

Efficient simulations of low-dimensional systems

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Trieste, Sep. 14 2015

Efficient simulations of low-dimensional systems

Overview

(1) Matrix-product states and probes for topological phases

- Review: Entanglement and matrix-product states (MPS)
- MPS for infinite systems
- Extracting fingerprints of topological order

(2) Efficient simulation of dynamical properties

- Time-evolving block decimation (TEBD)
- Quench dynamics and entanglement growth
- MPO based time evolution

(3) Tutorial: Hands on session

(2) Efficient simulation of dynamical properties

$$i\hbar \frac{\partial}{\partial t} |\psi\rangle = H |\psi\rangle$$

Time evolution of MPS

- How to efficiently simulate the time evolution of MPS?

$$|\psi_t\rangle = \exp(-iHt)|\psi_{t=0}\rangle$$

- **Time evolving block decimation**

[Vidal '03]

- Time dependent DMRG

[White & Feiguin '04, Daley et al. '04, ...]

- Krylov space based methods

[Schmitteckert '04, ...]

- Time dependent variational principle

[Haegemann et al. '11 / '15]

- **Matrix-product operator based time evolutions**

[Zaletel et al. '15]

Time evolving block decimation

Time evolving block decimation

- Assume we have a Hamiltonian of the form

$$H = \sum_j h^{[j,j+1]}$$

- Time evolution in real time

$$|\psi_t\rangle = \exp(-iHt)|\psi_{t=0}\rangle$$

- Time evolution in imaginary time

$$|\psi_0\rangle = \lim_{\tau \rightarrow \infty} \frac{\exp(-H\tau)|\psi_i\rangle}{\|\exp(-H\tau)|\psi_i\rangle\|}$$

Time evolving block decimation

- Consider the Hamiltonian $H = \sum_j h^{[j,j+1]}$
- Decompose the Hamiltonian as $H=F+G$

$$F \equiv \sum_{\text{even } j} F^{[j]} \equiv \sum_{\text{even } j} h^{[j,j+1]}$$

$$G \equiv \sum_{\text{odd } j} G^{[j]} \equiv \sum_{\text{odd } j} h^{[j,j+1]}$$



- We observe $[F^{[r]}, F^{[r']}] = 0$ ($[G^{[r]}, G^{[r']}] = 0$)
but $[G, F] \neq 0$

Time evolving block decimation

- Apply Suzuki-Trotter decomposition of order p

$$\exp(-i(F + G)\delta t) \approx f_p[\exp(-F\delta t), \exp(-G\delta t)]$$

with $f_1(x, y) = xy$, $f_2(x, y) = x^{1/2}yx^{1/2}$, etc.

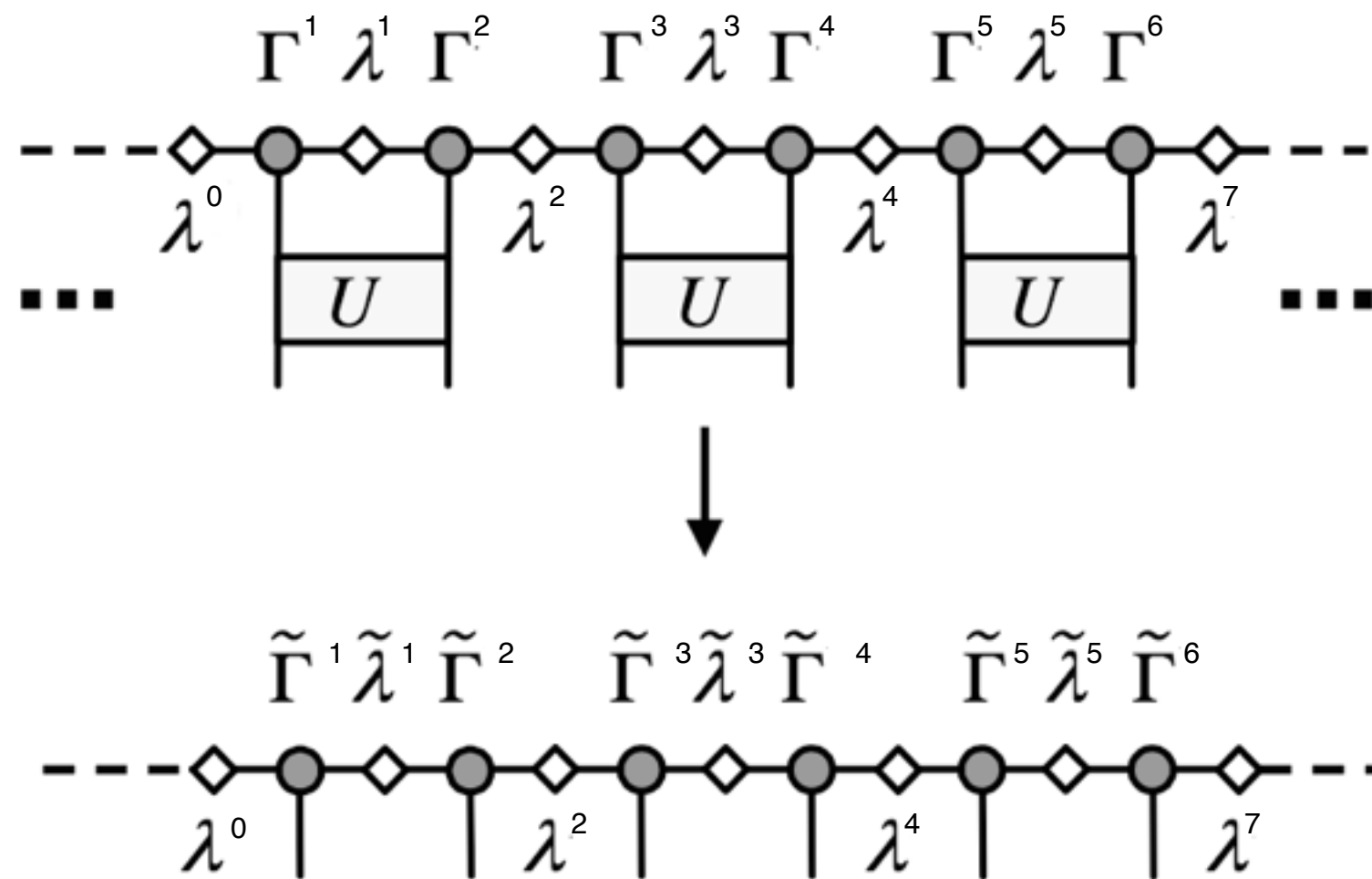
- Two chains of two-site gates

$$U_F = \prod_{\text{even } r} \exp(-iF^{[r]}\delta t)$$

$$U_G = \prod_{\text{odd } r} \exp(-iG^{[r]}\delta t)$$

Time evolving block decimation

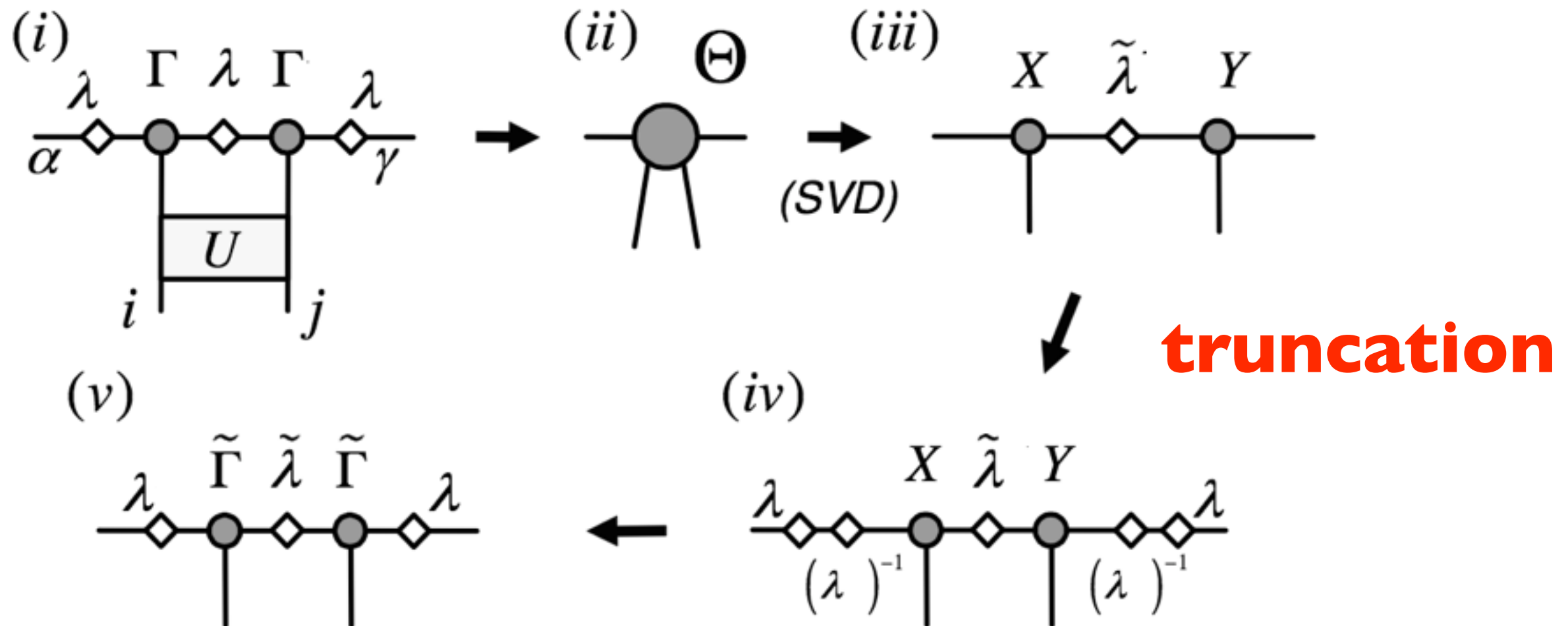
- Time Evolving Block Decimation algorithm (TEBD)



- How do we get the original form back?

Time evolving block decimation

- Time Evolving Block Decimation algorithm (TEBD)

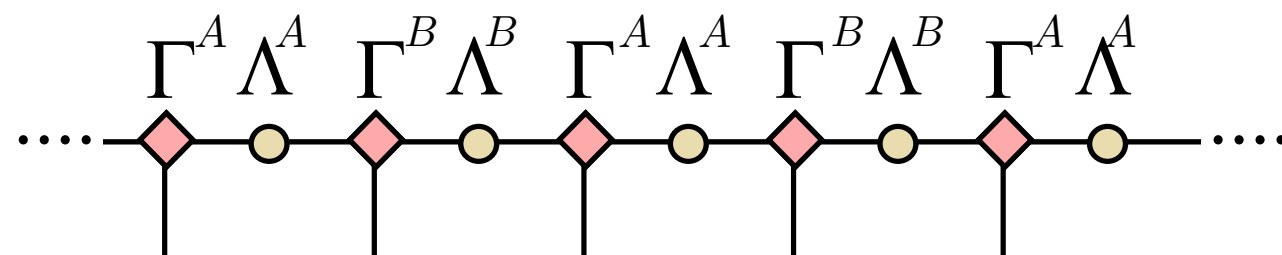


- Scales with the matrix dimension as χ^3

Time evolving block decimation

- Assume that $|\psi\rangle$ is translational invariant and $N = \infty$:
infinite Time Evolving Block Decimation algorithm (**iTEBD**)
- Partially break translational symmetry to simulate the action of the gates

$$\Gamma^{[2r]} = \Gamma^A, \quad \lambda^{[2r]} = \lambda^A, \quad \Gamma^{[2r+1]} = \Gamma^B, \quad \lambda^{[2r+1]} = \lambda^B$$



- Time evolution achieved by repeated local application of gates (parallel)

Time evolving block decimation

- Python + numpy provide useful tools to simply implement the algorithm as key functions are already implemented

$$\text{X}=\text{tensordot}(\text{Y},\text{Z},\text{axes}=(1,0)) \quad X_{ijk} = \sum_m Y_{im} Z_{mjk}$$

$$\text{X}=\text{reshape}(\text{X},(\text{dim1}*\text{dim2},\text{dim3})) \quad X_{ijk} \rightarrow X_{(ij)k}$$

$$\text{X}=\text{transpose}(\text{X},(0,2,1)) \quad X_{ijk} \rightarrow X_{ikj}$$

Time evolving block decimation

First define the parameters of the model / simulation

```
J=1.0; g=0.5; chi=5; d=2; delta=0.01; N=1000;
G = np.random.rand(2,d,chi,chi); l = np.random.rand(2,chi)
```

Generate the two-site time evolution operator

```
H = np.array( [[J,-g/2,-g/2,0], [-g/2,-J,0,-g/2], [-g/2,0,-J,-g/2], [0,-g/2,-g/2,J]] )
U = np.reshape(expm(-delta*H),(2,2,2,2))
```

Perform the imaginary time evolution alternating on A and B bonds

```
for step in range(0, N):
```

```
    A = np.mod(step,2); B = np.mod(step+1,2)
```

Construct theta

```
theta = np.tensordot(np.diag(l[B,:]),G[A,:,:,:],axes=(1,1))
theta = np.tensordot(theta,np.diag(l[A,:],0),axes=(2,0))
theta = np.tensordot(theta,G[B,:,:,:],axes=(2,1))
theta = np.tensordot(theta,np.diag(l[B,:],0),axes=(3,0))
```

Apply U

```
theta = np.tensordot(theta,U,axes=([1,2],[0,1]))
```

SVD

```
theta = np.reshape(np.transpose(theta,(2,0,3,1)),(d*chi,d*chi))
X, Y, Z = np.linalg.svd(theta); Z = Z.T
```

Truncate

```
l[A,0:chi]=Y[0:chi]/np.sqrt(sum(Y[0:chi]**2))
```

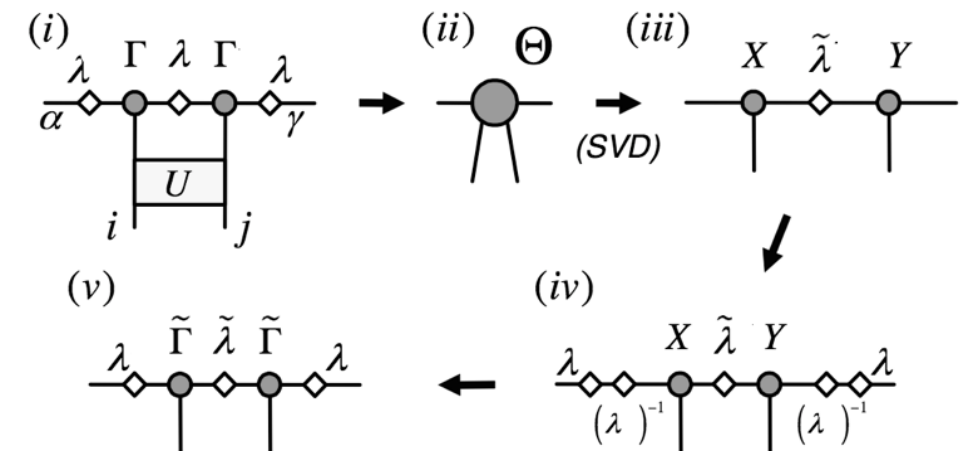
```
X=np.reshape(X[0:d*chi,0:chi],(d,chi,chi))
```

```
G[A,:,:,:]=np.transpose(np.tensordot(np.diag(l[B,:]**(-1)),X,axes=(1,1)),(1,0,2))
```

```
Z=np.transpose(np.reshape(Z[0:d*chi,0:chi],(d,chi,chi)),(0,2,1))
```

```
G[B,:,:,:]=np.tensordot(Z,np.diag(l[B,:]**(-1)),axes=(2,0))
```

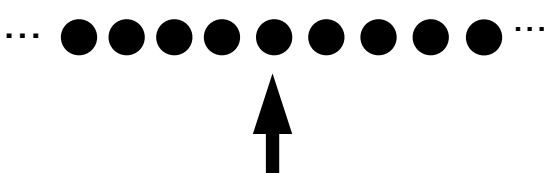
```
print "E_iTEBD =", -np.log(np.sum(theta**2))/delta/2
```

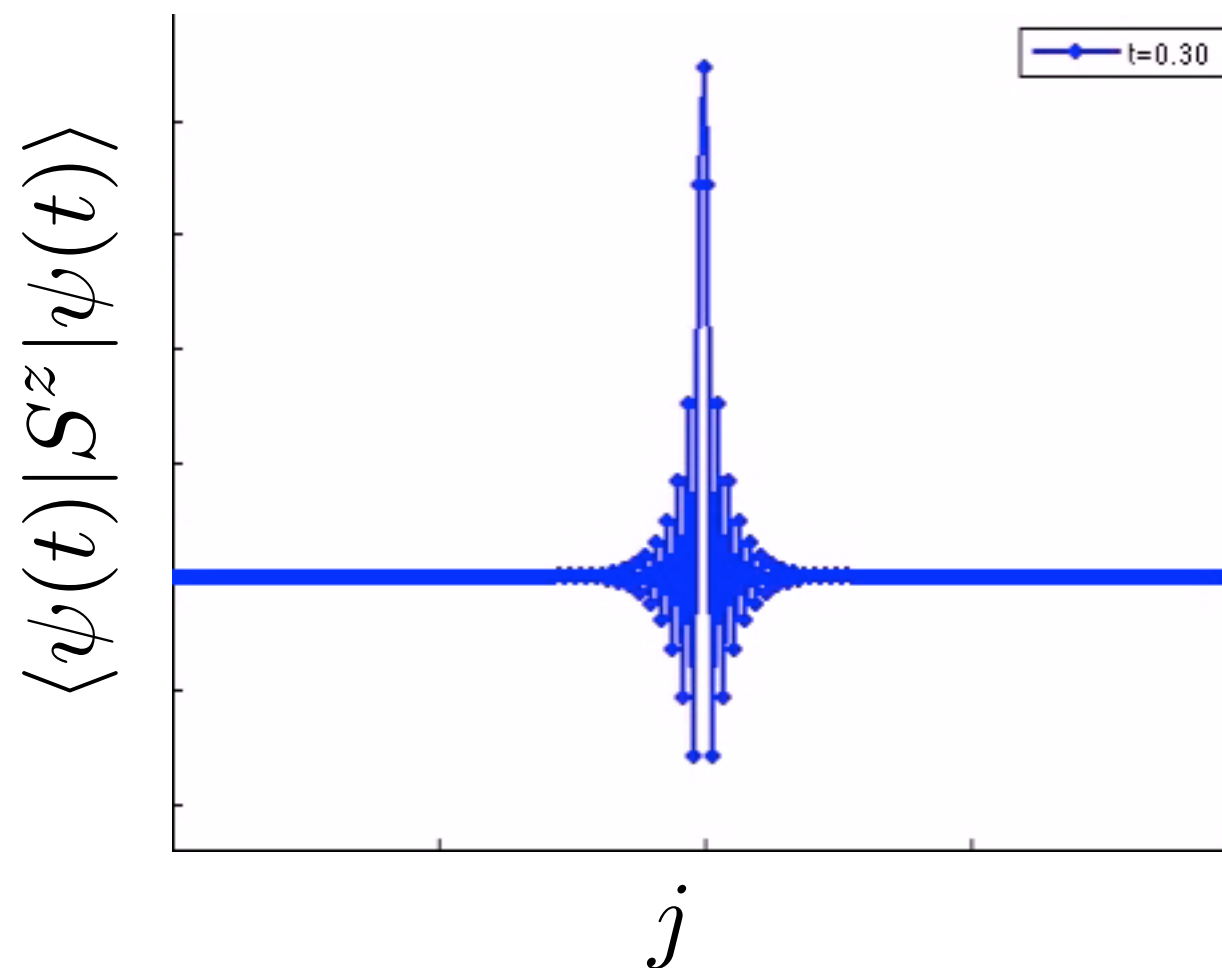


Quench dynamics and entanglement growth

Dynamical Response

- Spin-1 Heisenberg model: $H = \sum_j \vec{S}_j \cdot \vec{S}_{j+1}$

- Time evolution of $S_{j_0}^+ |\psi_0\rangle$ $\cdots \bullet \bullet \bullet \bullet \bullet \bullet \bullet \bullet \cdots$


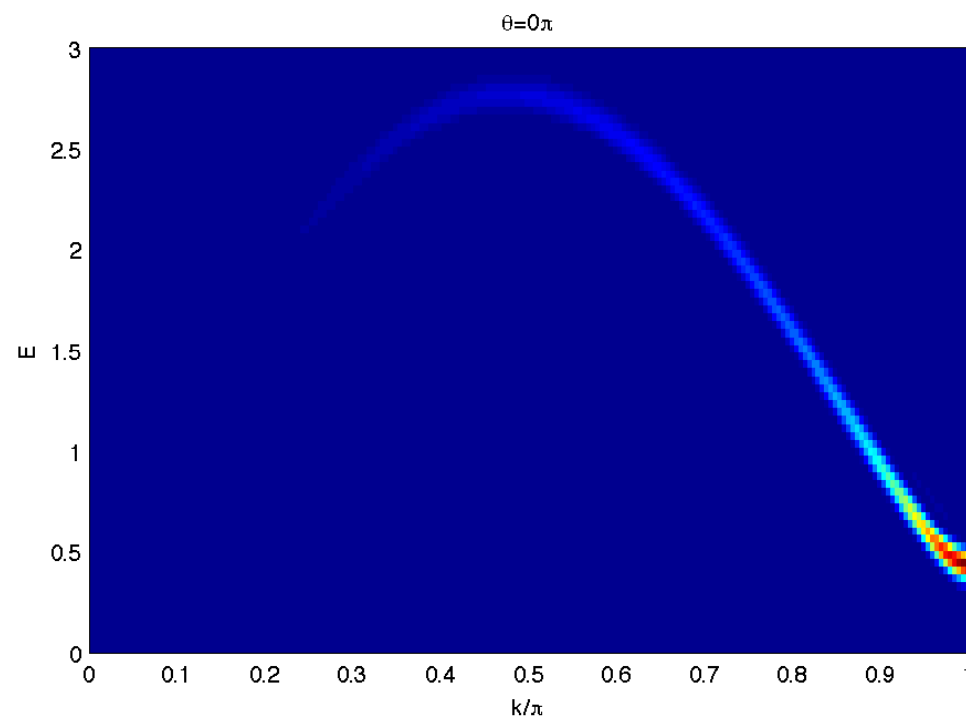
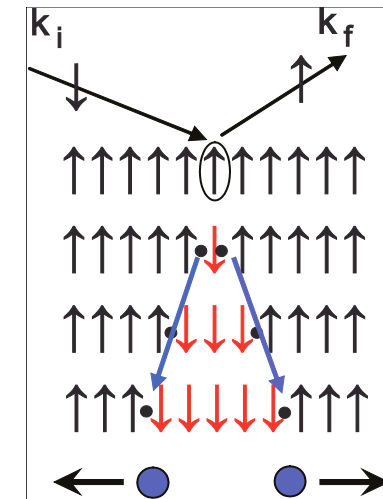


Dynamical Response

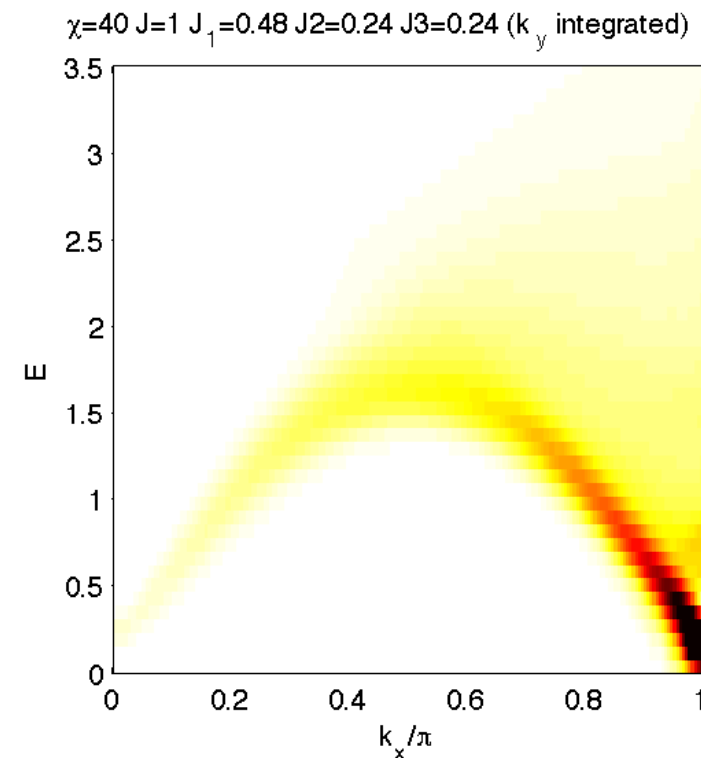
- Dynamical structure factor $S(k, \omega)$

$$C(x, t) = \langle \psi_0 | S_x^-(t) S_0^+(0) | \psi_0 \rangle$$

$$S(k, \omega) = \sum_x \int_{-\infty}^{\infty} dt e^{-i(kx + \omega t)} C(x, t)$$



Spin-1 Heisenberg



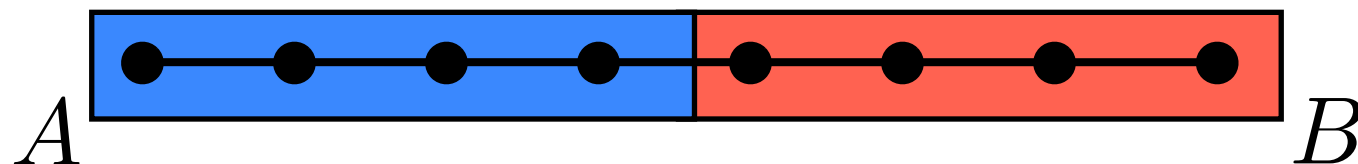
Spin-1/2 Ladder

Global Quenches

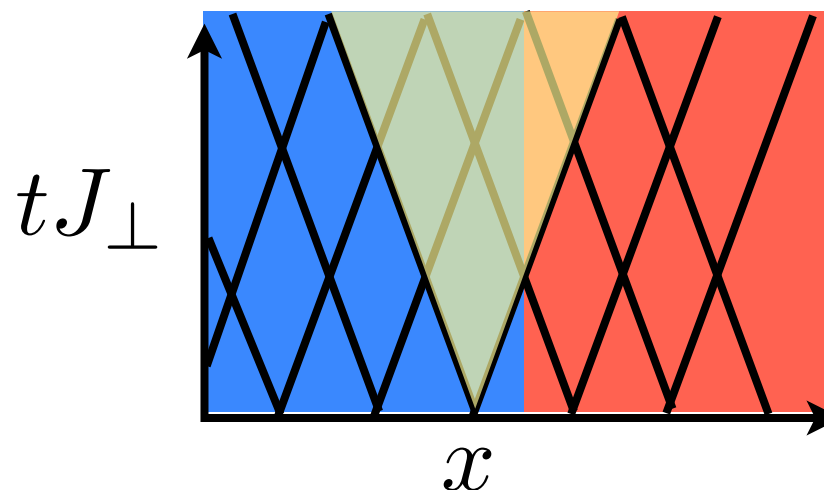
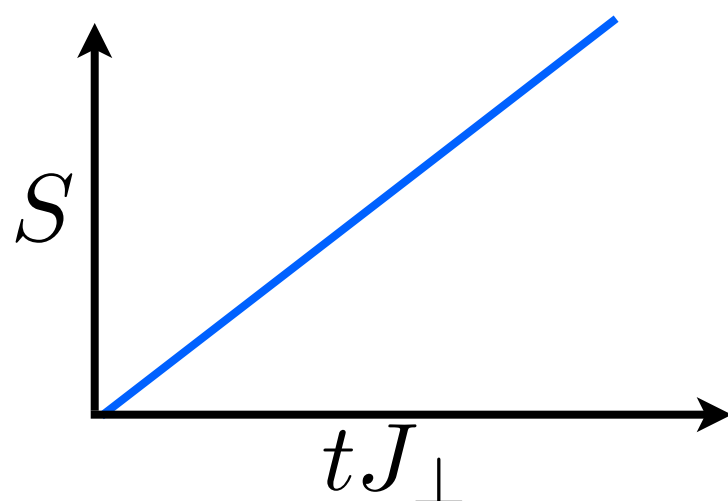
- Start from an unentangled product state ($S = 0$)

$$|\psi_0\rangle = |\uparrow\downarrow\uparrow\downarrow\uparrow\downarrow\uparrow\downarrow\uparrow\downarrow\uparrow\downarrow\uparrow\downarrow\uparrow\downarrow\uparrow\downarrow\rangle$$

- Measure the entanglement after quench and the time evolution with $U(t) = e^{-itH}$

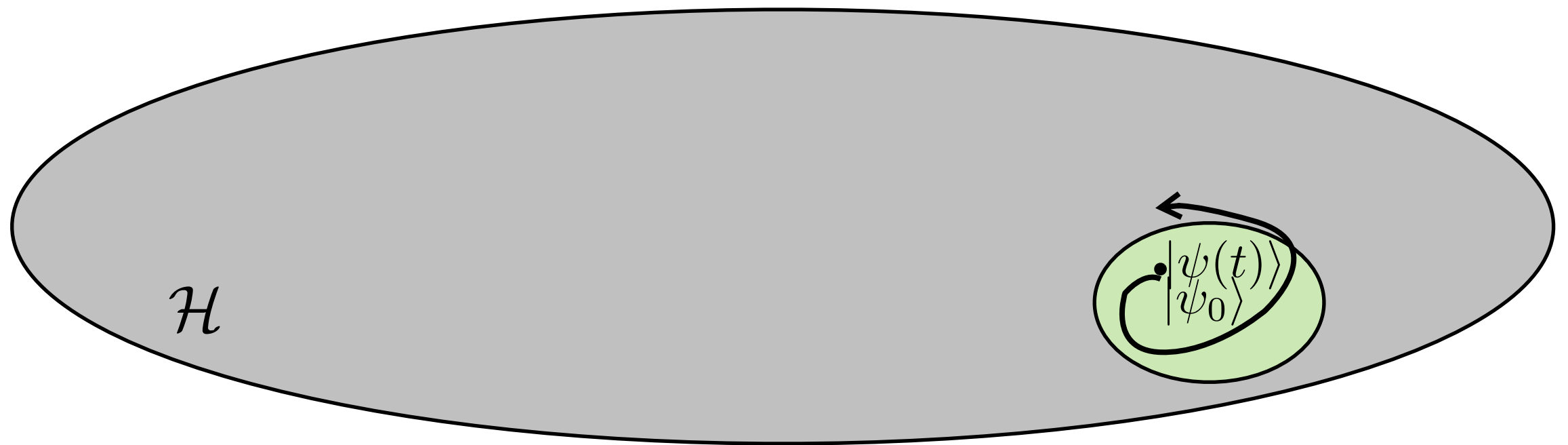


- Time evolution with a Heisenberg Hamiltonian:



Global Quenches

- Quickly leaving the comfort zone:
Exponential growth of the bond dimension!



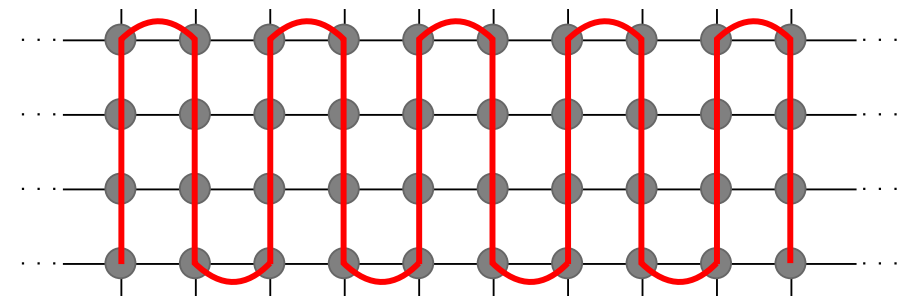
- Only short times can be simulated!

Hands on session!

MPO based time evolution

MPO based time evolution

- Desirable to have a method that can be...
 - (i) ... applied to any long-ranged Hamiltonian
 - (ii) ... applied to an infinitely long system
 - (iii) ... easily implemented



MPO based time evolution

- Hamiltonian expressed as a sum of terms $H = \sum_x H_x$
Expand $U = \exp(-itH)$ for $t \ll 1$:

$$\underbrace{1 + t \sum_x H_x}_{\epsilon \sim \underline{L^2} t^2} \rightarrow \underbrace{\prod_x (1 + t H_x)}_{\epsilon \sim \underline{L} t^2}$$

Neglect overlapping terms in expansion

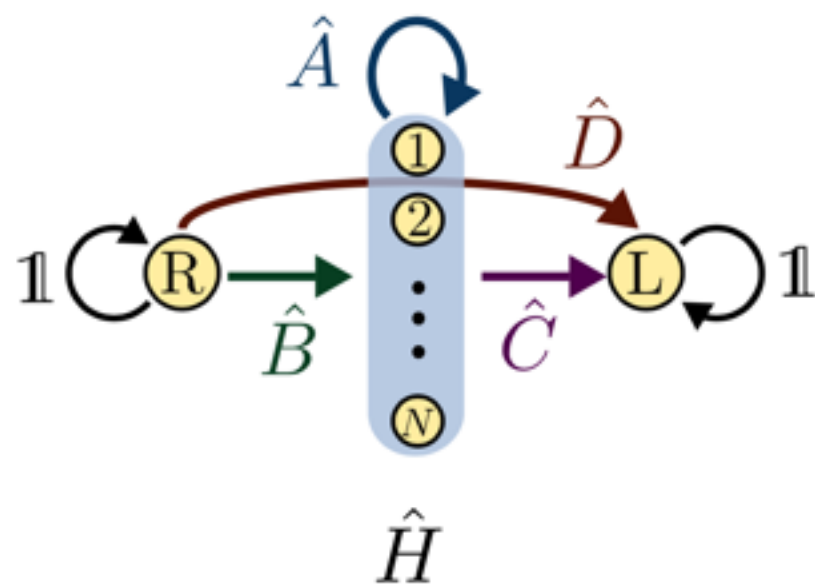
$$\begin{aligned} &\approx 1 + t \sum_x H_x + t^2 \sum_{x < y} H_x H_y \\ &\quad + t^3 \sum_{x < y < z} H_x H_y H_z + \dots \end{aligned}$$

Compact matrix product operator representation

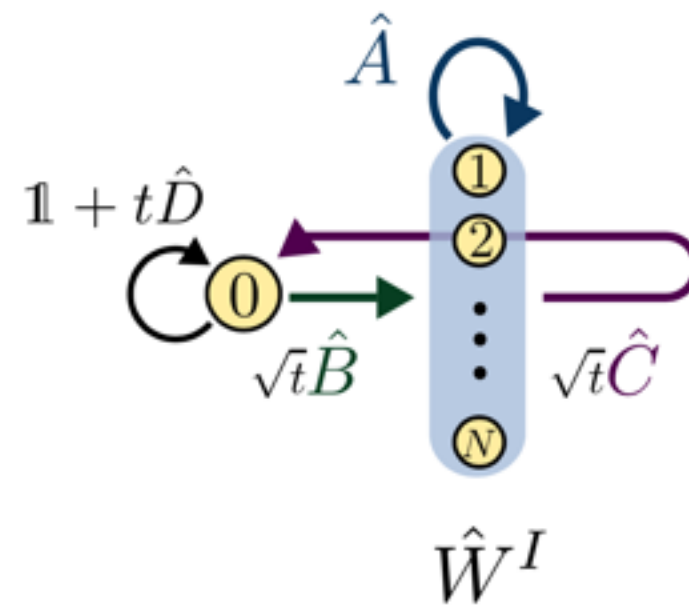
$$W_{\alpha\beta}^{[n]j_n j'_n} = \alpha \text{---} \begin{array}{c} j'_n \\ | \\ \text{---} \text{◇} \text{---} \\ | \\ j_n \end{array} \text{---} \beta$$

MPO based time evolution

- For experts on matrix product operators....



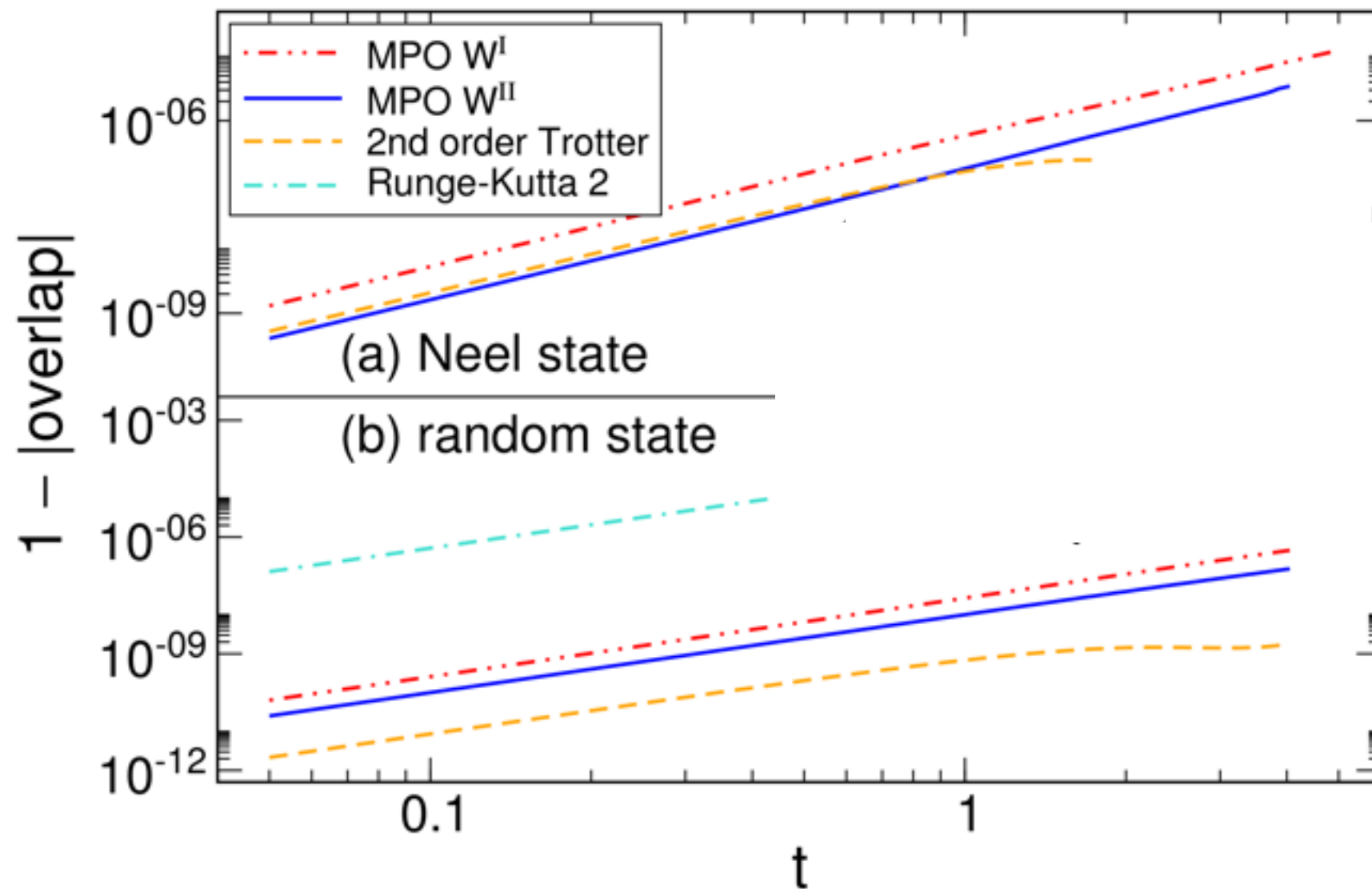
D dimensional
Hamiltonian MPO



$D - 1$ dimensional
time evolution MPO

MPO based time evolution

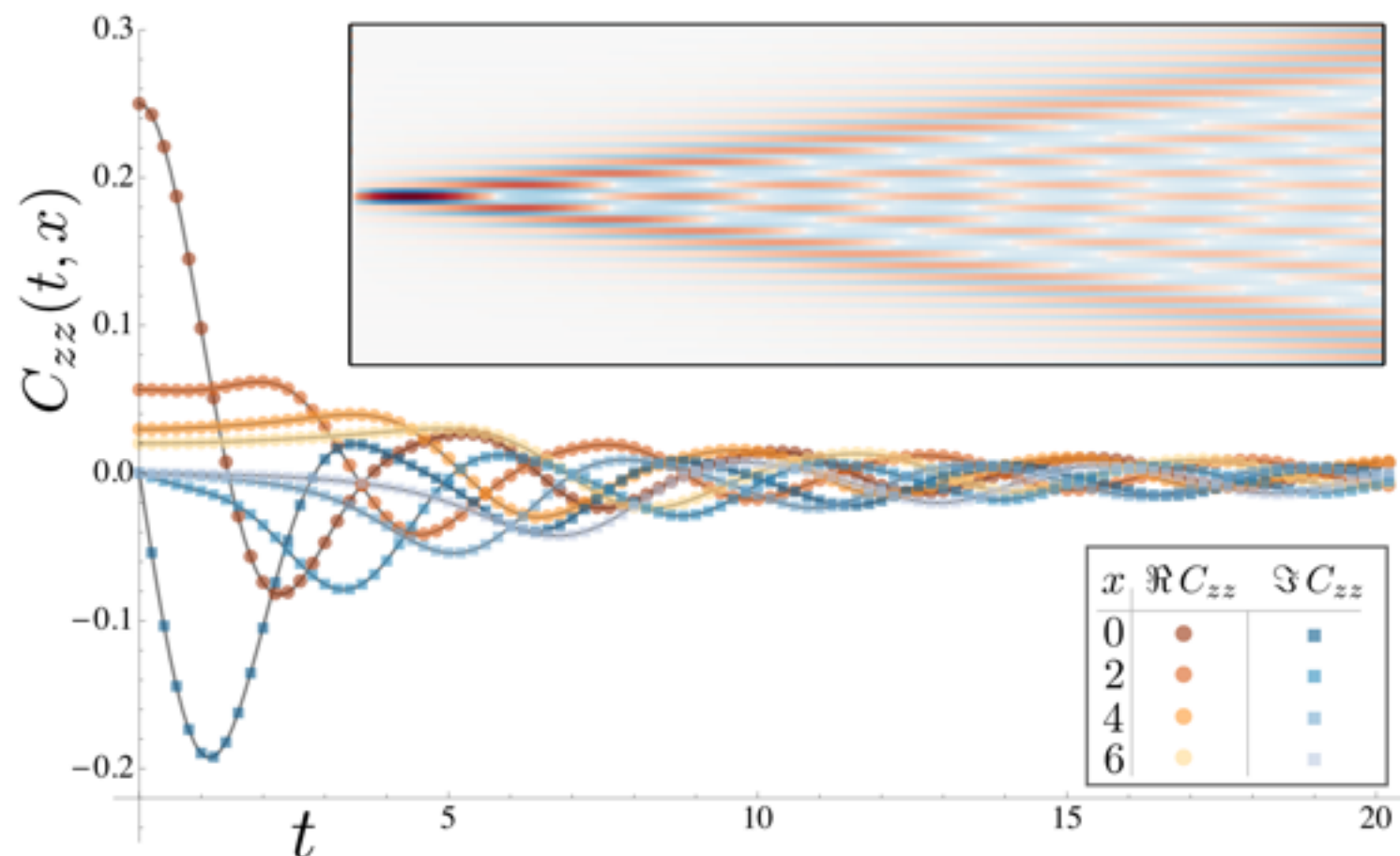
- Quench in the **spin-1/2 Heisenberg chain**



MPO based time evolution

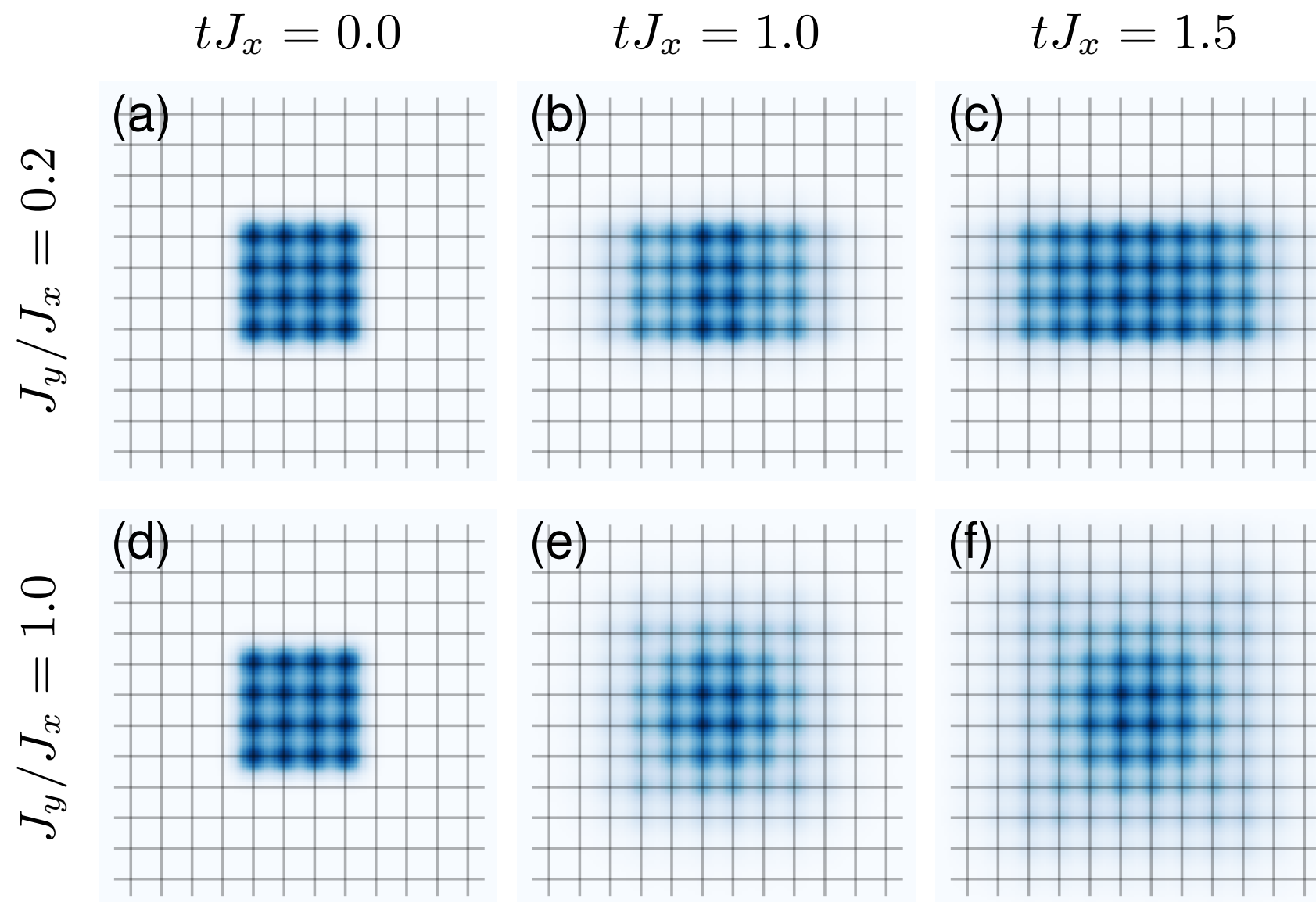
- Dynamical correlation functions in the **Haldane Shastry** model [Haldane & Zirnbauer '93]

$$H_{\text{HS}} = \sum_{x,r>0} \frac{\mathbf{S}_x \cdot \mathbf{S}_{x+r}}{r^2}.$$



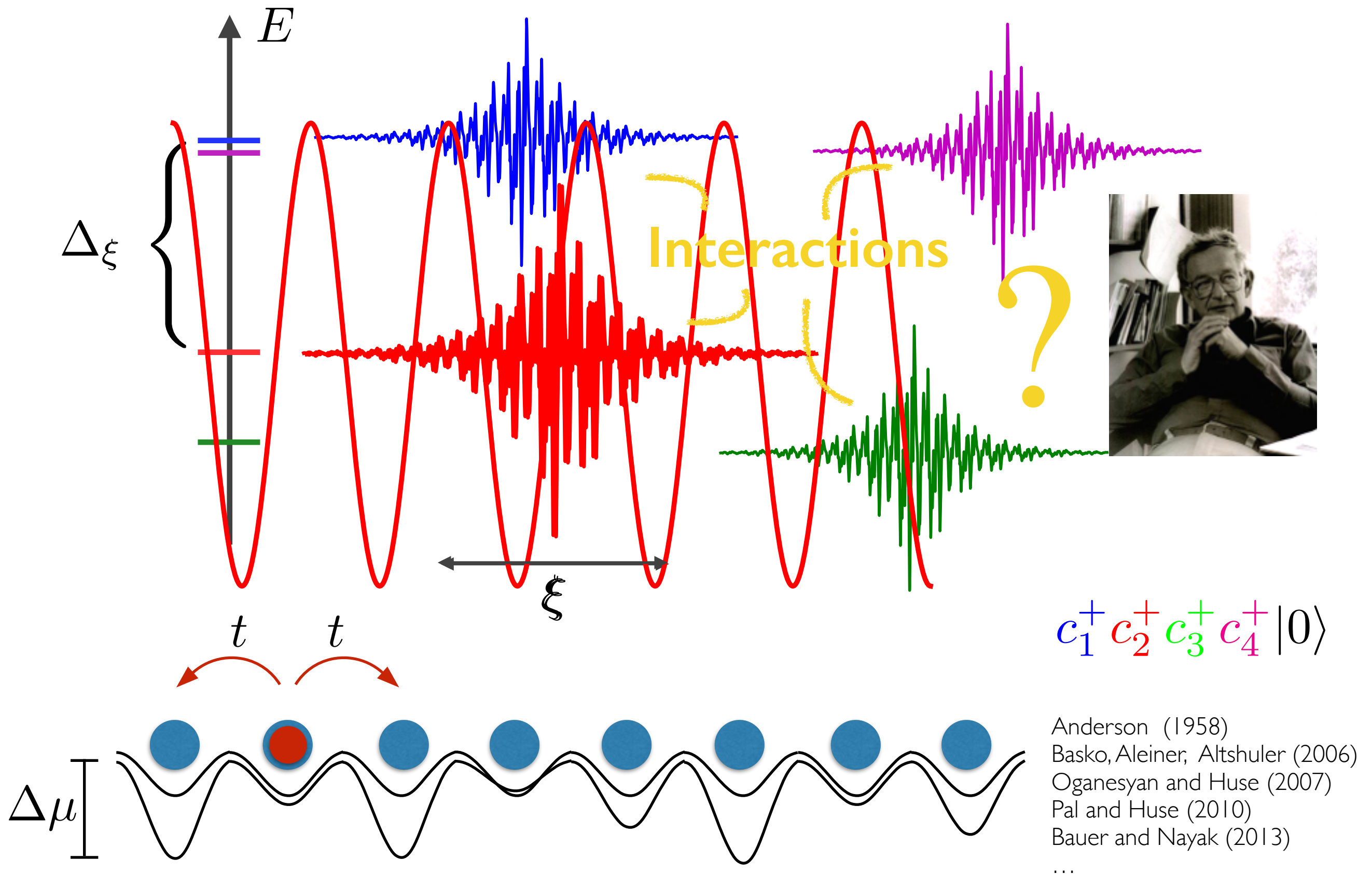
MPO based time evolution

- Expansion of bosonic clouds in 2D [Hauschild et al. '15]

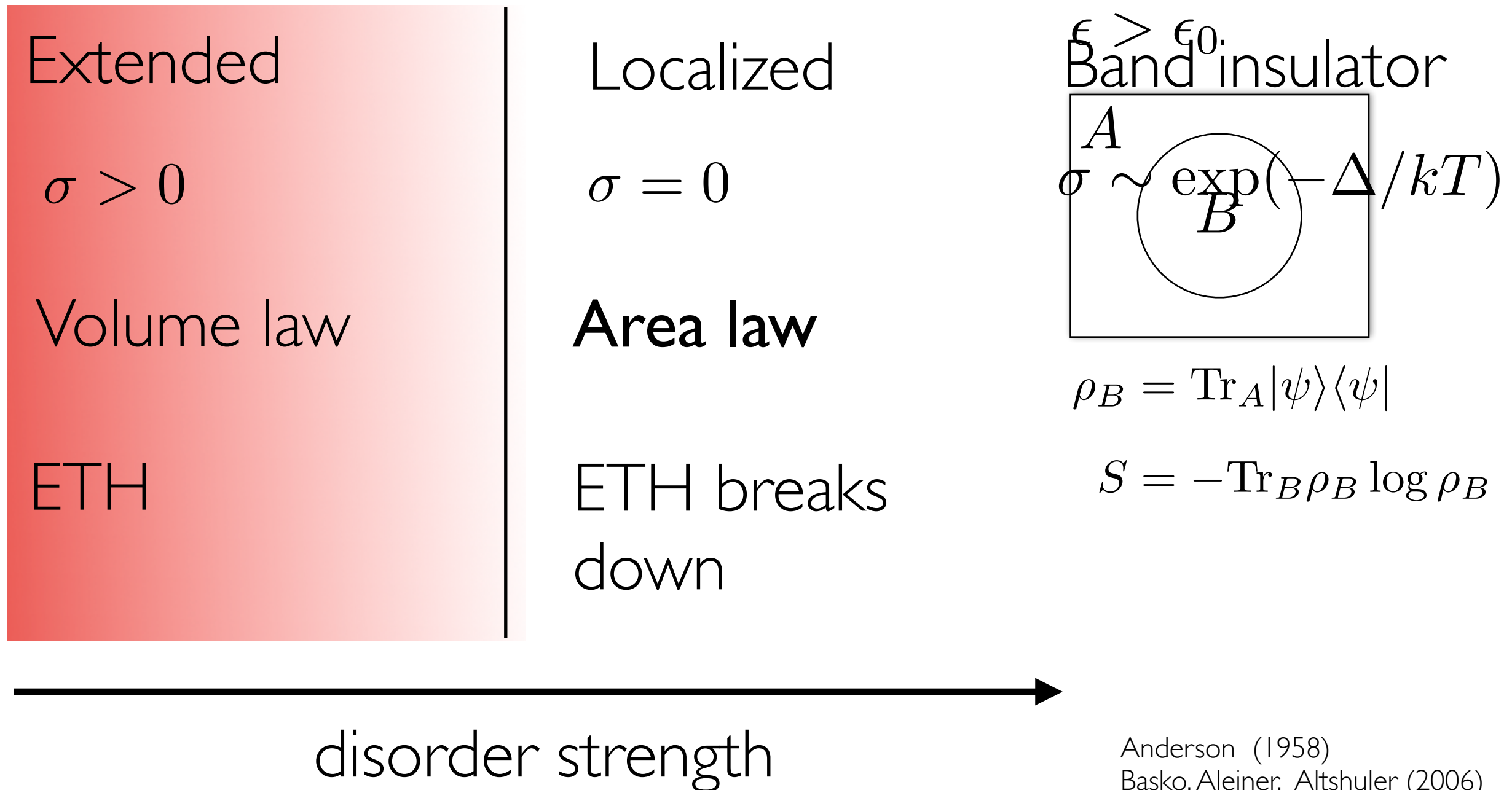


Many-body localization

Many-body localization



Many-body localization

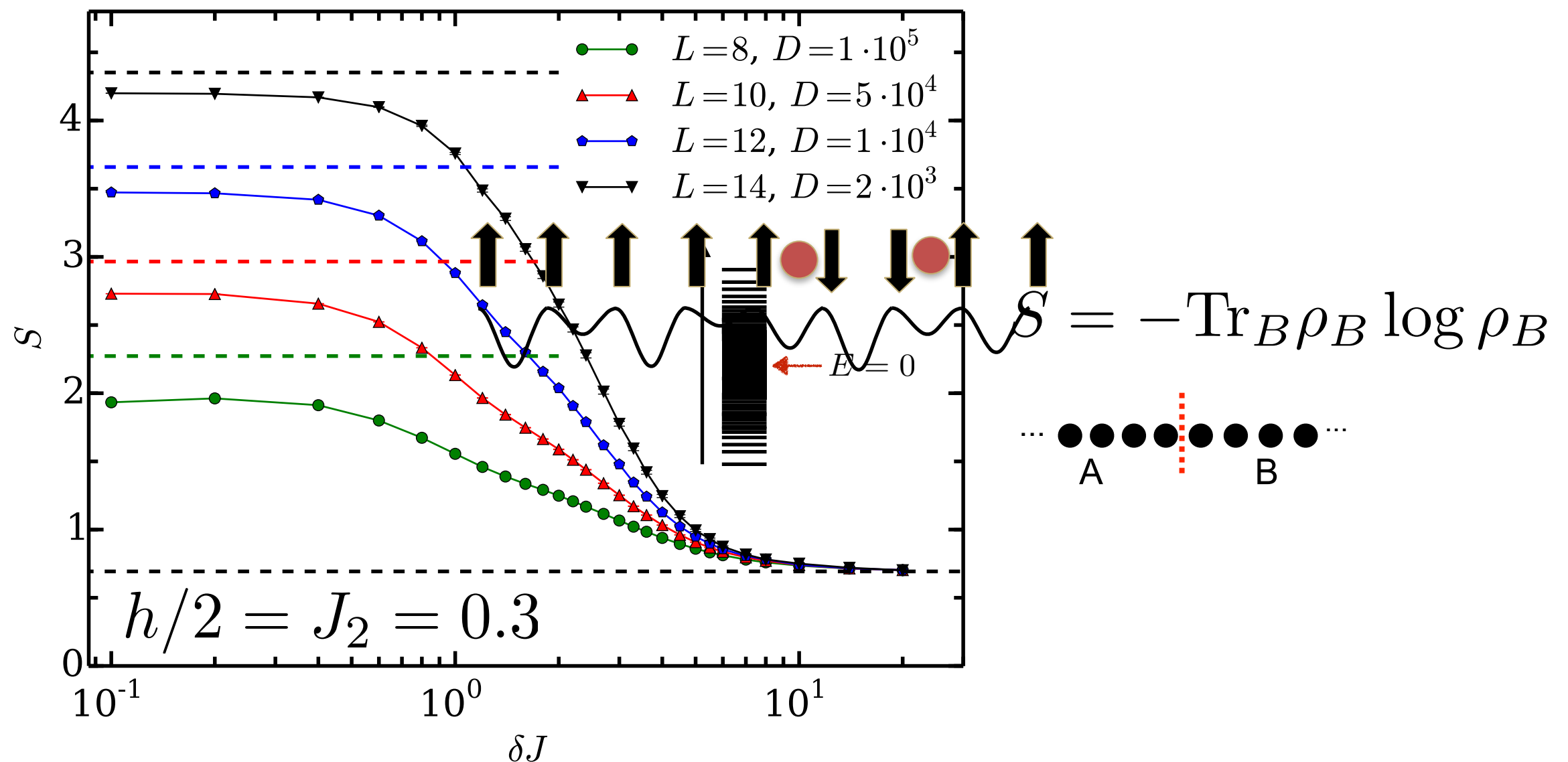


Anderson (1958)
 Basko, Aleiner, Altshuler (2006)
 Oganesyan and Huse (2007)
 Pal and Huse (2010)
 Bauer and Nayak (2013)
 ...

Many-body localization transition

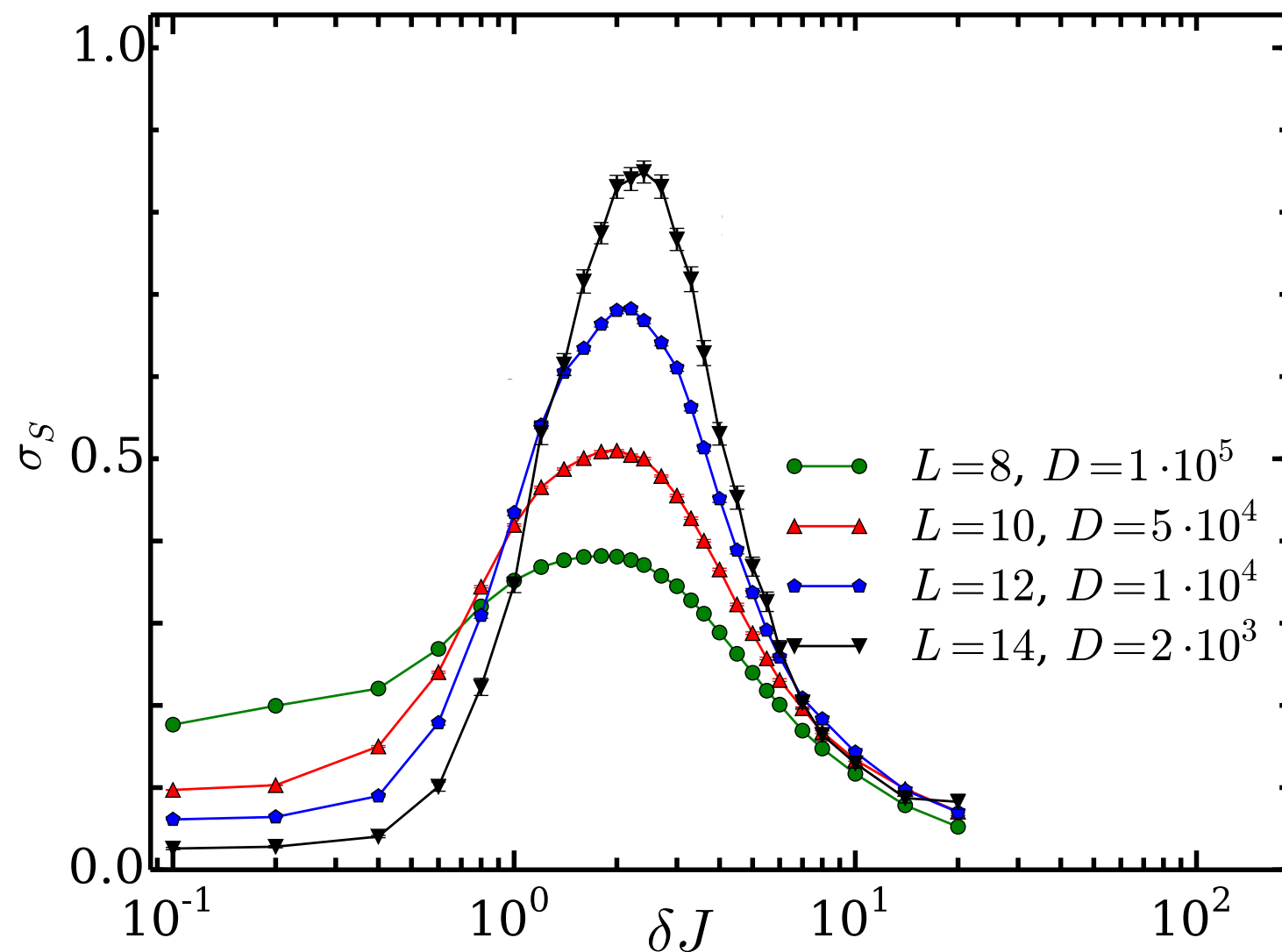
- Localized and extended phase: **AREA vs. VOLUME** law

$$H = - \sum_i (1 + \delta J_i) \sigma_i^z \sigma_{i+1}^z + h \sum_i \sigma_i^x + J_2 \sum_i \sigma_i^z \sigma_{i+2}^z$$



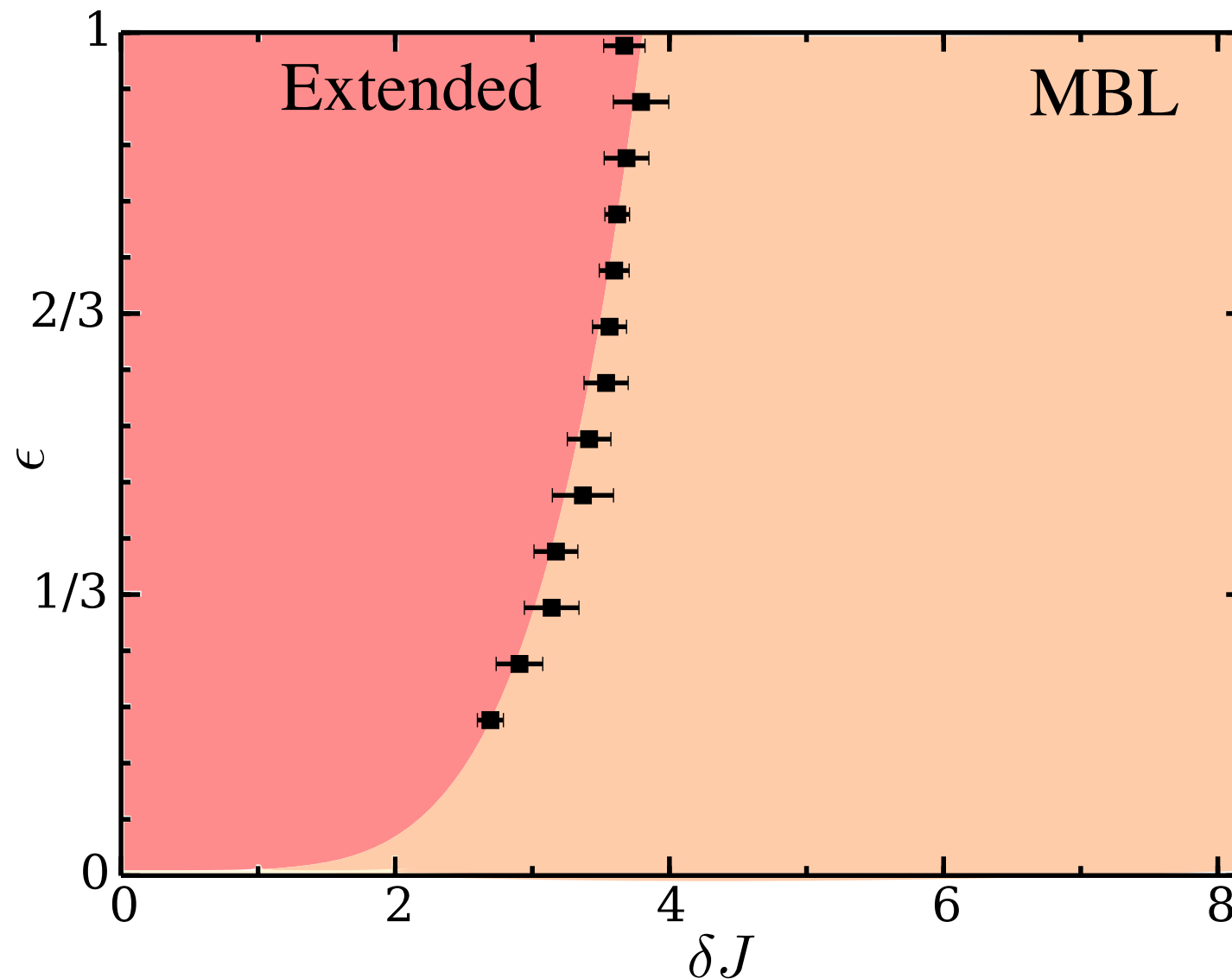
Many-body localization transition

- Localized and extended phase: **AREA vs. VOLUME** law
➡ Variance of S diverges at the transition point



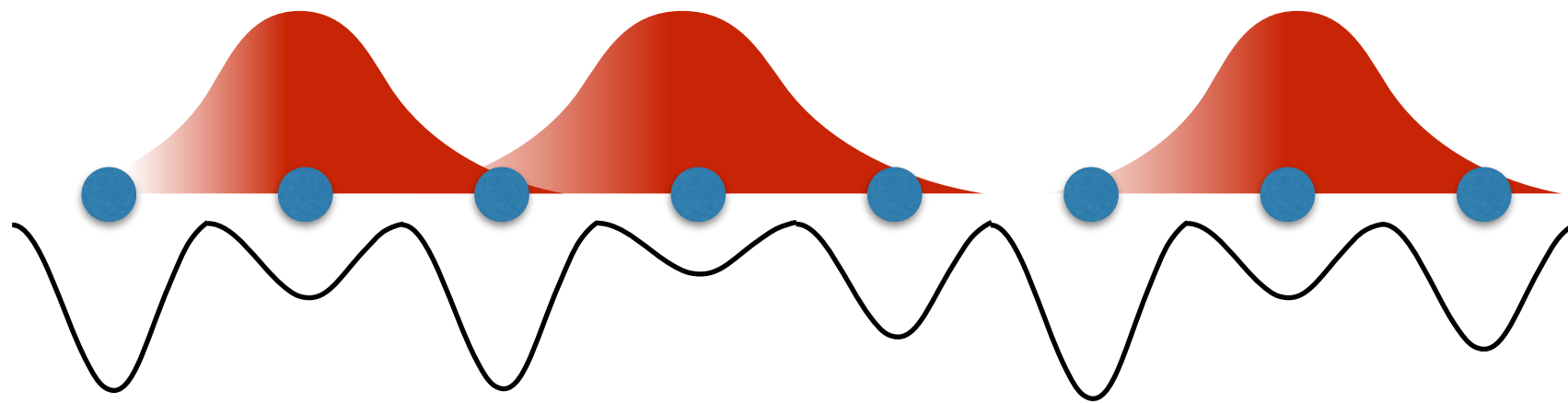
Many-body localization transition

- Repeating the scaling for various energy densities yields the phase diagram



Quasi local integrals of motion

- Many-body eigenstates of Anderson insulator



- “Quasi local” product state representation of 2^L states

$$|\psi_{n_1, n_2, \dots, n_L}\rangle = (c_1^\dagger)^{n_1} (c_2^\dagger)^{n_2} \dots (c_L^\dagger)^{n_L} |0\rangle$$

Quasi local integrals of motion

- Many-body localization: “p-bits” (σ) and “l-bits” (τ):

[Huse & Oganesyan '13, Serbyn, Papic, Abanin '13]

$$\begin{aligned} |\psi_{\tau_1, \tau_2, \dots, \tau_L}\rangle &= \\ |\tau_1, \tau_2, \dots, \tau_L\rangle &= \end{aligned} \begin{array}{ccccccc} \sigma_1 & \sigma_2 & \sigma_3 & & \dots & & \sigma_{L-1} & \sigma_L \\ | & | & | & | & | & | & | & | \\ \hline & U^{\sigma_1, \dots, \sigma_L}_{\tau_1, \dots, \tau_L} & & & & & & \\ \hline | & | & | & | & | & | & | & | \\ \uparrow & \uparrow & \downarrow & \uparrow & \uparrow & \uparrow & \downarrow & \uparrow \end{array}$$

- All 2^L many-body eigenstates given by a “quasi local” unitary
- Efficient representation as **Matrix-Product Operator** ???

Disordered Anisotropic Heisenberg Chain

- Toy model to study the MBL phases [Anderson '58]



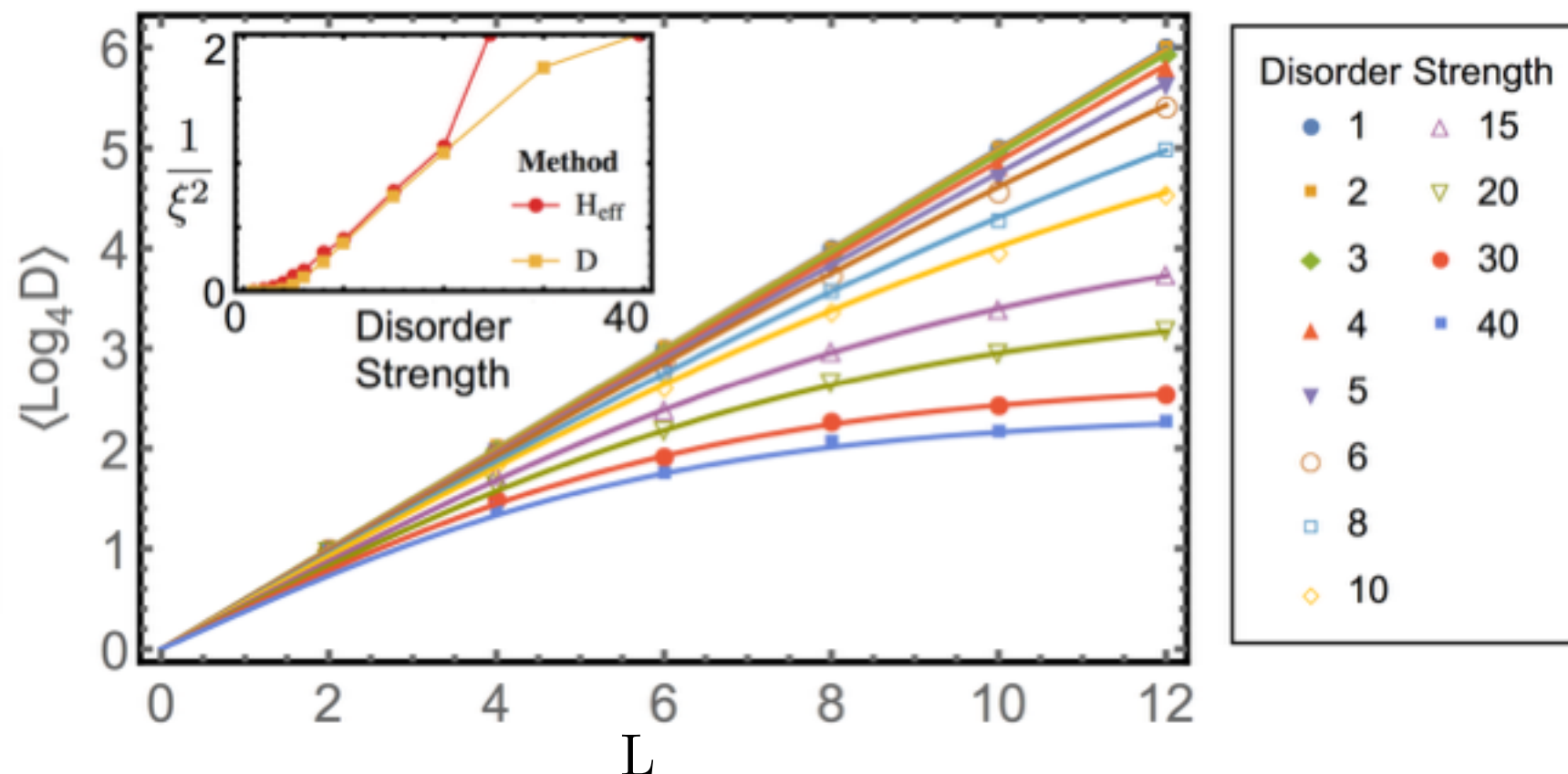
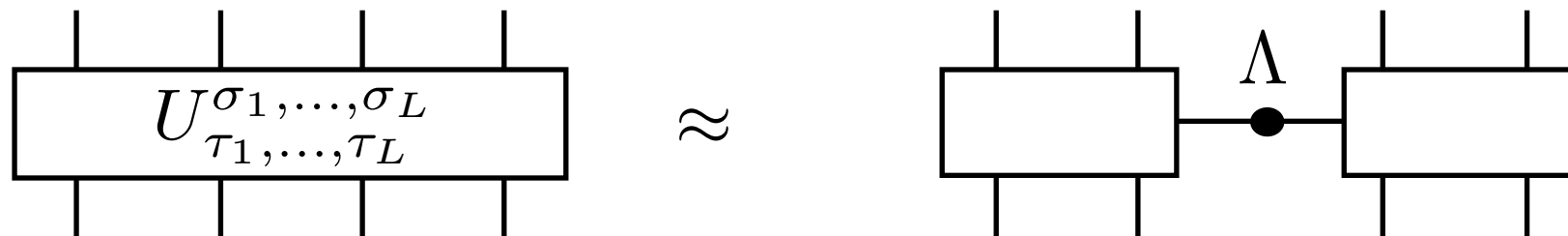
$$H = J_{\perp} \sum_i \underbrace{(S_i^x S_{i+1}^x + S_i^y S_{i+1}^y)}_{\text{hopping}} + \underbrace{\sum_i h_i S_i^z}_{\text{random potential}} + J_z \underbrace{\sum_i S_i^z S_{i+1}^z}_{\text{interaction}}$$

with $h_i \in [-W, W]$

- All single particle states localized for $W \neq 0$
- $J_{\perp} = J_z = 1$: fully MBL for $W \gtrsim 3.5$ [Pal & Huse '10]

Quasi local integrals of motion

- Compression using exact diagonalization (ED) [Pekker & Clark '14]

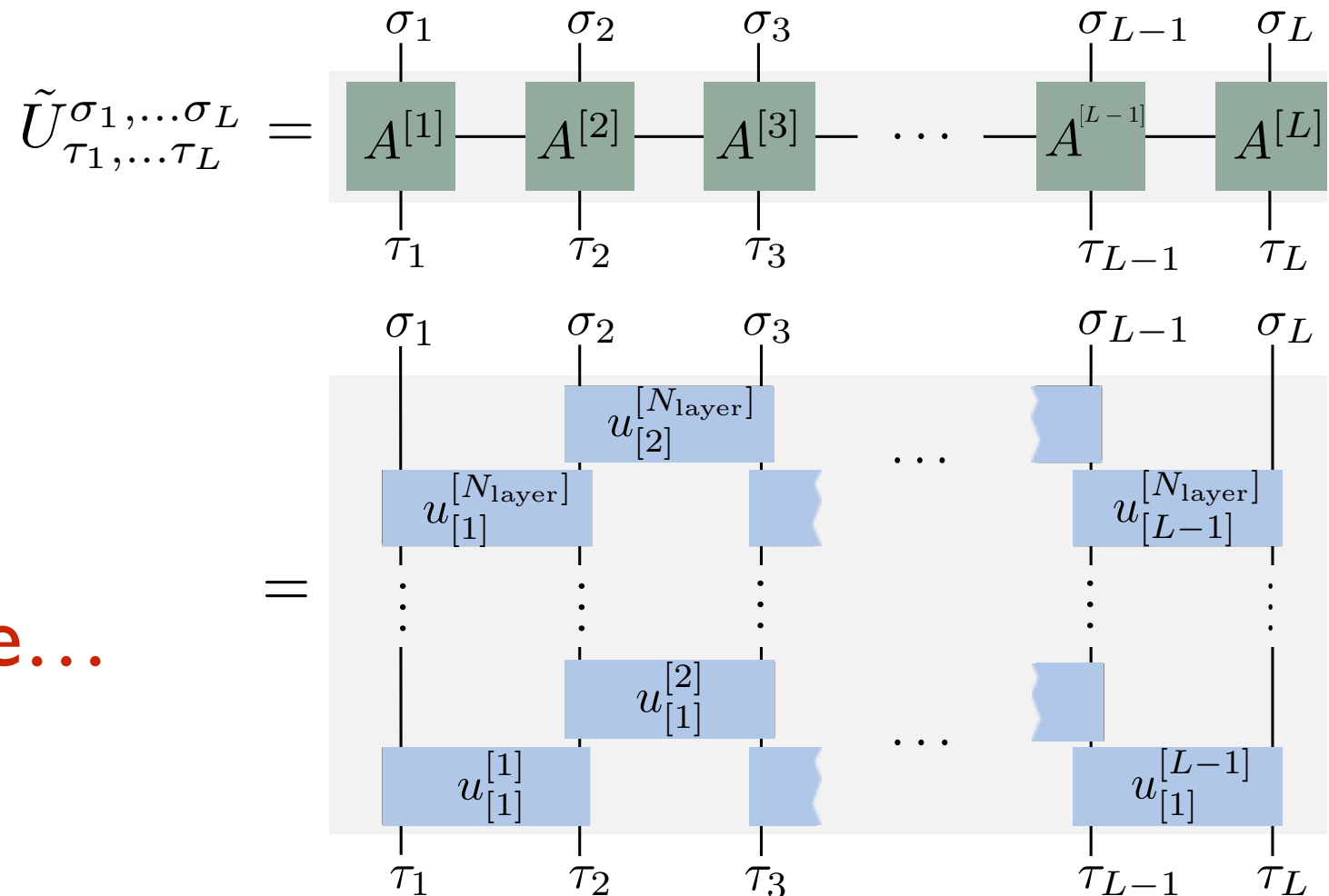


- ED exponential in size! Gauge of $U^{\sigma_1, \dots, \sigma_L}_{\tau_1, \dots, \tau_L}$? Unitarity?

Variational Ansatz:

- Finite depth local unitary network

Different unitary networks possible...



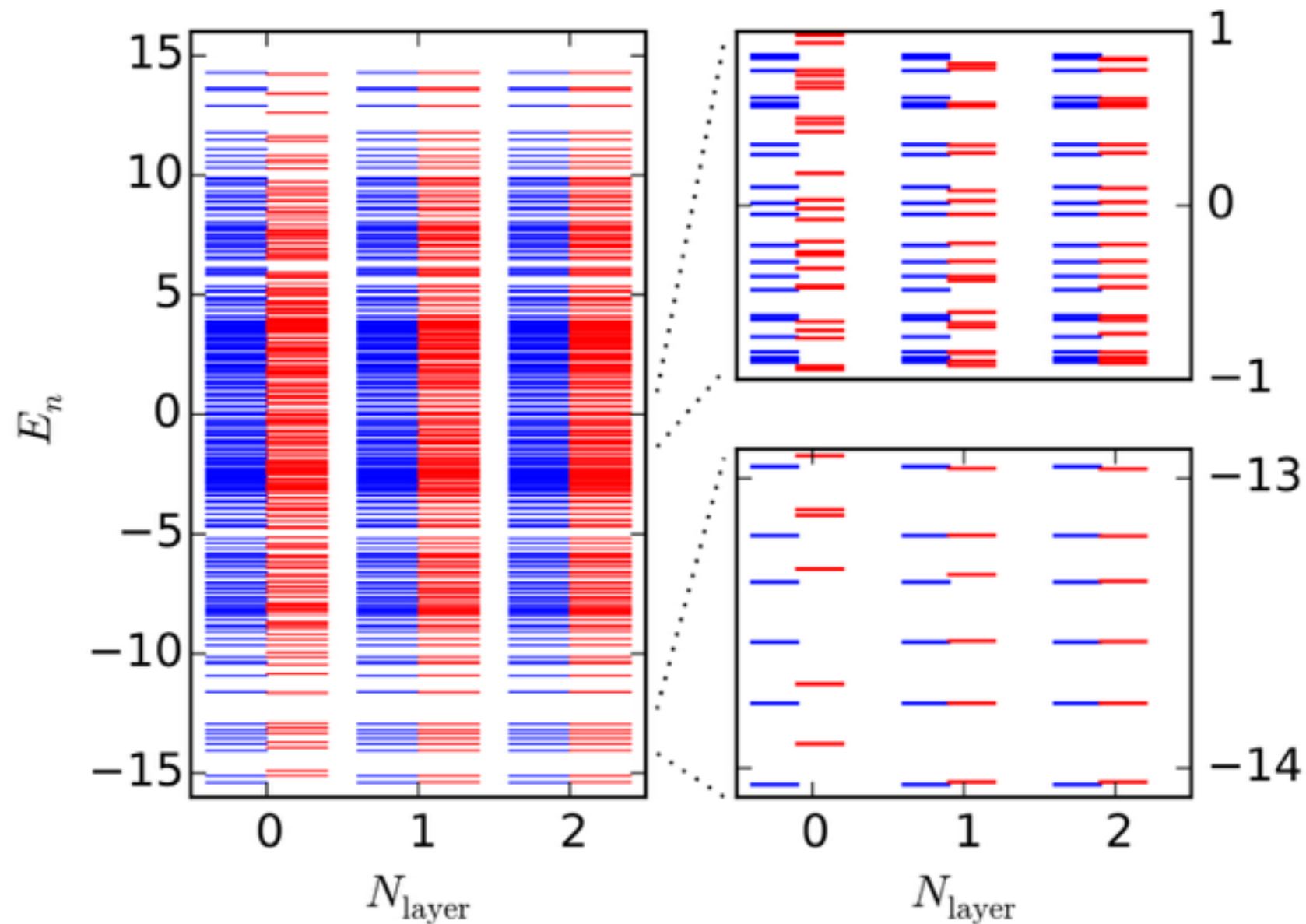
- Locally minimize the cost function using CG

$$f(\{A^{[n]}\}) = \sum_{\{\tau\}} \langle \psi_{\tau} | H^2 | \psi_{\tau} \rangle - \langle \psi_{\tau} | H | \psi_{\tau} \rangle^2 \geq 0$$

Scaling: **Linear in L and exponential in N_{Layer}**

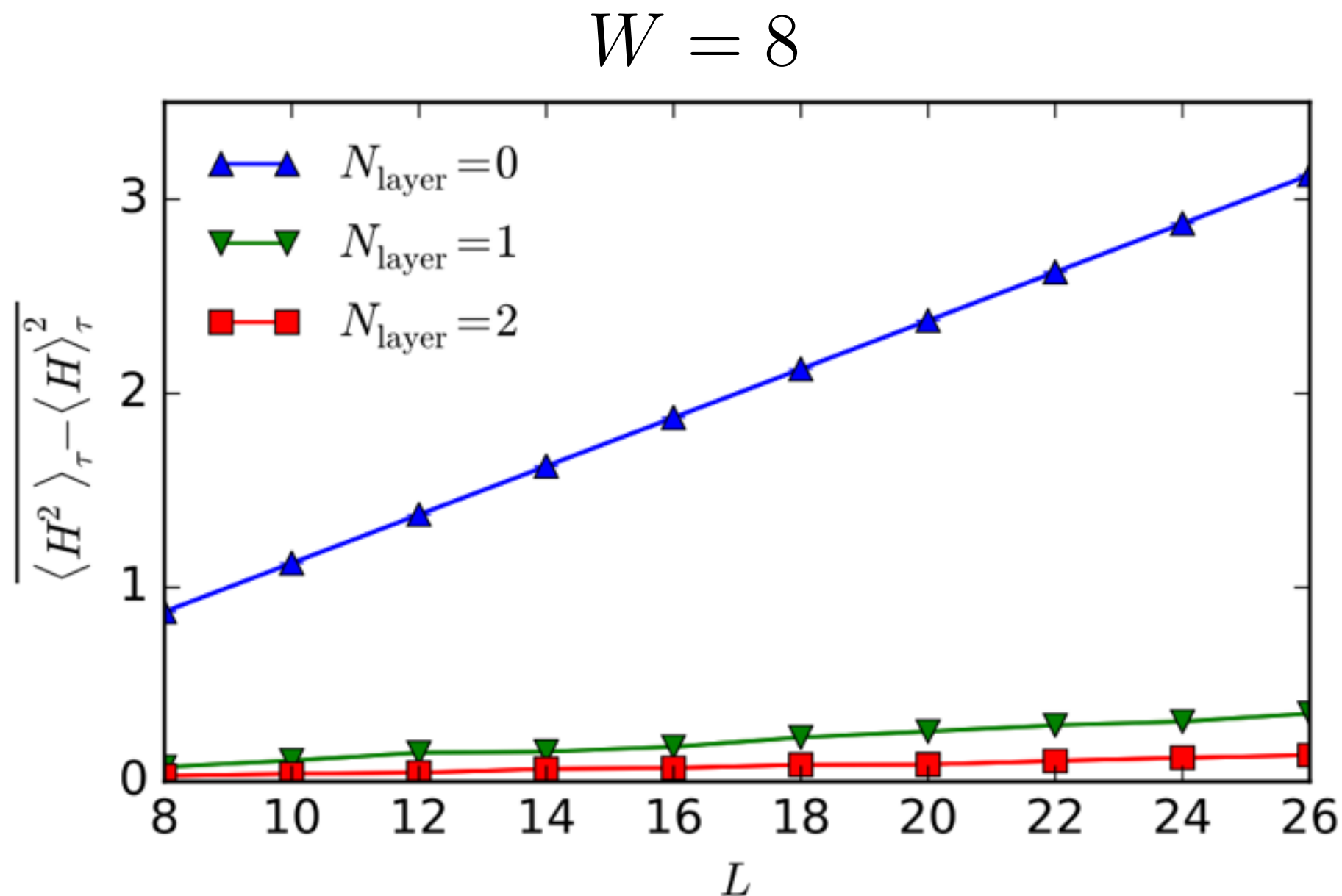
Comparison with exact results

- Deep in localized phase with $W = 8$ and $L = 8$:



Comparison with exact results

- Linear scaling of the mean variance: **Constant error density**



Comparison with exact results

- Spectral function: $A(\omega) = \frac{1}{2^L} \sum_{\{\tau_1\}, \{\tau_2\}} |\langle \tau_1 | S_{L/2}^z | \tau_2 \rangle|^2 \delta(\omega - E_{\tau_1} + E_{\tau_2})$

- • ED full — ED MPO — $N_{\text{layer}}=0$ — $N_{\text{layer}}=1$ — $N_{\text{layer}}=2$

