





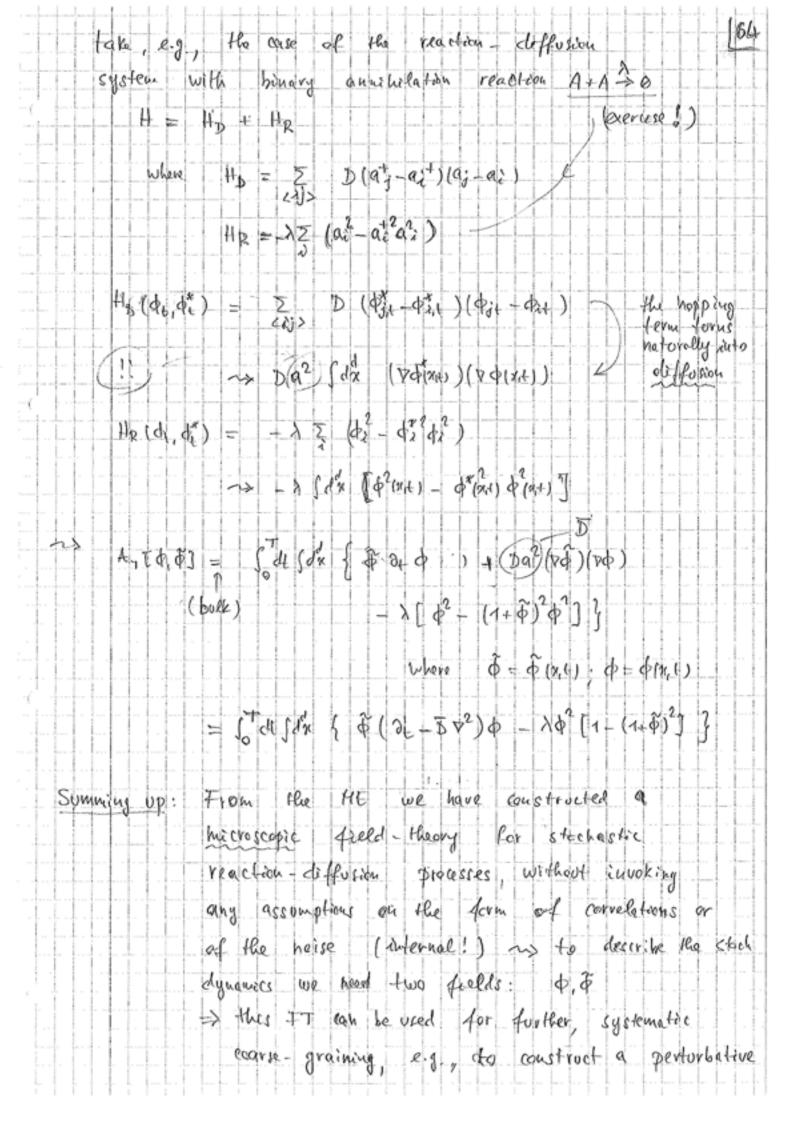
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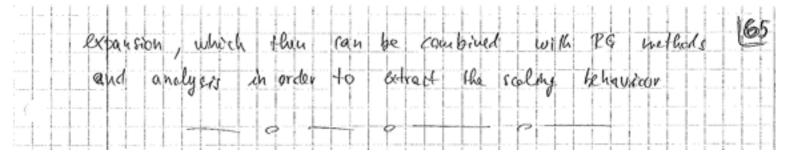
Spring College on the Physics of Complex Systems

26 May - 20 June, 2014

Stochastic processes and applications Lectures 8 & 9

Andrea Gambassi SISSA & INFN Obs: (a) so far we have inserted the observable o at the "end" of the evolution. (0>(T) = <P | O((a) a) () | \$(0) > = <P | O((a) a) Y) e HT | \$(0) > but one might be actually interested in -two - (or more 1) time correlation functions in which the observable @ is introduced at different times e.g. ni = atal < no(T) nj(T'KT)> = <PIn; e-4(T-T)) nj e HT 10(0)> ar in general: < O1 (10, 02) (+) O2 (10, 02) (+) > = < D10, (0,02) e HT-T' O2 (10,02) e 100) exercise: write down the corresponding expression as a porter integral. (freating properly the boundary teams) 02 ((at air) -> 02 ((4) (4)) (b) We have considered only one site: the construction. can be down at each lite interpendently and leads to: ITI S doedo - TI Sody down and the spatial variable then enters in the action to and to with the som over all the sites of the latter. (c) If the is interested in the "collections properties at large length stales, one can perform on continuous brust of the actions Ar Ao by letting the lattice spacing a so, ending op in the typical field-thorrefront description in terms of quantities of (x,t) of (x,t) (or, elevingtively, &(x1)







Summarinug:

φaφ + H(1+φiφ) up to boundary terms.

See A. Kannenev:

Cambridge, 2011.

Systems"

dr. 4.

"Field Theory & Non-quilib.

Consider now, the O-dim case \$(x,t) → q(t) \$\tilde{\phi}(x,t) \rightarrow p(t)\$

H(1+\$,\$) → - H(P,q) = H(1+P,q)

H(1+\$,\$\$\$) → - H(P,q) = H(1+P,q)

St = ft [Pq-H(P,q)] | Obs: 31(0,q) = 0.

(cons. of probabil.

=) action of an Homiltonian system!

Pair (9,+ 190,10) = \$ 29 00 e - S[P,9)

For studying rave events or as a first approximation, (WKB) the previous functional integral can be evaluated in (WKB) the Stationary path approximation; the stationary path is determined by requiring:

$$\frac{\delta S}{\delta \phi(t)} = 0 \implies \dot{q} - \partial p J + (P, q) = 0 \implies Hamiltonian eqs. ef$$

$$\frac{SS}{\delta q(t)} = 0 \implies \dot{p} + \partial q J + (p, q) = 0 \quad (Up to bound. Jenus) \quad hnotion!$$



Note that: It is independent of to an the optimal pater! (the "energy" is conserved by the dynamics)

In fact: \$\frac{1}{4} H(\phi(t), q(t)) = \frac{2pH}{p} + \frac{2pH}{q} = 0

The the stationary state: q° >0 pg →0

=> if H(P(+),q(+)) +> 0 then the probability of the path is exponentially small in time, as:

 $S_t \propto t$

⇒ for + > +00 the optimal trajectory (Porto) > (q,+) is always on the curve H=0

How can we visualize the optiminal trajectories? In the "phase space".
(7.9)

by the curves at H=0, consider first this case;

(i) Because of cons. of probability: H(0,9)=0

(ii) it an absorbing state is present => W(h->?) < h

=> II(p, p)=0

Accordingly those are at least ? lives @ It=0: p=0 & 9=0.

For p=0 the corresp. Stationary path eq. is:

q = = = + H(p,q) | p=0 and corresponds (ex!)

is mean-field solution which neglects fluctutions & discretness of q.



Consider, e.g., the model recalled above: the rate equation is
$$\langle h \rangle = q$$

while for och, 9(4-00) exponentially fast.

Note, however, that even for $\sigma > \mu$ the only possible asymptotic state is the absorbing one, due to the fact that even if $Kh >_{1} \simeq q$ distinally, a fluctuation will always drive the system into the absorbing state $h = 0 \Rightarrow ho$ actual phase transition in Dd for $\lambda = 0$ is possible because $h(t) \neq +\infty$ at $t \neq 0$ [$\Rightarrow t \neq 0$] Less is possible because $h(t) \neq +\infty$ at $t \neq 0$] in higher-dimensions the phase transition in higher-dimensions the phase transition $t \neq 0$ active absorbing exists also for $\lambda \neq 0$ because diffusion can reintroduce fluctuations in the sites where the particles were previously exists.

=> the optimal path is eventually the one with 9=0

For the specific model above, one finds:

H(p19) = p[o(1+p)-p- \(1+p)9]9

and therefore, in addition to p=0 & q=0 we have also



activation 4 H traject

- the vector field is as in the figure

Q: if we start close to the metastable state, how long woll it take before extinction?

Rate of extinction: & e-Sex

where
$$SX = \int dt \left[pq - H(p,q) \right] \Big|_{p=p_0(q)}$$
 where: $p_0(q) = \frac{H}{\sigma - \lambda q} - 1$

$$= \int p_0 dq \implies \text{area of the triangle!}$$

Note that if 17/«1 => along the activation trajectory

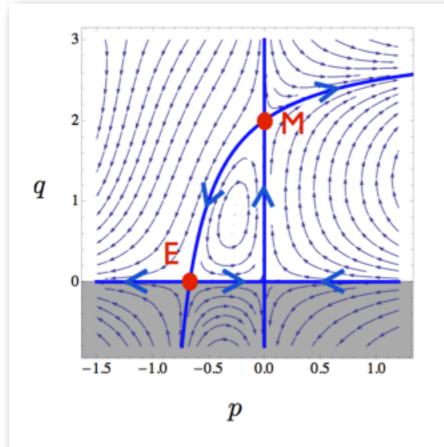
p=6 and one can neglect the

arvature of the curve:

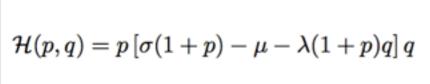


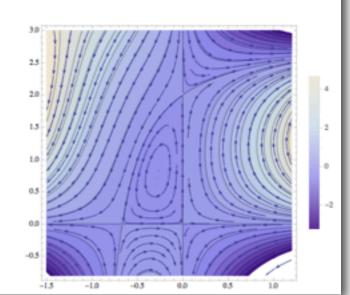
Accordingly:

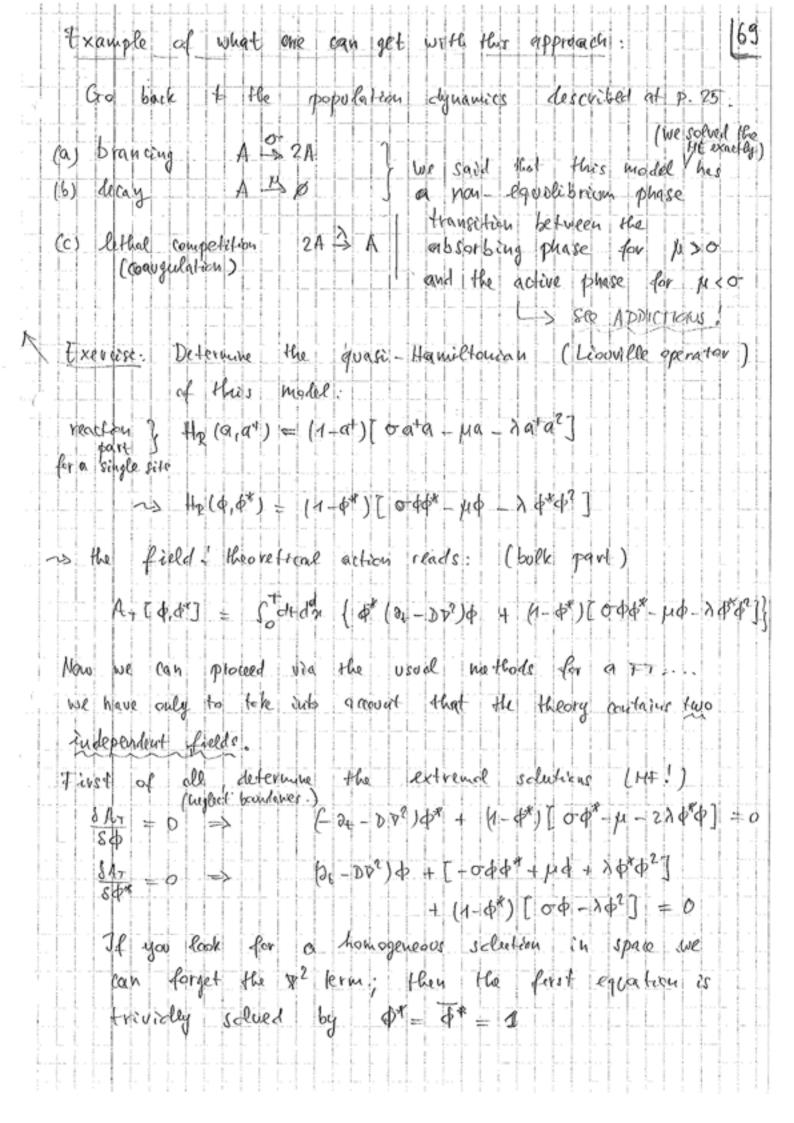
(see Kamener sec. 4.10)



$$\mu = 1$$
 $\sigma = 3$
 $\lambda = 1$







The second equation becomes, for $\phi = \overline{\phi}$ 2 0 = (0- m) 5 - 2 5? (Note that neglecting the fluctuations around of >> <n> = < 0> = 0 as the rate equation, as expected, emerges as the wan-field approximation of the complete theory (one might consider also diffusion.) => (a) for 2=0 \$(t) = exp { - \underset - \underset - \underset \under +> 00. In the active phase. (b) for 1 # 0, instead one can explicatly solve the equation (exercise!) finding that: (note that the quadratic term provents the density from "exploding") Mxo (absorbing): of (t > 0) ~ e most 12 (active): \$ (4 > 00) = \$ = 5-4 (saturation) μ=0 (crifical point): Φ(++00) ~ 1 What about fluctuations? in the case of I order phase transitions, fluctuations ave expected to: (a) modify the phase diagram (eg the actual location of the critical point. is but this is a non-universal aspect in the sense that it depends on the procepic details of the system (e.g., the way the foeld theory is regularied!)

$$\mathcal{A}_{T}[\phi,\phi^{*}] \equiv \int_{0}^{T} \mathrm{d}t \int \! \mathrm{d}^{d}x \left\{ \phi^{*}(\partial_{t} - \bar{D}\nabla^{2})\phi + H_{R}(\phi^{*},\phi) \right\}$$

$$(8) \stackrel{\leftarrow}{\swarrow} A \stackrel{\sigma}{\mapsto} A + A$$

$$(D) \stackrel{\leftarrow}{\longleftrightarrow} A \stackrel{\mu}{\mapsto} \emptyset$$

$$(C) \stackrel{\rightarrow}{\searrow} A + A \stackrel{\lambda}{\mapsto} A$$

$$(D) \stackrel{\leftarrow}{\longleftrightarrow} D$$

$$(D) \stackrel{\leftarrow}{\longleftrightarrow} A \stackrel{\mu}{\mapsto} \emptyset$$

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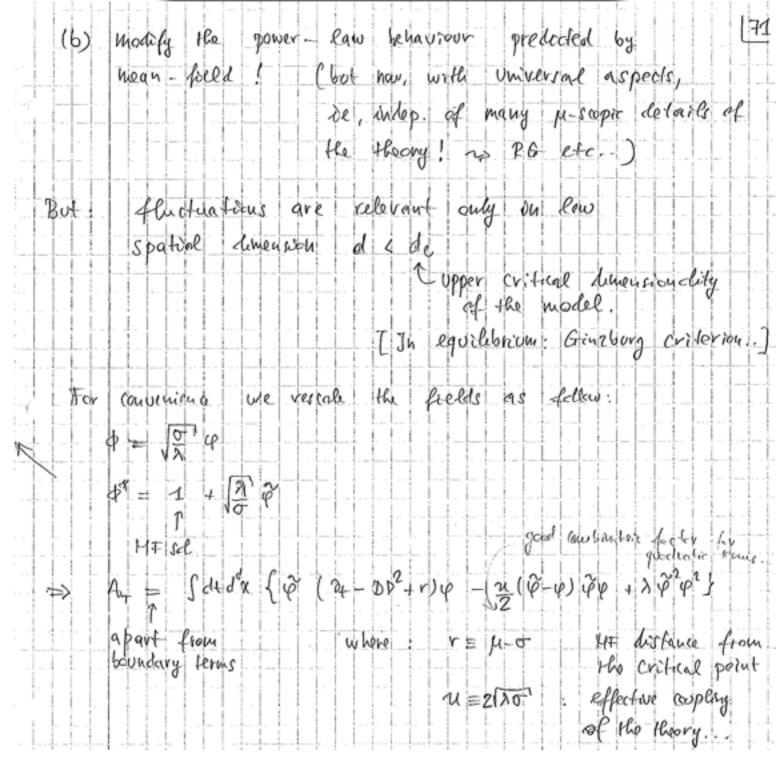
$$(D) \stackrel{\leftarrow}{\longleftrightarrow} A + A \stackrel{\lambda}{\mapsto} A$$

$$(D) \stackrel{\leftarrow}{\longleftrightarrow} A \stackrel{\mu}{\mapsto} \emptyset$$

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Consider the "action"

A= SA don { \$\varphi (2+-D+2++)\varphi - \frac{\varphi}{2} (\varphi - \varphi) \varphi \varphi + \lambda \varphi^2 \varphi^2}

add a scale t

Study the effect of short-wavelength fluctuations on those occurring at larger

We would like to implement wilson's RG scheme, which consists of 3 steps:

- (i) The thoory is originally defined with a large-momentum out off And (a = larker specing)

 In the momentum space we can separate each feeld

 \$\phi\$ whto larger momentum components \$\phi(k)\$, \$\frac{1}{2}\left(\frac{1}{2}\left)\$

 Small- momentum components \$\phi(k)\$

 \$\frac{1}{2}\left(\frac{1}{2}\left(\frac{1}{2}\left)\$

 \$\frac{1}{2}\left(\frac{1}2\left(\frac{1}2\left(\frac{1}2\left(\frac{1}2\left(\frac{1}2\left(\frac{1}2\left
- (ii) Integrate out the large momentum component \$> and deference the effective action for the small momentum (omponents \$\phi_{\infty} \infty now the resulting action has a coloff \$A\$, i.e a larger lattice spacing \$\frac{a}{s} > a\$

> in order to iterate the procedure of integrating out modes, it is therefore convenient to proceed to:

(22i) rescaling of coordinates, and fields:

introduce: x' = gx (k' = g'k) $t' = g^2 t$ ($\omega' = g^2 \omega$) Standard case: $\phi(x;t) = g \frac{d+q}{2} \phi'(x';t')$ $\frac{d-2+q}{2}$

then eventually rename the variables (object) -s (d, N+) and go back to paint (ii).

shote that eather each sungle step, the values out the

effective parameters charage as RG "flux".

Consider athe Gaussian theory: u= 1=0

=> of and of modes are decoupled and therefore the integration over & jives just a constant and does not modify the action for the slow modes ...

Due ends up with:

[(BV)] (BV)] (iii) x du g du g du x 2 x (tg 2 de 1 - Dg 2 v 2 + r) 4 1

Note that: in this thoog q, y play the same rate in the eleteraction, so one houristically expect flow to have the same scaling behav. (this can be made more pro use...)

= \(\biggr_1 \) \(\daggr_1 \) \(\varphi \

=) in order to be a fixed point: 9=0

2 = 5

and r=0; ofcerwise: r=rg2>r => as we iterate the Steps r=+0.

Consider, now, the behavior of the non-quadratic terms at the Gaussian fixed point: (i.e., assume in to be small and perturbative)

12-0 2-2 1 us 2-2 for dt d'a p2 p

u = u g 2-2 - s u" = u' g 2-1 = u(g 2-1)2 ... and so on ...

=> 112+00 if \$-2 <0 (124) ⇒ u 20 if \$-2>03 (d>4)

in this case the Gravssian foxed point is Gravssian FP is Ok no longer stable and one has to consider the effects of u on it; d= 4 is the upper critical dimens. of the model!

Wilson's RG:

(i) separate components
$$(\tau, D, r, \lambda, u; \Lambda)$$

$$\phi(k) = \begin{cases} \phi_{>}(k), & \rho \Lambda < |k| < \Lambda \\ \phi_{<}(k), & |k| < \rho \Lambda \end{cases}$$

(ii) integrate out
$$\phi_>(k)$$
 \Rightarrow effective theory for $\phi_<(k)$
$$(\tau',\,D',\,r',\,\lambda',\,u';\rho\Lambda)$$

(iii) rescaling of coordinates & fields:

$$\begin{cases} x' = \rho x \\ t' = \rho^{\mathbf{z}} t \\ \phi'(x',t') = \rho^{-(d+\eta)/2} \phi_{<}(x,t) \end{cases} (\tau'',D'',r'',\lambda'',u'';\Lambda)$$

$$(x', t', \phi') \rightarrow (x, t, \phi) \Rightarrow \text{back to (i)}$$

Gaussian fixed point:

$$\int dt \int_{\Lambda^{-1}} d^d x \, \tilde{\varphi}(\tau \partial_t - D\nabla^2 + r) \varphi$$

$$\stackrel{\text{(ii)}}{\mapsto} \int dt \int_{(\rho\Lambda)^{-1}} d^d x \, \tilde{\varphi}_{<}(\tau \partial_t - D\nabla^2 + r) \varphi_{<}$$

$$\stackrel{\text{(ii)}}{\to} \int_{\tau'} d^d x \, \tilde{\varphi}_{<}(\tau \partial_t - D\nabla^2 + r) \varphi_{<}$$

$$\stackrel{\text{(iii)}}{=} \int dt' \rho^{-z} \int_{\Lambda^{-1}} d^d x' \rho^{-d} \rho^{\frac{d+\eta}{2} \times 2} \tilde{\varphi}' (\tau \rho^z \partial_{t'} - D\rho^2 \nabla'^2 + r) \varphi'$$

$$= \int dt \int_{\Lambda^{-1}} d^d x \, \tilde{\varphi} (\tau \rho^{\eta} \partial_t - D\rho^{2+\eta-z} \nabla^2 + \underline{r} \rho^{\eta-z}) \varphi$$

$$\stackrel{\text{(iii)}}{=} \int dt \int_{\Lambda^{-1}} d^d x \, \tilde{\varphi} (\tau \rho^{\eta} \partial_t - D\rho^{2+\eta-z} \nabla^2 + \underline{r} \rho^{\eta-z}) \varphi$$

$$u'' = \rho^{d/2-2}u$$

$$\lambda'' = \rho^{d-2}\lambda$$

$$d/2-z+3\eta/2$$

Consider now:

=> if we work for d>2, this coopling

can be neglected! (are! this analysis is
octually velial around the

craustian fixed point, i.e.;
for d>4, structly speaking...
... hewever this can be verified
a posteriori)

the leading scaling behaviour enu be obtained by setting 2=0 The theory with 200 is well-known is high-energy physis and is called Reggeon field theory. of his a peculino symmetry colled Rapidity Reversal: ip(x,t) ←> - \psi(x,-t) > This FT characterizes a universality class to which also directed peralation belongs. There is even the Janssen- Grassberger conjective: "any continuous non-of. Phase transition from an active to an absorbing state in a system governed by a Flackovin stochastic elynamics that is decoupled from slow variables and in the absence of additional symmetries and tandonness should belong to this universality class"

$$\mathcal{A} = \int dt d^d x \left\{ \tilde{\varphi} (\partial_t - \bar{D} \nabla^2 + r) \varphi - \frac{u}{2} (\tilde{\varphi} - \varphi) \varphi \tilde{\varphi} \right\}$$

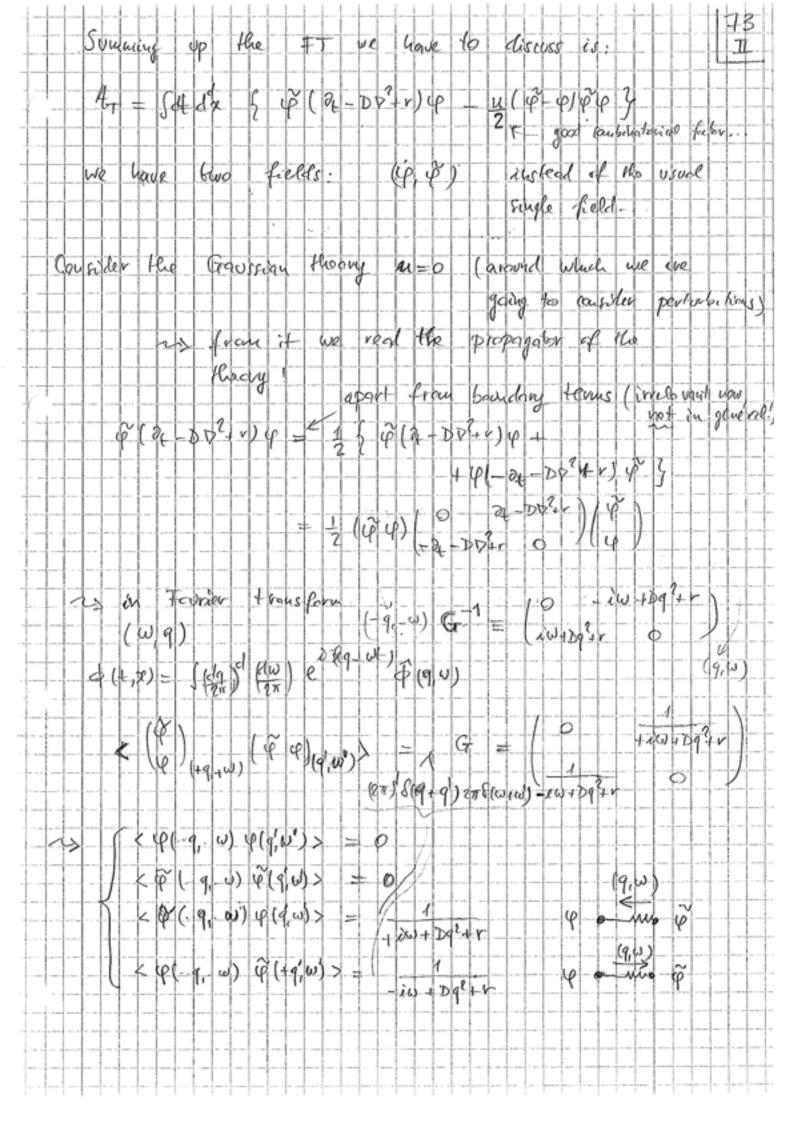
$$\varphi(x,t)\longleftrightarrow -\tilde{\varphi}(x,-t)$$

any

(Janssen-Grassberger, '81-'82)

- (i) continuous non-eq PT active → I abs
- (ii) Markovian dyn
- (iii) no slow variables
- (iv) no symmetries
- (v) no randmness

⇒ DP/CP univ. class

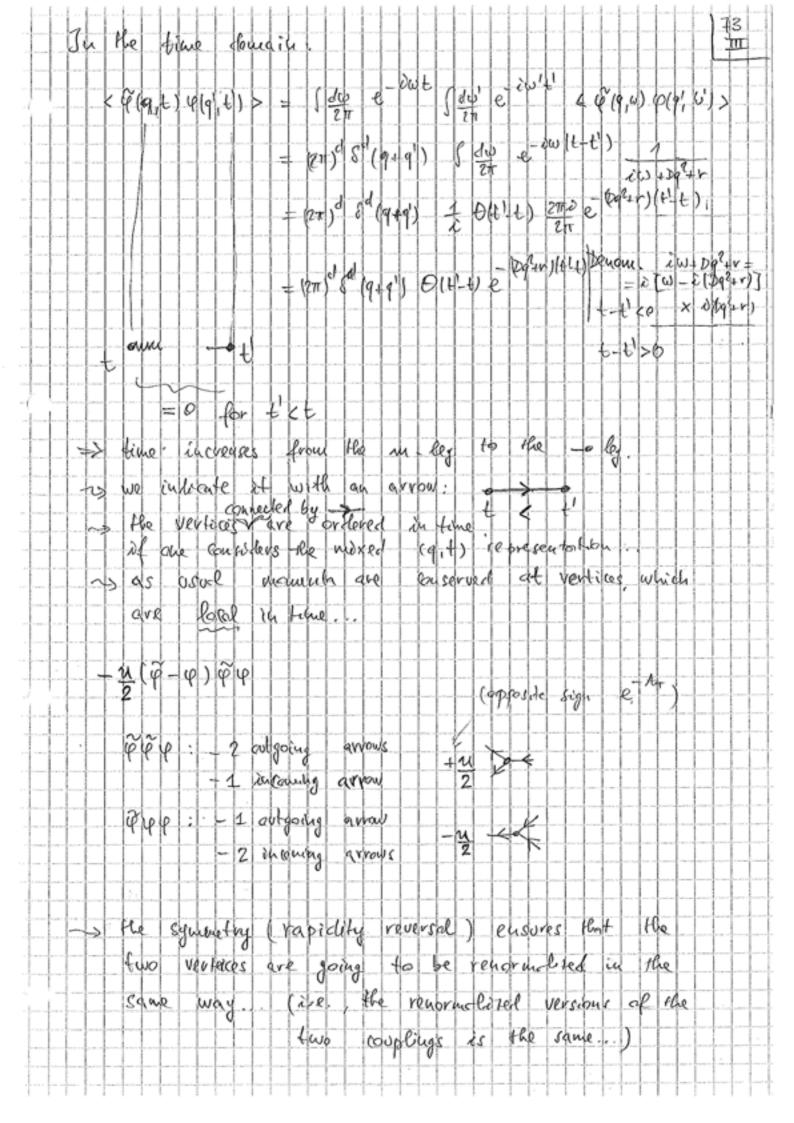


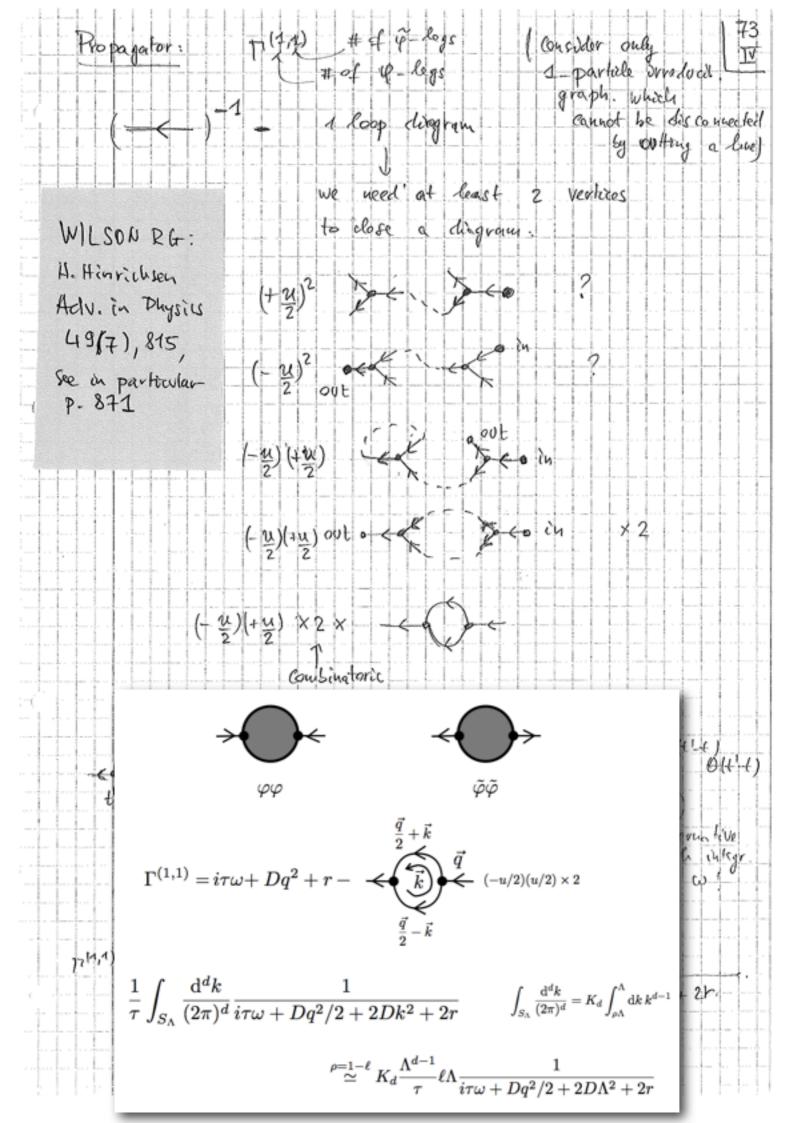
$$\begin{cases} \langle \tilde{\varphi}(\vec{q}, \omega) \tilde{\varphi}(\vec{q}', \omega') \rangle_0 = 0 \\ \langle \varphi(\vec{q}, \omega) \varphi(\vec{q}', \omega') \rangle_0 = 0 \\ \langle \tilde{\varphi}(\vec{q}, \omega) \varphi(\vec{q}', \omega') \rangle_0 = \frac{\delta^d(\vec{q} + \vec{q}') \delta(\omega + \omega')}{i\tau \omega + Dq^2 + r} \end{cases}$$

$$\frac{t}{\leftarrow} \underbrace{t'}_{\tau}$$

$$\langle \tilde{\varphi}(\vec{q}', t') \varphi(\vec{q}, t) \rangle_{0} = \Theta(t - t') \underline{e}^{-(Dq^{2} + r)(\underline{t - t'})}_{\tau} \delta^{d}(\vec{q} + \vec{q}')$$

$$\begin{array}{ccc} \frac{u}{2} & & & \\ & & \\ & \tilde{\varphi}\tilde{\varphi}\varphi & & & \tilde{\varphi}\varphi\varphi \end{array}$$





$$\frac{1}{\sqrt{2}} + \frac{1}{\sqrt{2}} = 0 + (1 - 1) \int_{S_{\Lambda}} \left(\frac{dk}{2\pi} \right)^{d} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right] \left(t - t' \right)} e^{-\left[D \left(\frac{3}{2} + k \right)^{2} + r \right]}$$

$$\frac{1}{t} \int_{QA}^{A} \frac{Std}{(2\pi)^{4}} dk k^{d-1} \frac{1}{2 + 2Dk^{2} + 2V} \int_{QA}^{A} \frac{for (5) d}{(2\pi)^{4}} dk k^{d-1} \frac{1}{2 + 2Dk^{2} + 2V}$$

$$\frac{1}{t} \int_{QA}^{A} \frac{Std}{(2\pi)^{4}} dk k^{d-1} \frac{1}{2 + 2Dk^{2} + 2V} \int_{QA}^{A} \frac{for (5) d}{(2\pi)^{4}} dk k^{d-1} \frac{1}{2 + 2Dk^{2} + 2V}$$

$$= \lambda \omega + Dq^{2} + r - 2\left(-\frac{u^{2}}{a}\right) \int \frac{du}{dx} \frac{dx}{dx} \frac{1}{\lambda \omega + Dq^{2} + 2Dk^{2} + 2k} + \frac{2}{\epsilon}$$

$$= \lambda \omega + Dq^{2} + r + \frac{u^{2}}{2} + \lambda d \int_{\epsilon}^{\epsilon} dx \frac{1}{\lambda \omega + Dq^{2} + 2Dk^{2} + 2k} + O(u^{4})$$

$$= \lambda \omega + Dq^{2} + r + \frac{u^{2}}{2} + \lambda d \int_{\epsilon}^{\epsilon} dx \frac{1}{\lambda \omega + Dq^{2} + 2Dk^{2} + 2k}$$

Note that (1)
$$P^{(3,1)}(q=0,\omega=0) = r + \frac{u^2}{2} kd + \frac{d^2}{2} l + \frac{1}{2DA^2 + 2r}$$

$$(2) \frac{\partial}{\partial q^2} p^{(4,4)} \Big|_{\substack{\omega = 0 \\ q = 0}} \equiv D' = D - \frac{u^2}{2} k_J \frac{\Lambda^d}{L} \cdot \frac{D}{2} \frac{D}{(2D\Lambda^2 + 2r)^2}$$

$$\Gamma^{(1,1)} = i\tau\omega + Dq^2 + r + \frac{u^2K_d\Lambda^d}{2\tau}\ell \frac{1}{i\tau\omega + Dq^2/2 + 2D\Lambda^2 + 2r}$$

$$r'\equiv \Gamma^{(1,1)}(q=0,\omega=0) \quad = r + \underbrace{\frac{u^2K_d\Lambda^d}{2\tau}}_{\textstyle 2D\Lambda^2+2r} \equiv rS_2$$

$$D' \equiv \left. \frac{\partial}{\partial q^2} \Gamma^{(1,1)} \right|_{q=0,\omega=0} = D - \underbrace{\frac{u^2 K_d \Lambda^d}{2\tau} \underbrace{\frac{\sum S_1}{D}}_{2(2D\Lambda^2 + 2r)^2}}_{q=0,\omega=0}$$

$$\tau' \equiv \left. \frac{\partial}{\partial (i\omega)} \Gamma^{(1,1)} \right|_{q=0,\omega=0} = \tau - \underbrace{\left(\frac{u^2 K_d \Lambda^d}{2\tau} \right)^{\frac{2}{2}} \frac{2S_1}{\tau}}_{q=0,\omega=0}$$

(3)
$$\frac{\partial}{\partial \hat{p}(\omega)} \uparrow^{(2,1)}(q;\omega) \mid_{q=0} = \tau' = \tau - \frac{u^2}{2} k_0 \Lambda^2 R \tau \frac{1}{(2b\Lambda^2 + 2r)^2}$$

And reduce $a \tau : \omega \rightarrow \omega \tau$)
$$2\tau \ell S_1$$

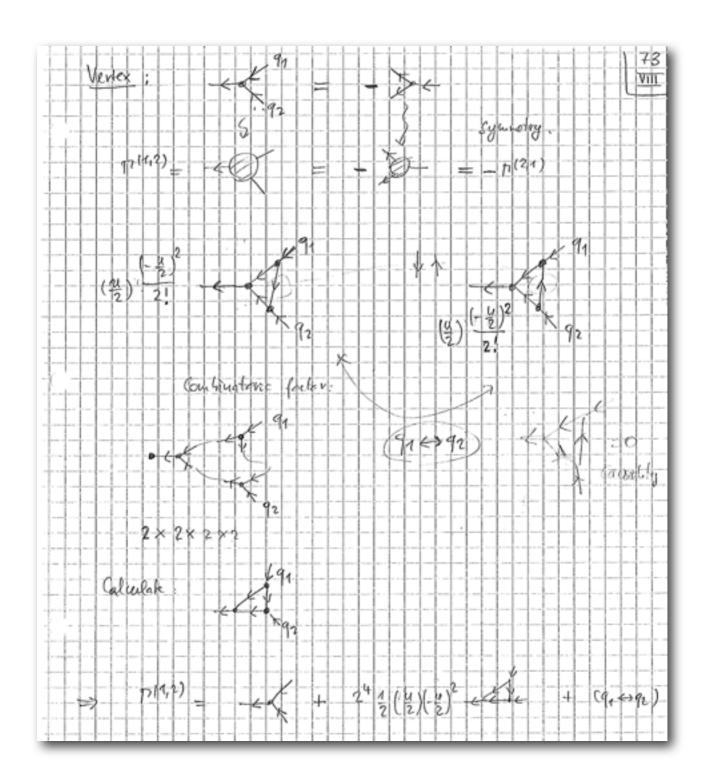
(we evalually consider
$$\frac{d\omega'}{2\pi} \int \frac{dk'}{2\pi} \int \frac{dk'}{2\pi} \frac{1}{i\omega'\epsilon + D(q_1+k)^2 + r} \frac{1}{-i\omega'\epsilon + Dk^2 + r} \frac{1}{-i\omega'\epsilon + D(q_2-k)^2 + r}$$

$$\omega' = \frac{i}{T} \left[D(q_1+k)^2 + r \right] \quad \omega' = -\frac{i}{T} \left[D(x^2 + r) \right] \quad \omega' = -i \frac{D}{T} \left[(q_2-k)^2 + r \right]$$

$$= \int_{A} \frac{dk}{2\pi} \int_{a}^{b} \frac{dk}{2\pi} \int_{b}^{b} \frac{1}{b(q_{1}+k)^{2} + Dk^{2} + 2k} \int_{b}^{b} (q_{1}+k)^{2} + D(q_{2}-k)^{2} + 2k} \int_{a}^{b} (q_{1}+k)^{2} + D(q_{2}-k)^{2} + 2k} \int_{b}^{b} (q_{1}+k)^{2} + D(q_{2}-k)^{2} + D(q_{2}-k)^{2} + 2k} \int_{b}^{b} (q_{1}+k)^{2} + D(q_{2}-k)^{2} + D(q_{2}-k)^{2} + 2k} \int_{b}^{b} (q_{1}+k)^{2} + D(q_{2}-k)^{2} + D(q_{2}-k)^{2$$

$$T^{(2,2)} = -u + (\frac{u}{2}) \left[-\frac{u}{2} \right]^2 \times 8 \left(\frac{1}{2} \times \frac{u}{2} \right)$$

$$= -u + 2u^3 k_d \Lambda^d \ell + \frac{1}{2} \frac{1}{(2D\Lambda^2 + 2r)^2} - 8u S_1 \ell$$



$$\Gamma^{(1,2)} = \begin{array}{c} \\ \\ \\ \end{array} = - \begin{array}{c} \\ \\ \end{array} = - \Gamma^{(2,1)} \end{array}$$

$$= -\frac{u}{4} + (u/2)(-u/2)^2 \times 8 + (\vec{q}_1 \longleftrightarrow \vec{q}_2)$$

$$\int \frac{d\omega'}{2\pi} \int_{S_{\Lambda}} \frac{d^{d}k}{(2\pi)^{d}} \frac{1}{i\tau\omega' + Dk^{2} + r} \frac{1}{[-i\tau\omega' + Dk^{2} + r]^{2}}$$

$$= \int_{S_{\Lambda}} \frac{d^{d}k}{(2\pi)^{d}} \frac{1}{\tau} \frac{1}{[2Dk^{2} + 2r]^{2}} \simeq \frac{K_{d}\Lambda^{d}}{\tau} \ell \frac{1}{(2D\Lambda^{2} + 2r)^{2}}$$

$$\Gamma^{(1,2)} = -u + 2u^3 \frac{K_d \Lambda^d}{\tau} \left(\frac{8uS_1}{(2D\Lambda^2 + 2r)^2} \right)$$

$$u' \equiv - \Gamma^{(1,2)} \Big|_{q_i = 0, \omega_i = 0} = u - 8uS_1 \ell$$

$$\rho = 1 - \ell, \quad \ell \to 0$$

$$\begin{cases}
\tau'' = \rho^{\eta} \tau' & \simeq (1 - \eta \ell) \tau' \\
D'' = \rho^{2-z+\eta} D' & \simeq [1 - (2 - z + \eta)\ell] D' \\
r'' = \rho^{\eta-z} r' & \simeq [1 - (\eta - z)\ell]r' \\
u'' = \rho^{d/2-z+3\eta/2} u' & \simeq [1 - (d/2 - z + 3\eta/2)\ell] u'
\end{cases}$$

$$u' = - \frac{1}{2} \frac{1}{(2DA^{2}+2r)^{2}} = 0$$

$$= u - (2u^{3}k) A^{d} \ell \frac{1}{2} \frac{1}{(2DA^{2}+2r)^{2}} \rightarrow gus_{1}\ell$$

Now we implement the rescaling : according to:

$$T'' = g^{9} T' \simeq (1 - g^{2}) T'$$

$$J'' = g^{2-2+9} D' \simeq [1 - (2-2+9)^{2}] D'$$

$$J'' = g^{9-2} T' \simeq [1 - (2-2+9)^{2}] T'$$

$$U'' = g^{\frac{4}{9}-2+\frac{3}{2}} U \simeq [1 - (\frac{4}{9}-2+\frac{3}{9})^{2}] U'$$

Accordingly; by composing the two transformations one founds;

$$r'' = [1 - (9-2)]r' = [1 - (9-2)\ell][r + r\ell S_2]$$

$$= r[1 - (9-2-S_2)\ell]$$

oud, eventually:

The retion change upon integrating out the short wave length modes.

Not of the parameters (T, D, T, U) we can always choose the hormalization of the fields of i and of time such that T and D do not charge: with l.

The remarking equations have to be solved:

$$\partial_{e} r = -r \left(q - 2 - S_{2} \right) = -r \left(+2S_{1} - 2 + S_{1} - S_{2} \right) = +r \left(2 + S_{1} + S_{2} \right)$$

$$\partial_{e} u = -u \left(\frac{d}{2} - 2 + \frac{3}{2} q + 8S_{1} \right) = -u \left(\frac{d}{2} - 2 + S_{1} - 3S_{1} + 8S_{1} \right)$$

$$= -u \left(-\frac{\epsilon}{2} + 6S_{1} \right) = u \left(\frac{\epsilon}{2} - 6S_{1} \right)$$

RG flow:

$$\begin{cases} \partial_{\ell}\tau = -(\eta + 2S_1)\tau & \eta = -2S_1 \\ \partial_{\ell}D = -(2 - z + \eta + S_1)D & z = 2 - S_1 \end{cases}$$

$$\partial_{\ell}r = -(\eta - z - S_2)r & \begin{cases} \partial_{\ell}r = (2 + S_1 + S_2)r \\ \partial_{\ell}u = -\left(\frac{d}{2} - z + \frac{3\eta}{2} + 8S_1\right)u & \partial_{\ell}u = \left(\frac{\epsilon}{2} - 6S_1\right)u \end{cases}$$

$$\epsilon = 4 - d$$

$$\tilde{r} \equiv \frac{r}{D\Lambda^2}$$

$$g \equiv \frac{u^2 K_d \Lambda^d}{4\tau (2D\Lambda^2)^2} = \frac{K_d}{16} \frac{u^2 \Lambda^{d-4}}{D^2 \tau}$$

Remainsor Hant:

$$S_1 = \frac{u^2}{4} r_0 \frac{\lambda^d}{c} \frac{1}{(2D\Lambda^2 + 2r)^2}$$
 and $S_2 = \frac{u^l}{2} r_0 \frac{\lambda^d}{c} \frac{1}{r} \frac{1}{(2D\Lambda^2 + 2r)}$

For investigating the flow it is convenient to introduce dimensionless quantities

$$\tilde{r} \equiv \frac{r}{b\lambda^2}$$

while:
$$S_2 = 2\left(\frac{u^2}{4} \frac{k_1}{L} \frac{\Delta^d}{(2D\Lambda^2)^2} \frac{2D\Lambda^2}{r} \frac{1}{1+r} = 49 \frac{1}{r'(1+r')}\right)$$

and:
$$\partial_{e}\tilde{r} = \frac{\partial_{e}r}{\partial \Lambda^{2}} = \frac{1}{\partial \Lambda^{2}} r(2 + S_{1} + S_{2}) = \tilde{r}(2 + S_{1} + S_{2})$$

$$\partial_{2} z = 2u \partial_{2} u \times \frac{1}{4} \frac{kd}{t} \frac{\Lambda^{d}}{(2M^{2})^{2}} = 2g \left(\frac{c}{2} - 6S_{1}\right)^{2}$$

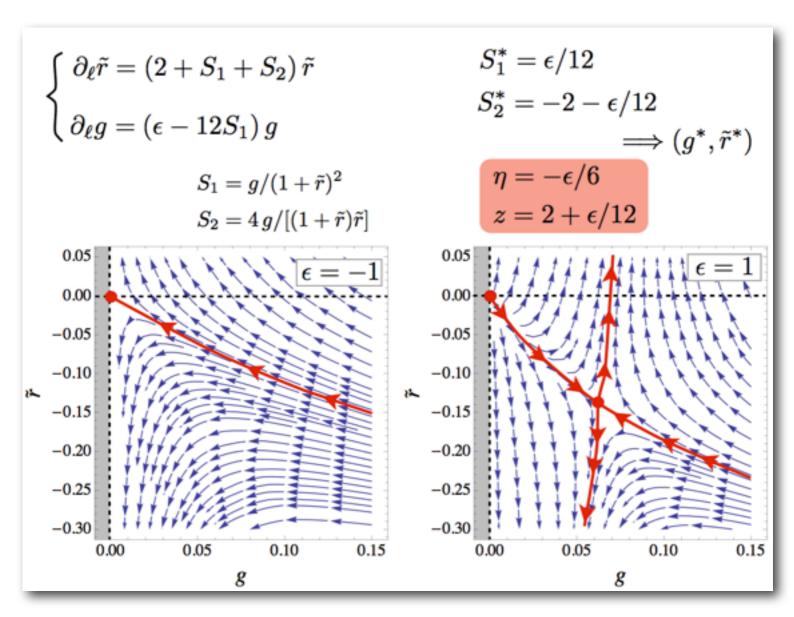
$$= g \left(\epsilon - 12 S_{1}\right)$$

Accordingly:
$$\partial_{\ell}\vec{r} = \vec{r}\left(2+s_1+s_2\right)$$

$$= \vec{r}\left(2+\frac{g}{(1+\vec{r})^2}+\frac{4g}{7(1+\vec{r})}\right)$$

$$\partial_{\ell}g = g\left[\ell-12\frac{g}{(1+\vec{r})^2}\right]$$

the flow of which is given in the figures.



The fixed goint values are determined by:

As in the case of equilibrium phase transitions Q RG, the remaining velocant exponent characterites the RG flow along the unstable direction (typically the temperature) close to the WF fixed point; solving the equations for \vec{v} Q g at the lowest order in f one finds (ex): $\vec{v} = -\frac{f}{6} + \theta(f^2) \qquad \text{where:} \qquad \frac{\partial \vec{v}}{\partial t} = \frac{\vec{v}}{v} \left(2 + \frac{g}{v} + \frac{u g}{v(1+v)^2}\right) \\
\vec{v} = \frac{c}{12} + \theta(f^2) \qquad \text{where:} \qquad \frac{\partial \vec{v}}{\partial t} = \frac{g}{v} \left(4 - 12 \frac{g}{v(1+v)^2}\right)$

fr(8,9)

Define: $Sr = \tilde{r} - \tilde{r}^*$ $Sg = g - g^*$

$$= \left(2 - \frac{\epsilon}{4}\right) \delta \tilde{r} + \left(4 + \frac{\epsilon}{2}\right) \delta g + 4.0.$$

$$\Rightarrow \quad \Im \left(\begin{array}{c} \operatorname{fr} \\ \operatorname{fg} \end{array} \right) = \left(\begin{array}{cc} 2 - \frac{\epsilon}{4} & 4 + \frac{\epsilon}{2} \\ 0 & -\epsilon \end{array} \right) \left(\begin{array}{c} \operatorname{fr} \\ \operatorname{fg} \end{array} \right)$$

=) we have to determine the eigenvalues: of the matrix which are: $-\epsilon$ and $2-\frac{\epsilon}{4}$.

The hogative one corresponds to the stable direction, while 2- & to the unstable one and can be identified, by analogy, with $1 = 2 - \frac{\xi}{4} = 0$ $0 = \frac{1}{2} + \frac{\xi}{16} + 0$ (c2)

