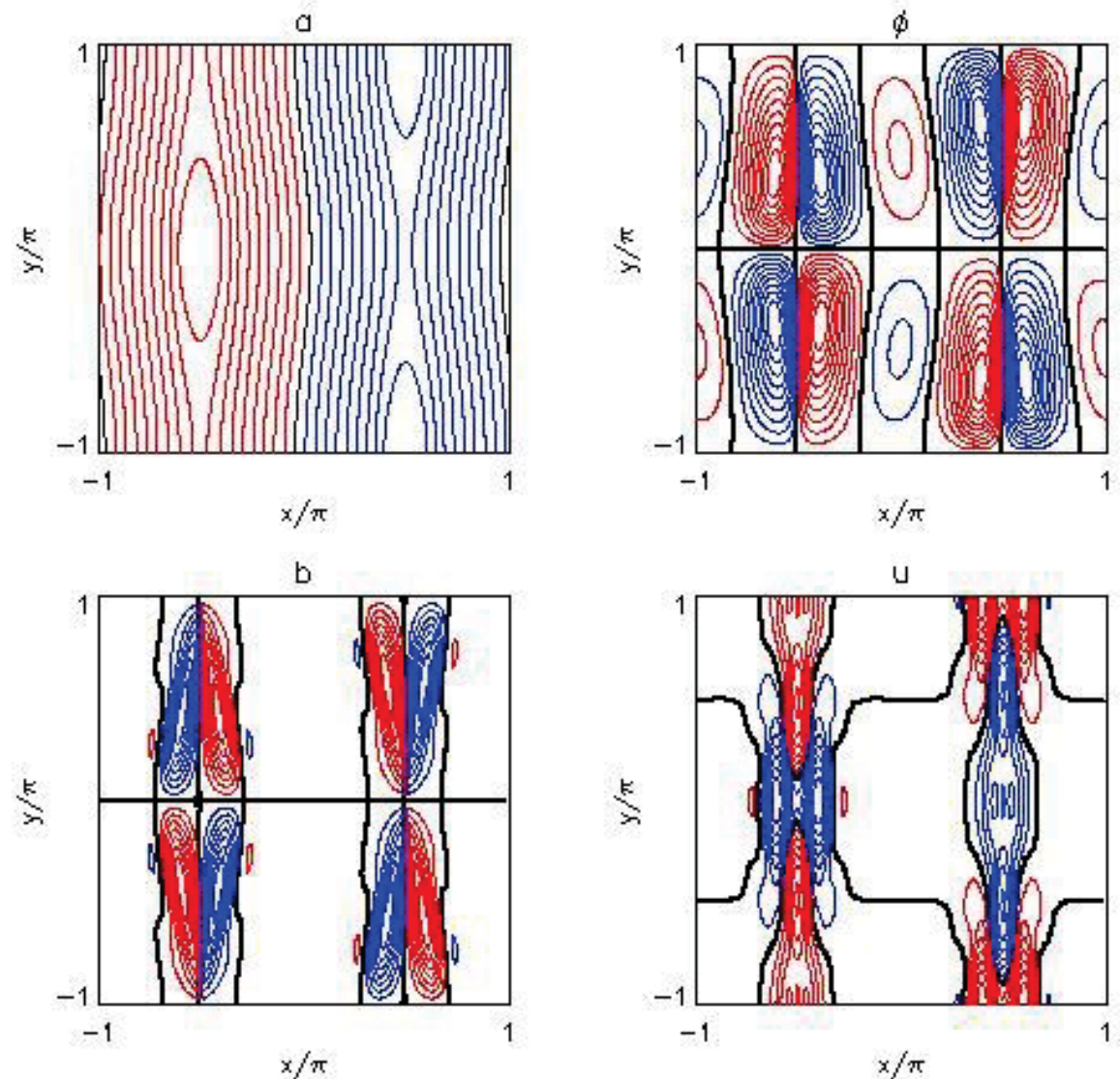


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# Hall-MHD reconnection in 2.5D

- When the Hall effect is considered, the out-of-plane fields are generated. They were initially set to zero.
- We show contour plots of the four scalar fields at three successive Alfvén times for  $\varepsilon = 0.07$
- The out-of-plane magnetic field develops a quadrupolar pattern, while the velocity field develops a net flow at the reconnection region.
- **Blue** contours are **positive** and the **red** ones are **negative**.

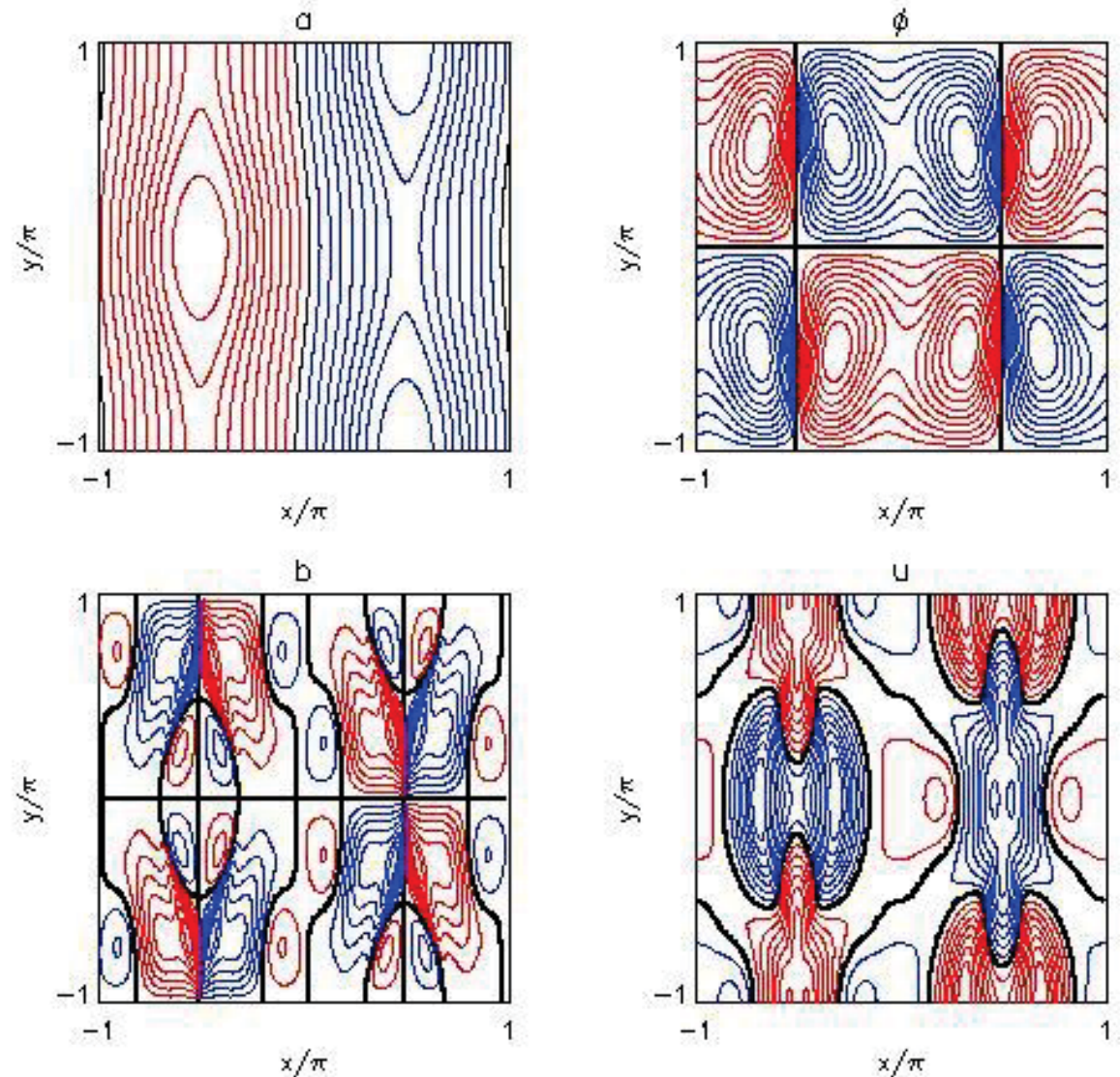






# Hall-MHD reconnection in 2.5D

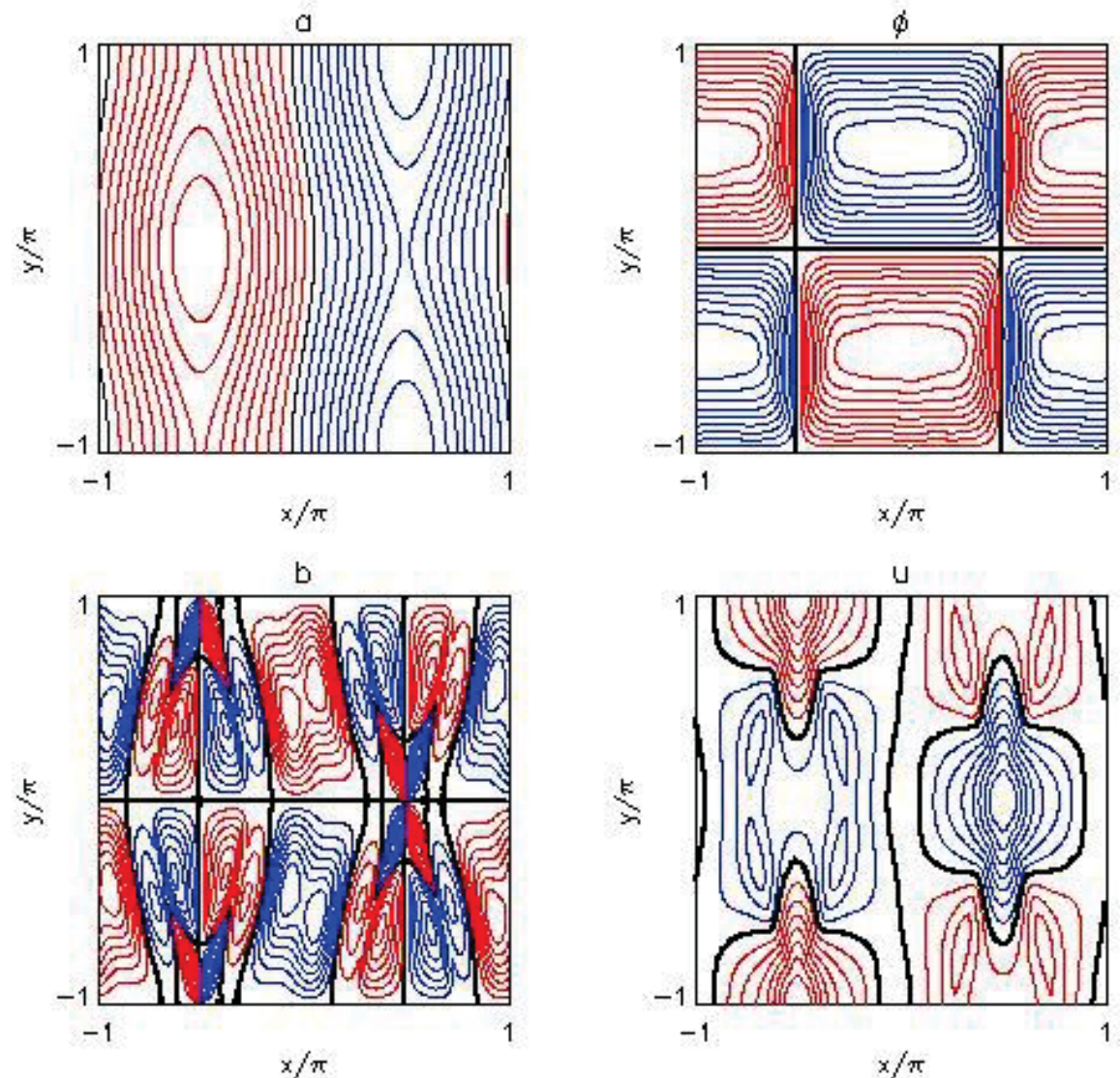
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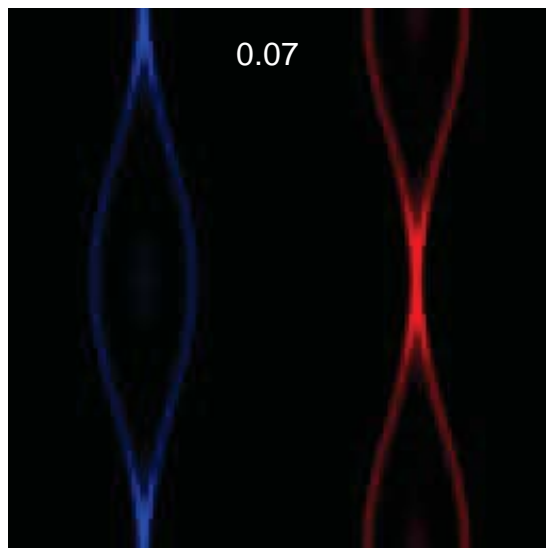
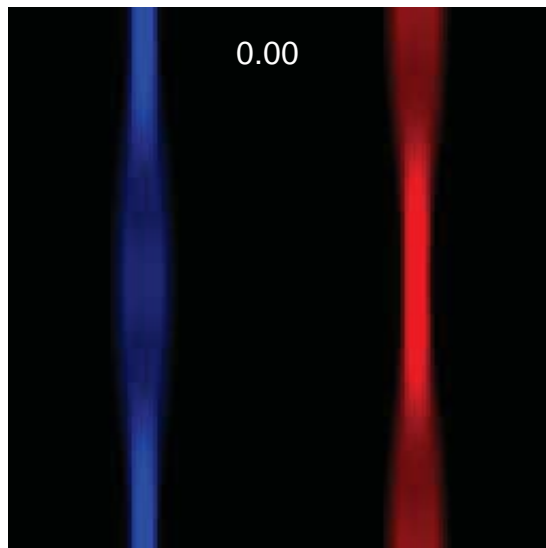
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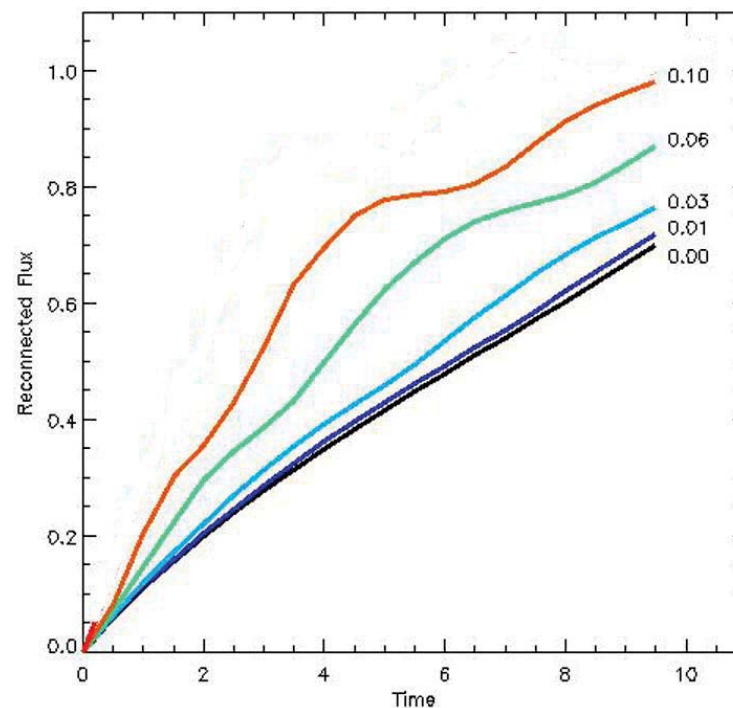




# Hall-MHD reconnection rates



- The out-of-plane **current density** is shown for the cases  $\varepsilon = 0.00$  and  $0.07$
- The current sheets become narrower and smaller as the Hall parameter is increased.
- The **reconnected flux** also increases with the Hall parameter, confirming previous results from collisionless and also Hall-MHD simulations.
- The plot shows reconnected flux vs. time for different values of the Hall parameter.

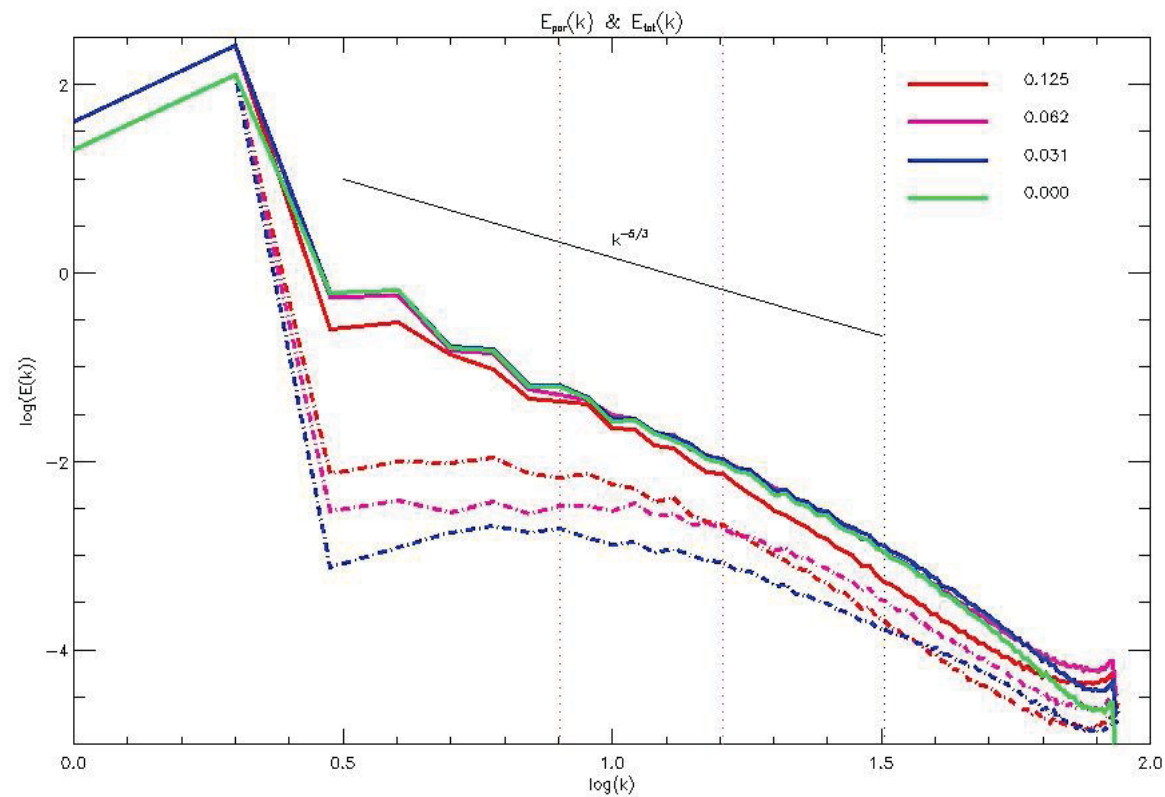






# Energy spectra

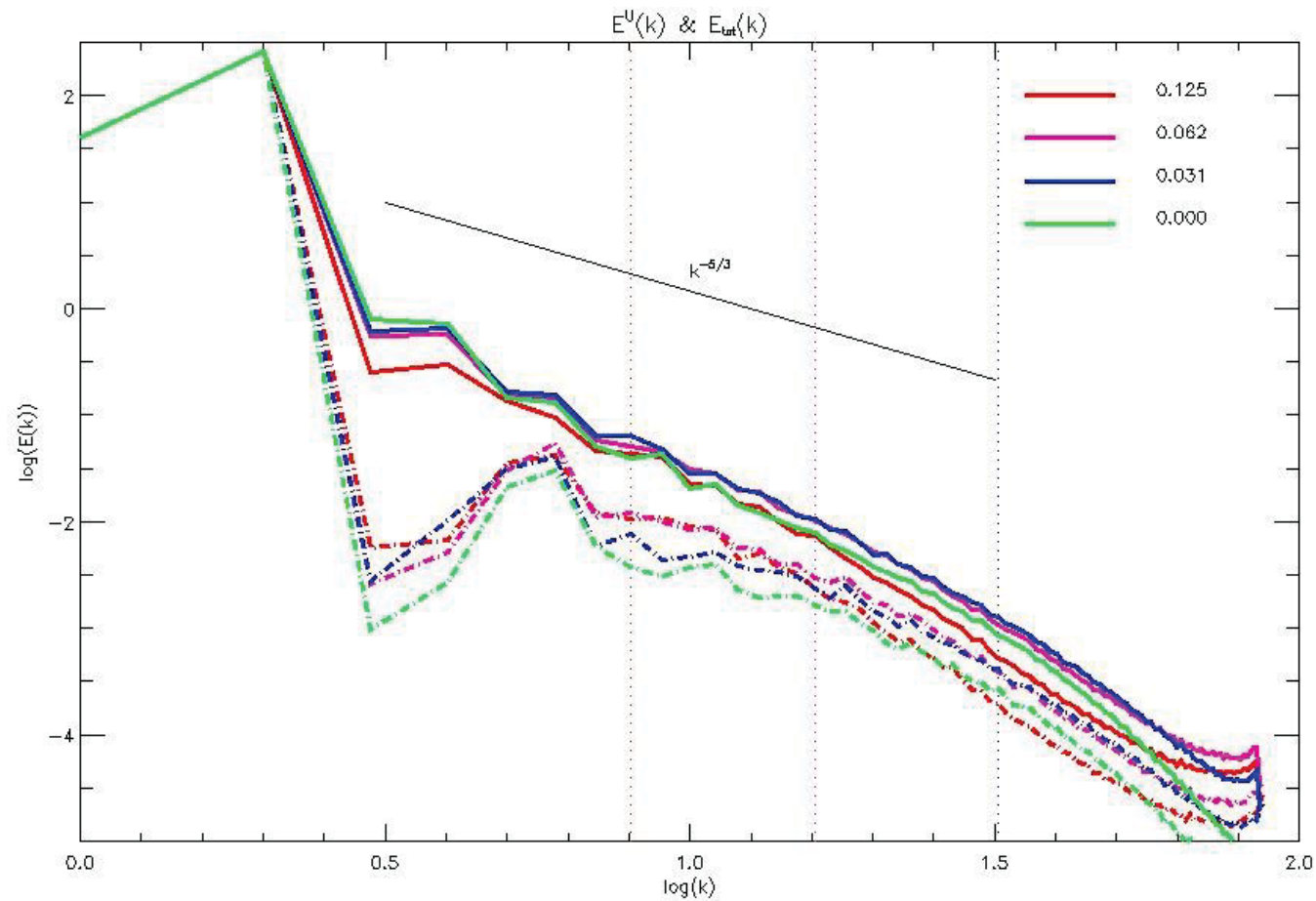
- We also computed energy power spectra for different values of the Hall parameter  $\mathcal{E}$ .
- The Kolmogorov slope  $k^{-5/3}$  is also displayed for reference.
- The dotted curves correspond to the parallel energy spectra.
- The vertical dotted lines indicate the location of the Hall scale  $k_{\mathcal{E}} \cong 1/\mathcal{E}$  for each run.





# Energy spectra

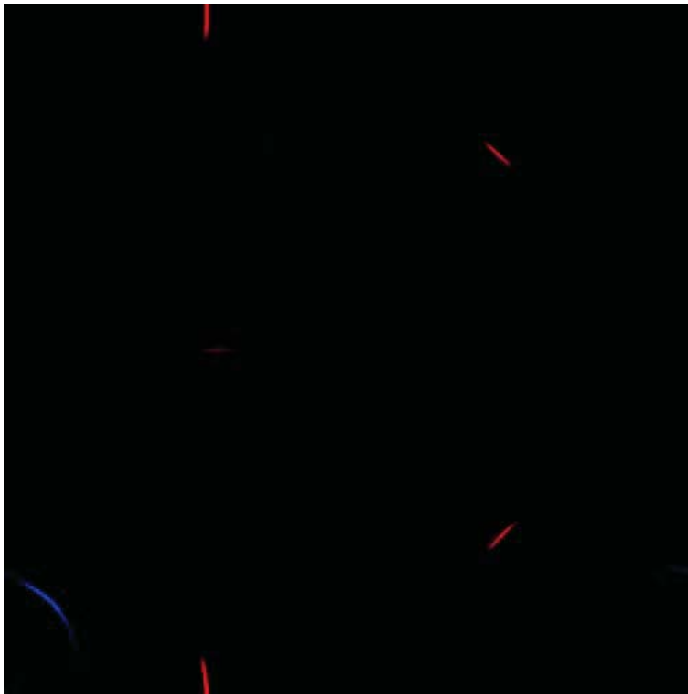
- Energy power spectra for different values of  $\varepsilon$ .
- The dotted curves are the spectra for kinetic energy.



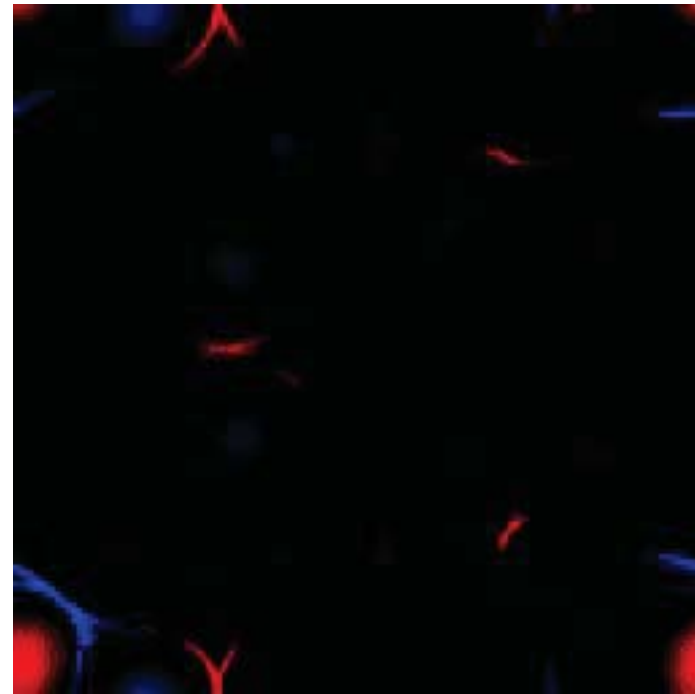


# Current sheets in RHMHD

- Energy dissipation concentrates on very small structures known as current sheets, in which current density flows almost parallel to  $z$ .
- The picture shows **positive** and **negative** current density in a transverse cut at  $z = \frac{1}{2}$ , for pure RMHD (i.e.  $\varepsilon = 0$ ).
- When the Hall effect is considered, current sheets display the typical Petschek-like structure.



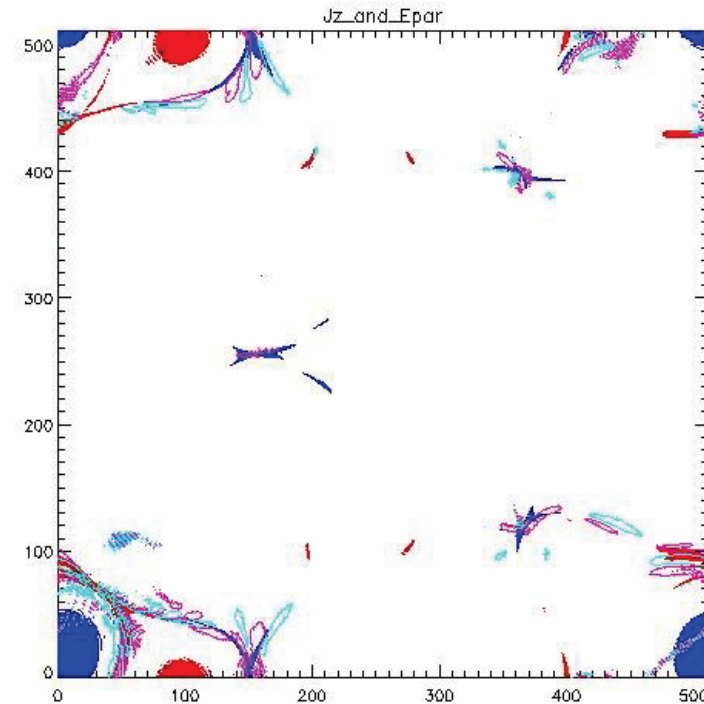
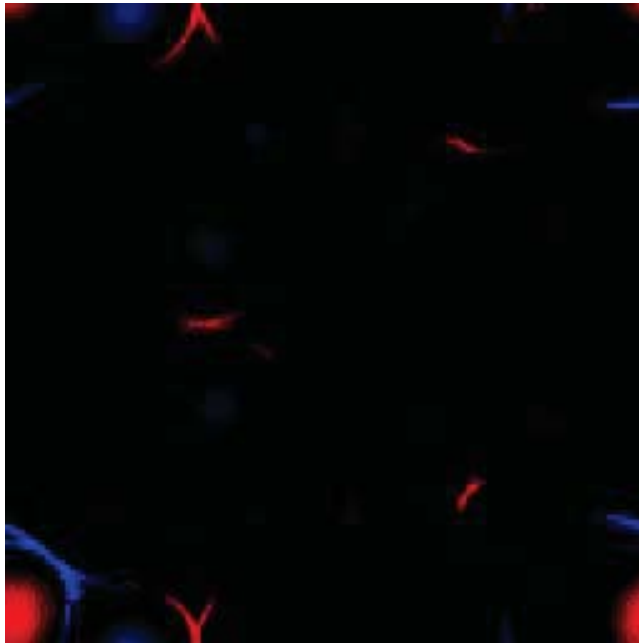
$\varepsilon = 0.0$



$\varepsilon = 0.1$



# Parallel electric field



- One of the important new features of the Hall effect, is the presence of a parallel electric field, i.e.  $E_{//} = \frac{\vec{E} \cdot \vec{B}}{|\vec{B}|}$
- To order  $\alpha^2$  it can be computed as  $E_{//} = \varepsilon (\partial_z b - [a, b])$   
and of course it can potentially accelerate particles along magnetic field lines.
- Current density is displayed in **red** and **blue**, while contours coloured in **light blue** and **pink** correspond to the parallel electric field.



## ... back to multi-species plasmas

- For each species **s** we have (Goldston & Rutherford 1995):

- Mass conservation 
$$\frac{\partial n_s}{\partial t} + \vec{\nabla} \cdot (n_s \vec{U}_s) = 0$$
- Equation of motion 
$$m_s n_s \frac{d\vec{U}_s}{dt} = q_s n_s (\vec{E} + \frac{1}{c} \vec{U}_s \times \vec{B}) - \vec{\nabla} p_s + \vec{\nabla} \cdot \vec{\sigma}_s + \sum_{s'} \vec{R}_{ss'}$$
- Momentum exchange rate 
$$\vec{R}_{ss'} = -m_s n_s \nu_{ss'} (\vec{U}_s - \vec{U}_{s'})$$

- These moving charges act as sources for electric and magnetic fields:

- Charge density 
$$\rho_c = \sum_s q_s n_s \approx 0$$
- Electric current density 
$$\vec{J} = \frac{c}{4\pi} \vec{\nabla} \times \vec{B} = \sum_s q_s n_s \vec{U}_s$$





# Two-fluid MHD equations

● Let us now retain electron inertia (i.e.  $0 < m_e \ll m_i$ ):

○ Mass conservation: 
$$0 = \frac{\partial n}{\partial t} + \vec{\nabla} \cdot (n \vec{U}) \quad , \quad n_e \cong n_i \cong n$$

○ Ions: 
$$m_i n \frac{d\vec{U}}{dt} = en \left( \vec{E} + \frac{1}{c} \vec{U} \times \vec{B} \right) - \vec{\nabla} p_i + \vec{R}$$

○ Electrons: 
$$m_e n \frac{d\vec{U}_e}{dt} = -en \left( \vec{E} + \frac{1}{c} \vec{U}_e \times \vec{B} \right) - \vec{\nabla} p_e - \vec{R}$$

○ Friction force: 
$$\vec{R} = -m_i n \nu_{ie} (\vec{U} - \vec{U}_e)$$

○ Ampere's law: 
$$\vec{J} = \frac{c}{4\pi} \vec{\nabla} \times \vec{B} = en (\vec{U} - \vec{U}_e) \quad \Rightarrow \quad \vec{R} = -\frac{m \nu_{ie}}{e} \vec{J}$$

○ Polytropic laws: 
$$p_i \propto n^\gamma \quad , \quad p_e \propto n^\gamma$$



# Retaining electron inertia: EHMHD equations

- The dimensionless version, for a length scale  $L_0$ , density  $n_0$  and Alfvén speed  $V_A = B_0 / \sqrt{4\pi m_i n_0}$

$$\frac{d\vec{U}_i}{dt} = \frac{1}{\varepsilon} (\vec{E} + \vec{U}_i \times \vec{B}) - \frac{\beta}{n} \vec{\nabla} p_i - \frac{\eta}{\varepsilon n} \vec{J}$$

$$\frac{m_e}{m_i} \frac{d\vec{U}_e}{dt} = -\frac{1}{\varepsilon} (\vec{E} + \vec{U}_e \times \vec{B}) - \frac{\beta}{n} \vec{\nabla} p_e + \frac{\eta}{\varepsilon n} \vec{J} \quad \text{where} \quad \vec{J} = \vec{\nabla} \times \vec{B} = \frac{n}{\varepsilon} (\vec{U}_i - \vec{U}_e)$$

- We defined the Hall parameter  $\varepsilon = \frac{c}{\omega_{pi} L_0}$

as well as the plasma beta  $\beta = \frac{\rho_0}{m_i n_0 V_A^2}$

and the electric resistivity  $\eta = \frac{c^2 \nu_{ie}}{\omega_{pi}^2 L_0 V_A}$

- Adding these two equations yields:

$$n \frac{d\vec{U}}{dt} = (\vec{\nabla} \times \vec{B}) \times \vec{B} - \beta \vec{\nabla} p$$

where  $\vec{U} = \frac{m_i \vec{U}_i + m_e \vec{U}_e}{m_i + m_e}$

and  $p = p_i + p_e$



# Retaining electron inertia: EIMHD equations

- In the equation for electrons (assuming incompressibility)

$$\frac{m_e}{m_i} \frac{d\vec{U}_e}{dt} = -\frac{1}{\varepsilon} (\vec{E} + \vec{U}_e \times \vec{B}) - \beta_e \vec{\nabla} p_e + \frac{\eta}{\varepsilon} \vec{J} \quad \vec{J} = \vec{\nabla} \times \vec{B} = \frac{1}{\varepsilon} (\vec{U}_i - \vec{U}_e)$$

we replace  $\vec{E} = -\frac{1}{c} \frac{\partial \vec{A}}{\partial t} - \vec{\nabla} \phi$  and  $\vec{B} = \vec{\nabla} \times \vec{A}$

to obtain

$$\frac{\partial}{\partial t} (\vec{A} - \varepsilon_e^2 \nabla^2 \vec{A} - \frac{\varepsilon_e^2}{\varepsilon} \vec{U}) = (\vec{U} - \varepsilon \vec{J}) \times (\vec{B} - \varepsilon_e^2 \nabla^2 \vec{B} - \frac{\varepsilon_e^2}{\varepsilon} \vec{U}) - \vec{\nabla} (\phi - \varepsilon \beta_e p_e - \frac{\varepsilon_e^2}{\varepsilon} \frac{U_e^2}{2}) + \eta \nabla^2 \vec{A}$$

- Electron inertia is quantified by the dimensionless parameter  $\varepsilon_e = \sqrt{\frac{m_e}{m_i}} \varepsilon = \frac{c}{\omega_{pe} L_0}$

- Just as the Hall effect introduces the new spatial scale  $k_H = \frac{1}{\varepsilon}$  (the ion skin depth), electron inertia introduces the electron skin depth  $k_e = \frac{1}{\varepsilon_e}$  which satisfies

$$k_e = \sqrt{\frac{m_i}{m_e}} k_H \gg k_H$$



# EIHMHD in 2.5D

- We now express the EIHMHD equations in 2.5D geometry. I.e. for simplicity we assume  $\partial_z = 0$  and therefore

$$\vec{B} = \vec{\nabla} \times [\hat{z} a(x, y, t)] + \hat{z} b(x, y, t)$$

$$\vec{U} = \vec{\nabla} \times [\hat{z} \varphi(x, y, t)] + \hat{z} u(x, y, t)$$

- The equations for these four scalar fields are

$$\begin{aligned} \partial_t a' &= [\varphi - \varepsilon b, a'] + \eta \nabla_{\perp}^2 a \\ \partial_t \omega &= [\varphi, \omega] - [a, j] + \nu \nabla_{\perp}^2 \omega \\ \partial_t b' &= [\varphi - \varepsilon b, b'] + [u - \varepsilon j, a'] + \eta \nabla_{\perp}^2 b \\ \partial_t u &= [\varphi, u] - [a, b] + \nu \nabla_{\perp}^2 u \end{aligned}$$

where

$$a' = (1 - \varepsilon_e^2 \nabla_{\perp}^2) a - \frac{\varepsilon_e^2}{\varepsilon} u \quad \text{and} \quad b' = (1 - \varepsilon_e^2 \nabla_{\perp}^2) b - \frac{\varepsilon_e^2}{\varepsilon} w$$

# Normal modes in EIHMHD

- If we linearize our equations around an equilibrium characterized by a uniform magnetic field, we obtain the following dispersion relation:

$$\left( \frac{\omega}{\vec{k} \cdot \vec{B}_0} \right)^2 \pm \frac{k\varepsilon}{1 + \varepsilon_e^2 k^2} \left( \frac{\omega}{\vec{k} \cdot \vec{B}_0} \right) - \frac{1}{1 + \varepsilon_e^2 k^2} = 0$$

- Asymptotically, at very large  $k$ , we have two branches

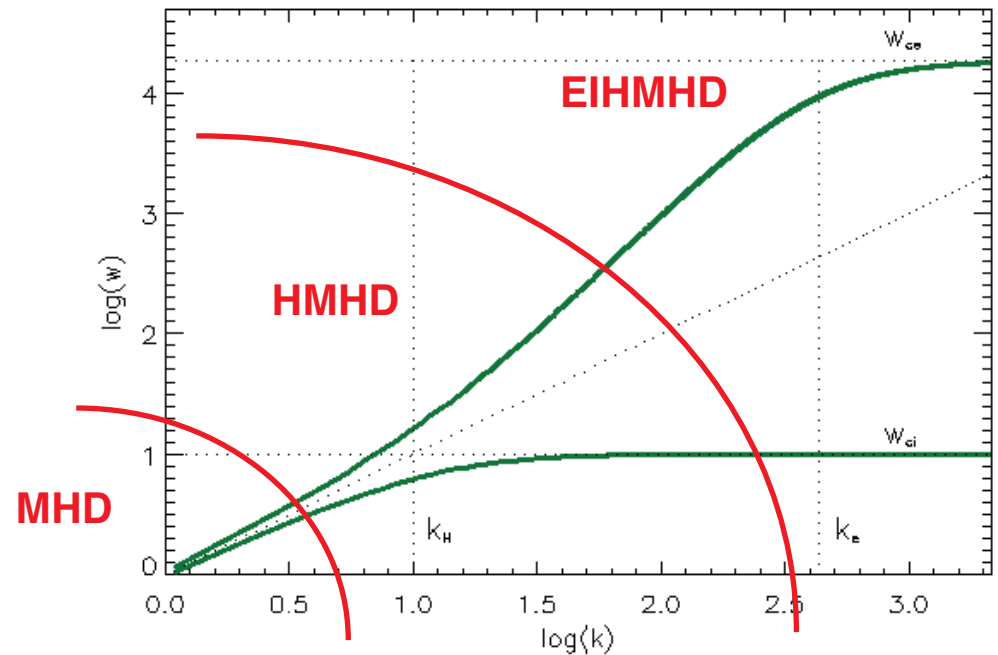
$$\omega \xrightarrow{k \rightarrow \infty} \omega_{ce} \cos \theta$$

$$\omega \xrightarrow{k \rightarrow \infty} \omega_{ci} \cos \theta$$

while for very small  $k$ , both branches simply become Alfvén modes, i.e.

$$\omega \xrightarrow{k \rightarrow 0} k \cos \theta$$

- Different approximations, just as one-fluid MHD, Hall-MHD and electron-inertia HMHD can clearly be identified in this diagram.







# Ideal invariants in EIH MHD

- For each species  $s$  in the incompressible and ideal limit

$$m_s n_s (\partial_t \vec{U}_s - \vec{U}_s \times \vec{W}_s) = q_s n_s (\vec{E} + \frac{1}{c} \vec{U}_s \times \vec{B}) - \vec{\nabla} (p_s + m_s n_s \frac{U_s^2}{2})$$

- Using that  $\vec{J} = \frac{c}{4\pi} \vec{\nabla} \times \vec{B} = \sum_s q_s n_s \vec{U}_s$  and  $E = -\frac{1}{c} \partial_t \vec{A} - \vec{\nabla} \phi$

we can readily show that energy is an ideal invariant, where

$$E = \int d^3 r \left( \sum_s m_s n_s \frac{U_s^2}{2} + \frac{B^2}{8\pi} \right)$$

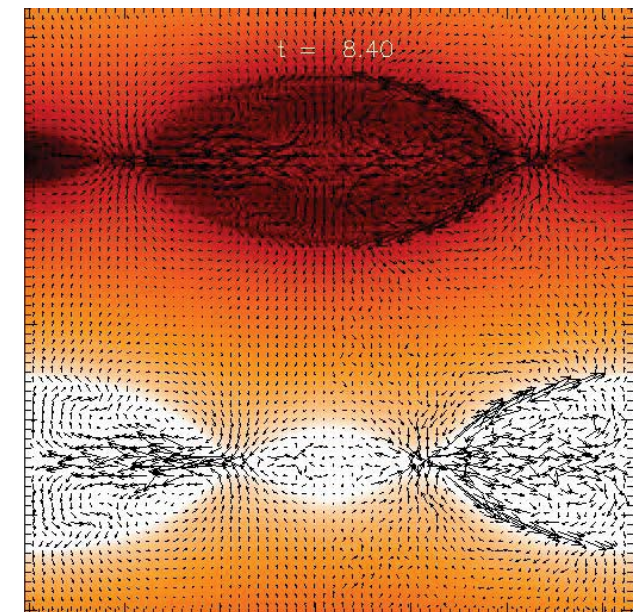
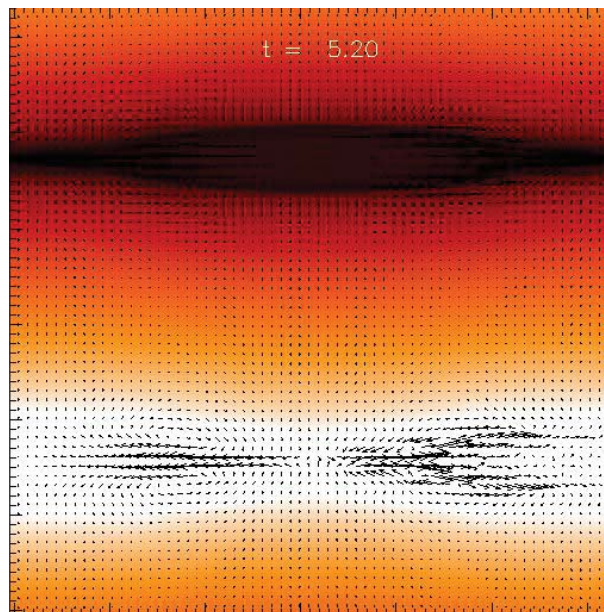
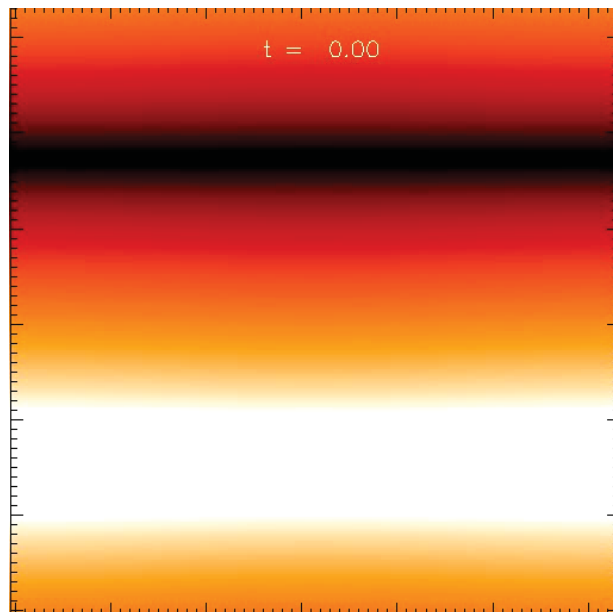
- We also have a helicity per species which is conserved, where

$$H_s = \int d^3 r \left( \vec{A} + \frac{cm_s}{q_s} \vec{U}_s \right) \cdot \left( \vec{B} + \frac{cm_s}{q_s} \vec{W}_s \right)$$



# EIHMHD simulations

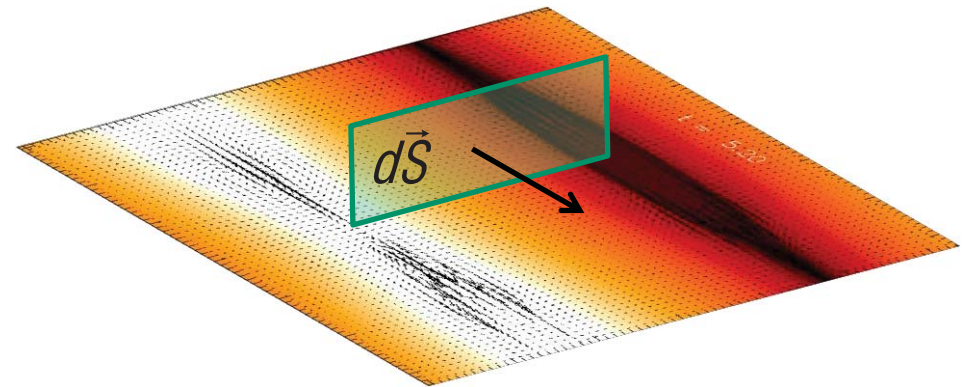
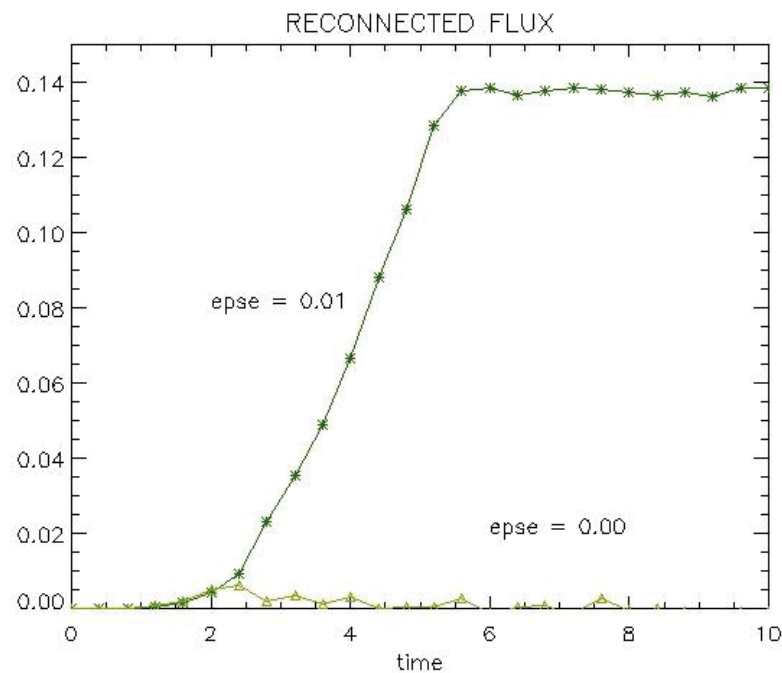
- We perform 512x512 simulations of the EIHMHD equations in 2.5D geometry to study magnetic reconnection.
- We force an external field with a double hyperbolic tangent profile to drive reconnection at two X points.
- At three successive times we show the current density in the background, the proton flow in the left half of each frame, and the electron flow on the right half.
- Although at large scales both flows look quite similar, in the vicinity of the X points, electrons tend to move much faster, close to the Alfvén velocity.





# Reconnected flux in EIHMHD

- The total reconnected flux at the X-point is the magnetic flux through the perpendicular surface that extends from the O-point to the X-point.
- We compare the total reconnected flux between a run that includes electron inertia and another one that does not.



- The reconnection rate is the time derivative of these two curves.
- The apparent saturation is just a spurious effect stemming from the dynamical destruction of the X-point.



# Conclusions

- In this presentation, we integrated the **Hall-MHD** equations numerically, to study magnetic reconnection. Even though the Hall effect does not produce reconnection, its role is to enhance the Ohmic reconnection rate.
- We also studied the role of the Hall effect in the presence of a strong external magnetic field. We showed the development of Kolmogorov-like turbulence in this system. Also, the existence of **parallel electric fields** can provide particle acceleration.
- We extended the Hall-MHD equations to include electron inertia, leading to what we call the **EIHMHD** equations.
- Integrating the EIHMHD equations in a 2.5D setup, we show that **electron inertia** leads to efficient magnetic reconnection, even in the absence of magnetic resistivity.
- The **ideal invariants** of a multi-species plasma are the total energy and also one helicity per species.