

A Finsler approach to the angular metrics

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- 1 Introduction to angular metrics
- 2 From angular metrics to short paths in $\mathcal{U}(n)$
- 3 Further related results

How can we define distances between subspaces?

Angular metrics

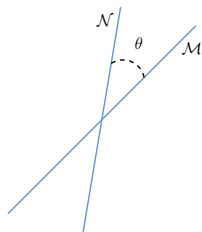
Angular metrics

Let $x, y \in \mathbb{C}^n$, $\mathcal{M} = \text{span}\{x\}$ and $\mathcal{N} = \text{span}\{y\}$. Then

$$\cos \theta = \frac{|\langle x, y \rangle|}{\|x\| \|y\|} = \|P_{\mathcal{M}} P_{\mathcal{N}}\| = s_1(P_{\mathcal{M}} P_{\mathcal{N}}).$$

($\theta \in [0, \frac{\pi}{2}]$). A natural distance between \mathcal{M} and \mathcal{N} is

$$\rho(\mathcal{M}, \mathcal{N}) = \theta.$$



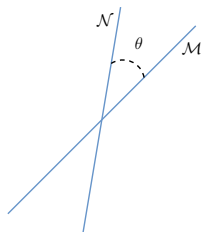
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Remark: We can also define:

$$d_{\text{gap}}(\mathcal{M}, \mathcal{N}) = \|P_{\mathcal{M}} - P_{\mathcal{N}}\|_{\text{sp}} = \sin \theta.$$

However, this metric is not *intrinsic* in the following sense: let (X, d) be a metric space. Given a continuous curve $\alpha : [a, b] \rightarrow X$, we can define

$$L_d(\alpha) = \sup_{a=t_0 < t_1 < \dots < t_n=b} \sum_{k=1}^n d(\alpha(t_k), \alpha(t_{k-1})), \text{ and } \widehat{d}(x, y) = \inf_{\gamma: x \leftrightarrow y} L(\gamma).$$

Then, d is called intrinsic if $d = \widehat{d}$. (For d_{gap} , it holds that $\widehat{d}_{\text{gap}} = \rho$).

What happens for subspaces of higher dimensions?

Angular metrics

The Grassmannian, \mathcal{G}_n , is the set of all the subspaces of \mathbb{C}^n . Given $\mathcal{M} \in \mathcal{G}_n$

$$\mathcal{M} \iff P_{\mathcal{M}} \iff S_{\mathcal{M}} = 2P_{\mathcal{M}} - I.$$

- Using these identifications, we can endow \mathcal{G}_n with a topology such that it becomes a compact space.
- The connected components of \mathcal{G}_n are the subsets $\mathcal{G}_{n,m}$ consisting of those subspaces of dimension m .

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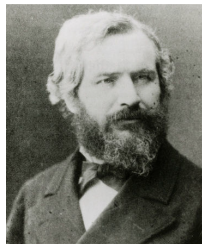
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Definition (C. Jordan 1875)

Given two k -dimensional subspaces $\mathcal{M}, \mathcal{N} \subseteq \mathbb{C}^n$, the principal angles between them are the angles $\theta_i(\mathcal{M}, \mathcal{N})$ belonging to $[0, \pi/2]$, $1 \leq i \leq k$, whose cosinus are the k -biggest singular values of $P_{\mathcal{M}}P_{\mathcal{N}}$. In other words:

$$\cos \theta(\mathcal{M}, \mathcal{N}) := (s_1(P_{\mathcal{M}}P_{\mathcal{N}}), \dots, s_k(P_{\mathcal{M}}P_{\mathcal{N}})).$$



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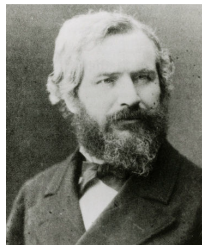
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Now, given a norm $\|\cdot\|$ in \mathbb{R}^k :

Is the function $d(\mathcal{M}, \mathcal{N}) := \|\theta(\mathcal{M}, \mathcal{N})\|$ a metric in each $\mathcal{G}_{n,m}$?



Angular metrics

Recall that $\phi : \mathbb{R}^n \rightarrow \mathbb{R}$ is a **gauge symmetric function** if it satisfies:

- ϕ is a norm;
- $\phi(x_1, \dots, x_n) = \phi(|x_1|, \dots, |x_n|)$;
- $\phi(x_1, \dots, x_n) = \phi(x_{\sigma(1)}, \dots, x_{\sigma(n)})$.

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Recall also, that a norm $\| \cdot \|$ is called **unitarily invariant** if for every $A \in \mathcal{M}_n(\mathbb{C})$ and every pair of unitary matrices $U, V \in \mathcal{U}(n)$

$$\|A\| = \|UAV\|.$$

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Proposition

Given an unitarily invariant norm, there exists a gauge symmetric function ϕ such that:

$$\|A\| = \phi(s(A)).$$

Conversely, every gauge symmetric function defines a unitarily invariant norm, that we will called $\|\cdot\|_\phi$, in this way.

Theorem (Li-Qiu-Zhang '05)

Let $\phi : \mathbb{R}^m \rightarrow \mathbb{R}$ be a gauge symmetric function and $\rho_\phi : \mathcal{G}_{n,m} \times \mathcal{G}_{n,m} \rightarrow \mathbb{R}$ the function defined by

$$\rho_\phi(\mathcal{M}, \mathcal{N}) = \phi(\theta(\mathcal{M}, \mathcal{N})).$$

Then, ρ_ϕ is an unitarily invariant metric.

Geometric preliminaries

Unitary group

Proposition

The group $\mathcal{U}(n)$ is a submanifold of $\mathcal{M}_n(\mathbb{C})$, and for each point $U \in \mathcal{U}(n)$

$$T_U \mathcal{U}(n) \simeq i\mathcal{H}(n).$$

Let $\|\cdot\|$ be a *unitarily invariant* norm in $\mathcal{M}_n(\mathbb{C})$. Given a smooth curve $\alpha : [a, b] \rightarrow \mathcal{U}(n)$

$$\text{Length}_{\|\cdot\|}(\alpha) := \int_a^b \|\dot{\alpha}\| dt,$$

which let us define the distance between two points of $\mathcal{U}(n)$ by:

$$\text{dist}_{\|\cdot\|}(U, V) := \inf \{ \text{Length}(\gamma) : \gamma \text{ joins } U \text{ and } V \}.$$

With respect to the connection $\nabla_X Y = \frac{1}{2}[X, Y]$, the geodesics are

$$\gamma(t) = Ue^{itX} \quad (X \in \mathcal{H}(n))$$

Remark: If the unitarily invariant norm is $\|\cdot\|_F$, then $\mathcal{U}(n)$ with the corresponding metric structure is a Riemannian structure.

Geometric preliminaries

Grassmann manifold

Proposition

The Grassmann space \mathcal{G}_n is a submanifold of $\mathcal{U}(n)$.

It can be proved that the tangent space at $S = 2P - I \in \mathcal{G}_n$ is:

$$T_S \mathcal{G}_n = \left\{ X = \begin{bmatrix} 0 & -\hat{X} \\ \hat{X}^* & 0 \end{bmatrix} \begin{matrix} R(P) \\ R(I-P) \end{matrix} : \hat{X} \in \mathcal{M}_{k,n-k}(\mathbb{C}) \right\}.$$

Remarks:

- Given $S \in \mathcal{G}_n$ and $X \in T_S \mathcal{G}_n$, then by the structure of X

$$\gamma_{S,X}(t) = S e^{-tX} = e^{tX/2} S e^{-tX/2}.$$

In particular, **the geodesic moves inside \mathcal{G}_n all the time.**

- The map $S \mapsto -S$, corresponding to the map $\mathcal{M} \mapsto \mathcal{M}^\perp$, is an isometric diffeomorphism between $\mathcal{G}_{n,m}$ and $\mathcal{G}_{n,n-m}$. So, from now on we will assume that $m \leq \frac{n}{2}$.

Geometric preliminaries

Direct rotations

Theorem (Davis-Kahan '70)

Let \mathcal{M} and \mathcal{N} two subspaces of $\mathcal{G}_{n,m}$. There exists $X \in T_{S_{\mathcal{M}}}\mathcal{G}_{n,m}$ such that

$$S_{\mathcal{M}}e^X = e^{-X/2}S_{\mathcal{M}}e^{X/2} = S_{\mathcal{N}} \quad \text{and} \quad \lambda(X) = \{\pm i\theta(\mathcal{M}, \mathcal{N}), 0, \dots, 0\}.$$

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Let $\gamma(t) = S_{\mathcal{M}}e^{tX}$ for $t \in [0, 1]$. For any unitarily invariant norm $\|\cdot\|$

$$\text{Length}_{\|\cdot\|}(\gamma) = \int_0^1 \|\dot{\gamma}\| dt = \int_0^1 \|S_{\mathcal{M}}X e^{tX}\| dt = \|X\|.$$

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If $\|\cdot\|$ is any Schatten norm $\|\cdot\|_p$ then

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More generally, given a g.s.f. ϕ in \mathbb{R}^m , if we consider the norm:

$$\|A\|_{\phi} = \frac{1}{2}\phi(s_1(A) + s_2(A), \dots, s_{2m-1}(A) + s_{2m}(A)),$$

then $\text{Length}_{\|\cdot\|_{\phi}}(\gamma) = \rho_{\phi}(\mathcal{M}, \mathcal{N})$.

Short paths in $\mathcal{U}(n)$

Theorem (A., Larotonda, Varela (maybe '13))

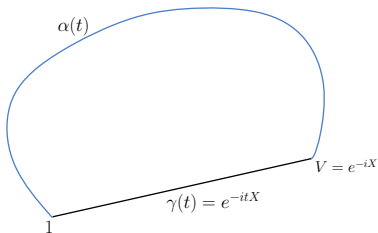
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Idea of the proof: Without loss of generality, we can assume that $U = 1$.

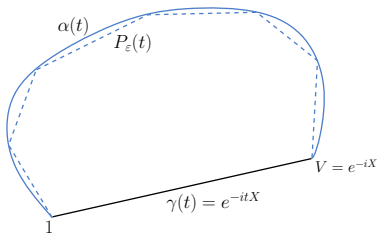


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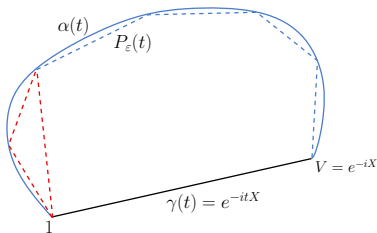


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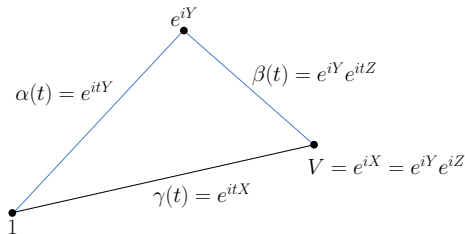
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- $e^{iX} = e^{iY}e^{iZ}$
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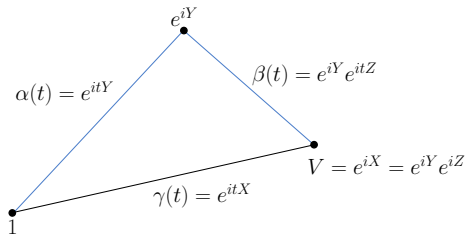
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- Suppose for a moment that $e^{iX} = e^{i(Y+Z)}$;
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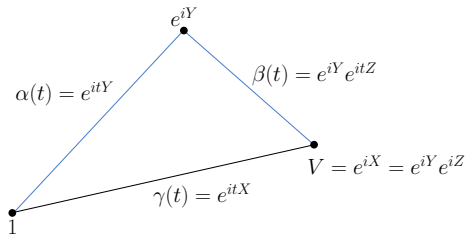
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Thompson's formula

Theorem (R. Thompson '86)

Given $A, B \in \mathcal{H}(n)$, there exist unitary matrices U and V such that:

$$e^{iA}e^{iB} = e^{i(UAU^* + VB V^*)} . \quad (1)$$

History:

- 1962: Given $A, B \in \mathcal{H}(n)$, Horn found a concrete list of inequalities that the eigenvalues of A , B and $A + B$ have to satisfy.

He conjectured: if $a, b, c \in \mathbb{R}^n$ satisfy these inequalities, then there exist $A, B \in \mathcal{H}(n)$ such that

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- 1980: Thompson conjectured (1).
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Uniqueness of the short paths

A norm $\| \cdot \|$ defined in \mathbb{R}^n is called **strictly convex** if for every $x, y \in \mathbb{R}^n$

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Theorem (A., Larotonda, Varela)

Assume ϕ is strictly convex, and let $U, V, W \in \mathcal{U}(n)$ be such that

$$d_\phi(U, V) = d_\phi(U, W) + d_\phi(W, V), \text{ and } d_\infty(U, V) < \pi.$$

Then U, V, W are aligned in $\mathcal{U}(n)$, that is, there exists $t_0 \in [0, 1]$ and $Z \in \mathcal{H}(n)$ with $\|Z\|_{sp} < \pi$ such that

$$V = Ue^{iZ}, \quad \text{while} \quad W = Ue^{it_0Z}.$$

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Remark: In the case of \mathcal{G}_n , this result was also proved by Li-Qiu-Zhang.

Uniqueness of short paths

Continuación

Corollary (A., Larotonda, Varela)

Let X be a Hermitian element such that $\|X\|_{sp} < \pi$. Then, $\gamma(t) = Ue^{itX}$ is the unique piecewise C^1 path in $\mathcal{U}(n)$ joining U with $V = Ue^{iX}$.

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Idea of the proof:

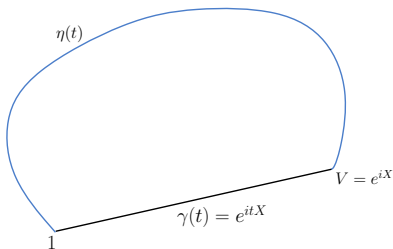
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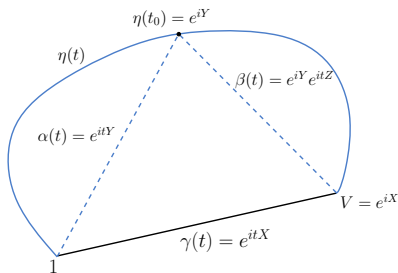
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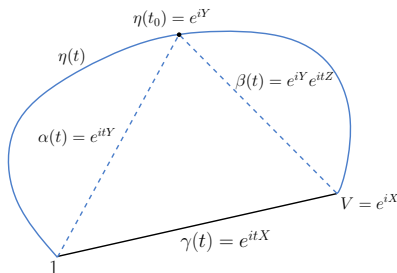
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Idea of the proof:

$$\begin{aligned}\|X\| &\leq \|Y\| + \|Z\| \\ &\leq \int_0^{t_0} \|\dot{\eta}\|_{\phi} dt + \int_{t_0}^1 \|\dot{\eta}\|_{\phi} dt \\ &= \text{Length}(\eta) = \|X\|\end{aligned}$$

\implies
Previous Thm

$$\eta(t_0) \in \gamma(t)$$



Unitarily invariant actions

Let \mathcal{S} be the action defined on piecewise C^1 curves $\alpha : [a, b] \rightarrow \mathcal{U}(n)$ by

$$\mathcal{S}(\alpha) = \int_a^b \mathcal{L}(\dot{\alpha}(t)) dt, \quad (2)$$

where $\mathcal{L} : \mathcal{H}(n) \rightarrow [0, +\infty)$ is a convex function that satisfies

$$\mathcal{L}(UAV) = \mathcal{L}(A),$$

for every $A \in \mathcal{H}(n)$, and every unitary matrices U and V .

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Examples:

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Problem

Given $U, V \in \mathcal{U}(n)$, and a fixed interval $[a, b]$, find the piecewise C^1 curves $\gamma : [a, b] \rightarrow \mathcal{U}(n)$ such that $\gamma(a) = U$, $\gamma(b) = V$ and γ minimize the action given by (2).

Unitarily invariant actions

Results

Let $U \in \mathcal{U}(n)$, $V = Ue^{iZ}$, $Z \in \mathcal{H}(n)$, and γ the path defined on $[a, b]$ by:

$$\gamma(t) = Ue^{i\frac{(t-a)}{b-a}Z}.$$

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Theorem (A., Larotonda, Varela)

If $\|Z\|_{sp} \leq \pi$, then $\gamma(t)$ minimizes \mathcal{S} among piecewise smooth curves $\alpha : [a, b] \rightarrow \mathcal{U}(n)$ joining U to V . In particular

$$\inf_{\alpha} \mathcal{S}(\alpha) = (b-a)\mathcal{L}\left(\frac{Z}{b-a}\right).$$

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Theorem (A., Larotonda, Varela)

If \mathcal{L} is strictly convex and $\|Z\|_{sp} < \pi$, then $\gamma(t)$ is the unique minimizer.

Thompson's formula

Some infinite dimensional versions

Let A and B be two compact operators acting on a Hilbert space \mathcal{H} .

Proposition (A., Larotonda, Varela '12)

There exist unitary operators U_k and V_k , such that

$$e^{iA}e^{iB} = \lim_{k \rightarrow \infty} e^{iU_k A U_k^* + iV_k B V_k^*}.$$

Remark: A similar result also holds for embeddable II_1 factors.

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Remark: A similar result also holds for embeddable II_1 factors.

To avoid the limit, we need to embed the operators in a larger Hilbert space:

Theorem (A., Larotonda, Varela '12)

There is an isometry W , and unitary operators U and V such that

$$e^{iWAW^*}e^{iWBW^*} = e^{iU(WAW^*)U^* + iV(WBW^*)V^*}.$$

תודה
Dankie Gracias
Спасибо شُكراً
Merci Takk
Köszönjük Terima kasih
Grazie Dziękujemy Děkojame
Ďakujeme Vielen Dank Paldies
Kiitos Täname teid 谢谢
Thank You Tak
感謝您 Obrigado Teşekkür Ederiz
Σας ευχαριστούμε 감사합니다
Bedankt Дěkujeme vám
ありがとうございます
Tack